CSE 40537/60537 Biometrics

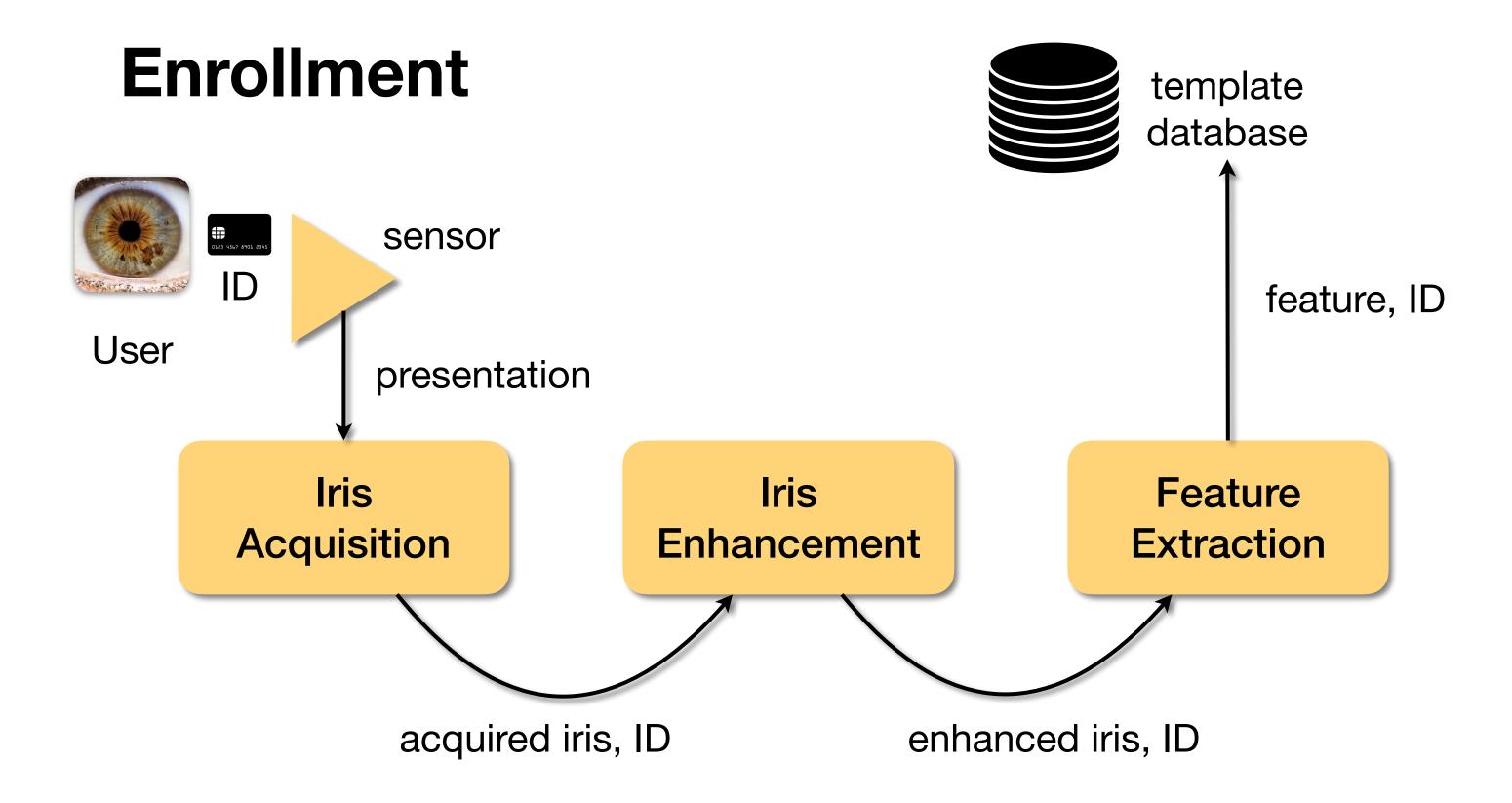
Daniel Moreira
Spring 2022



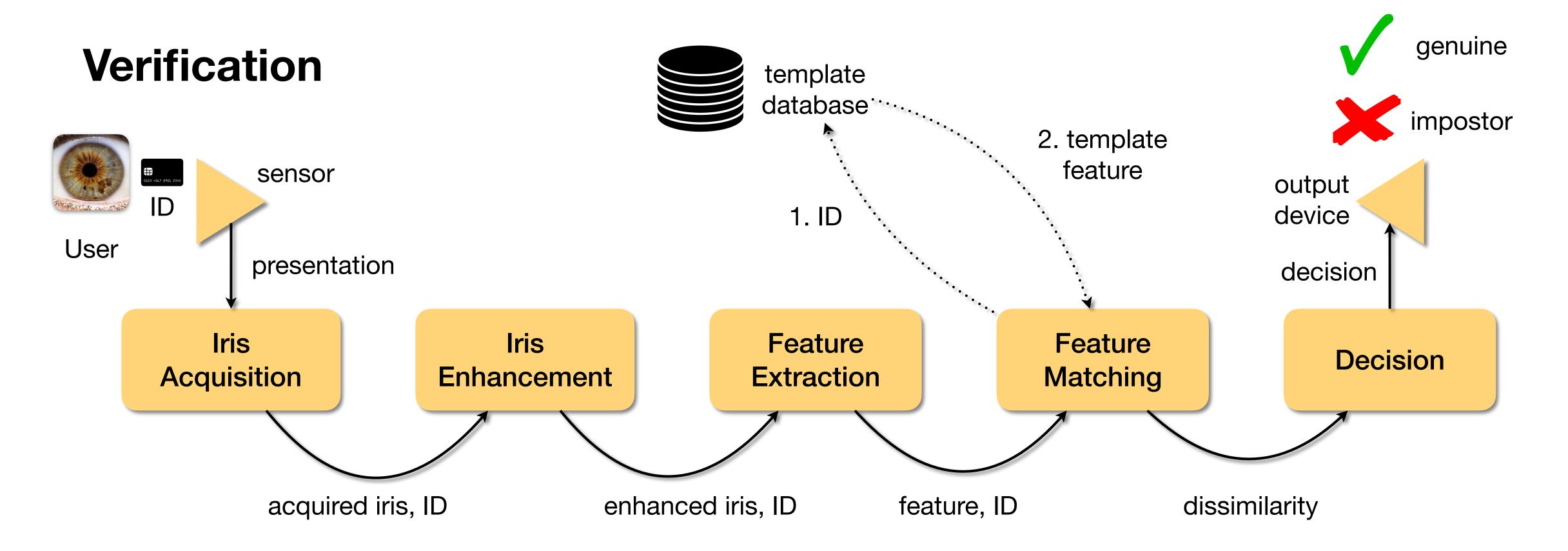
### Today you will...

Get to know Iris acquisition and enhancement.

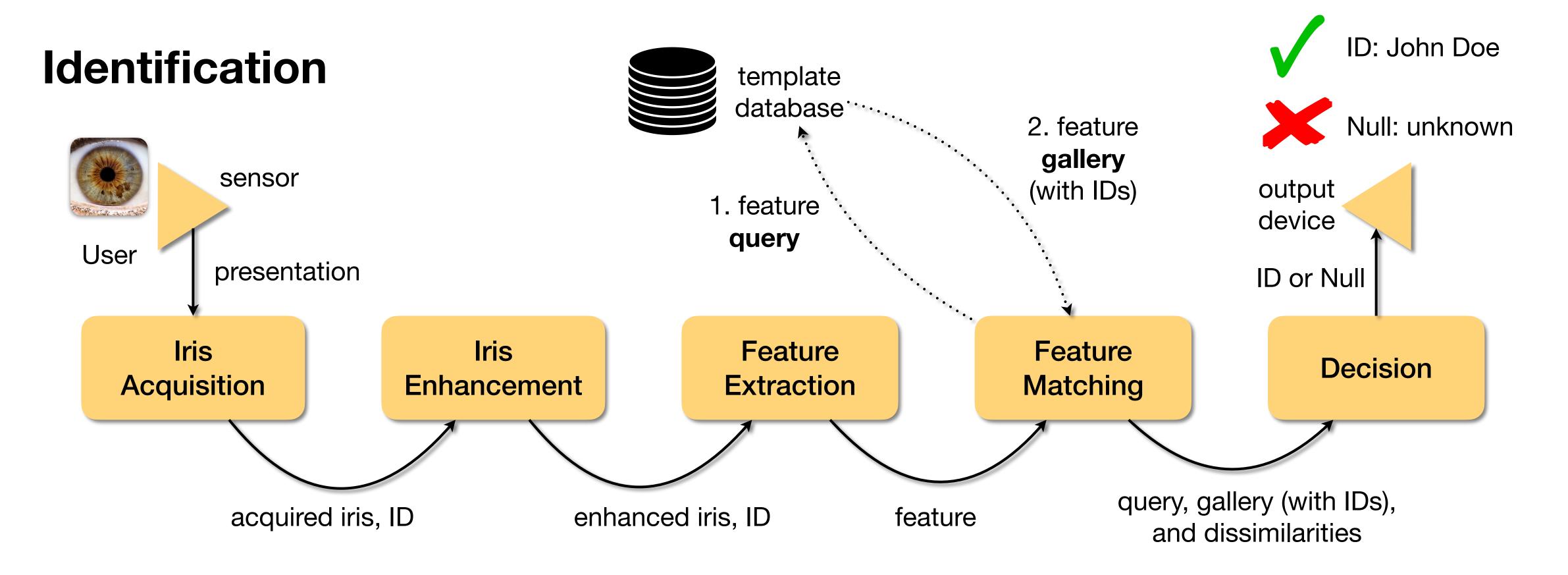




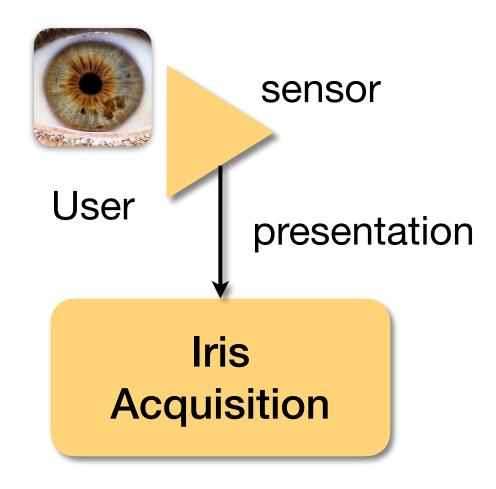




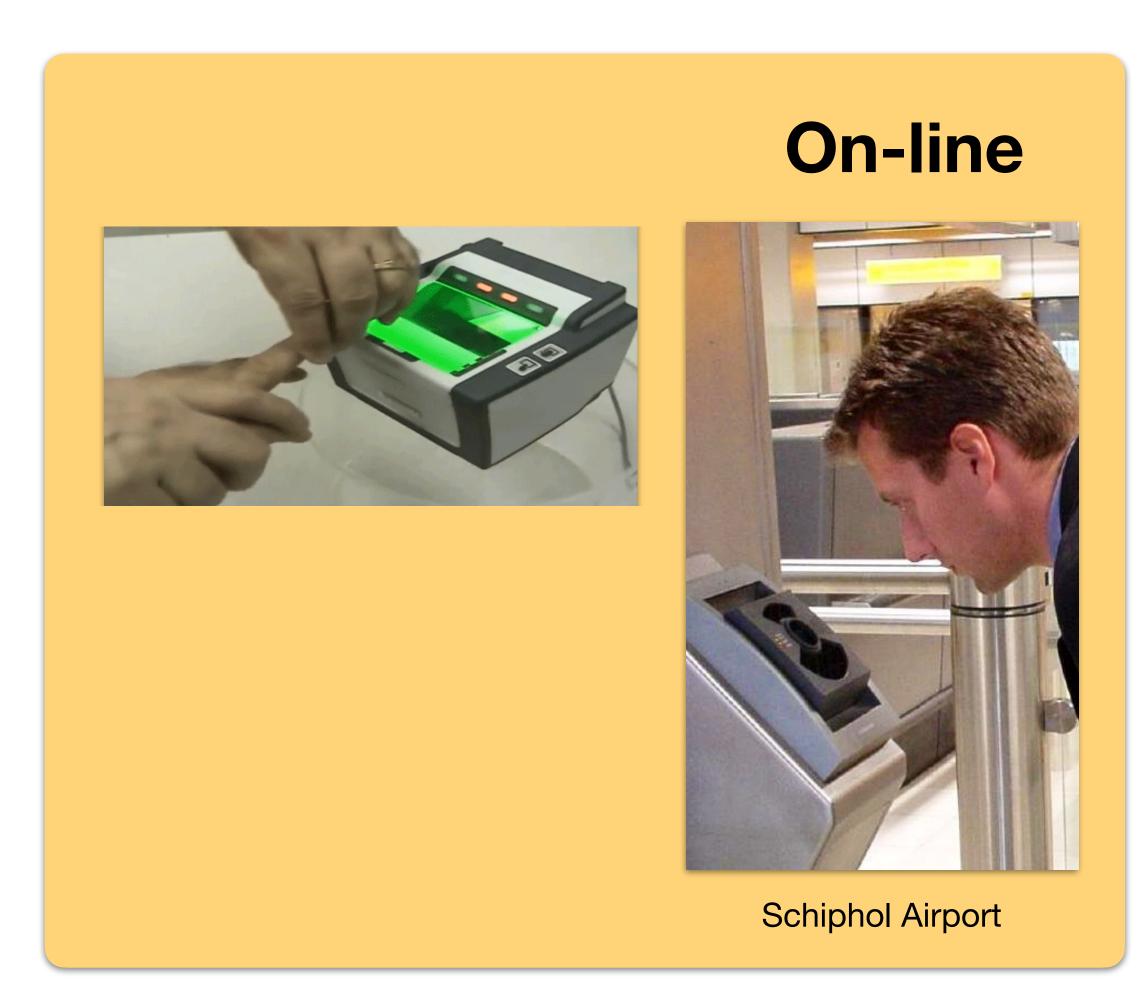


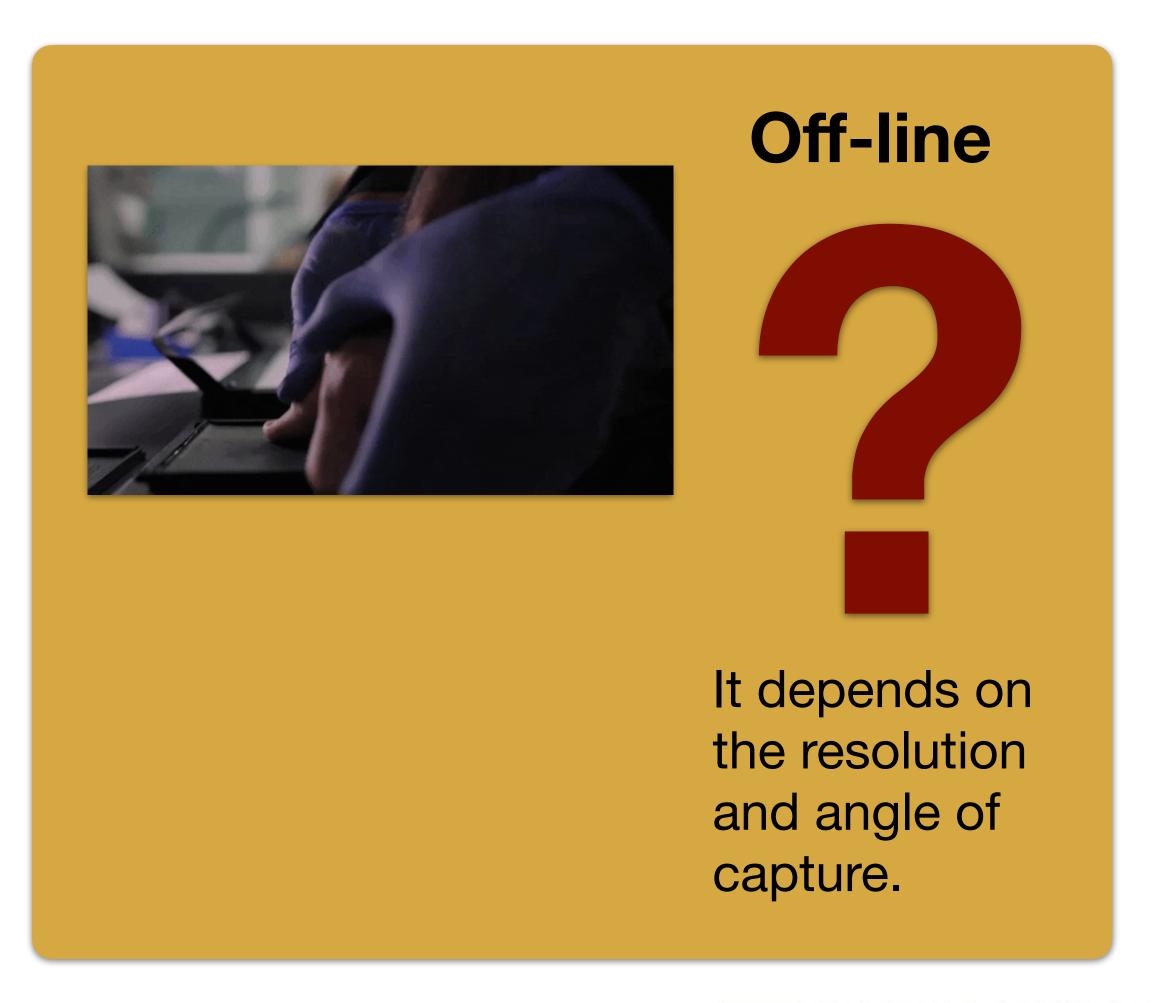










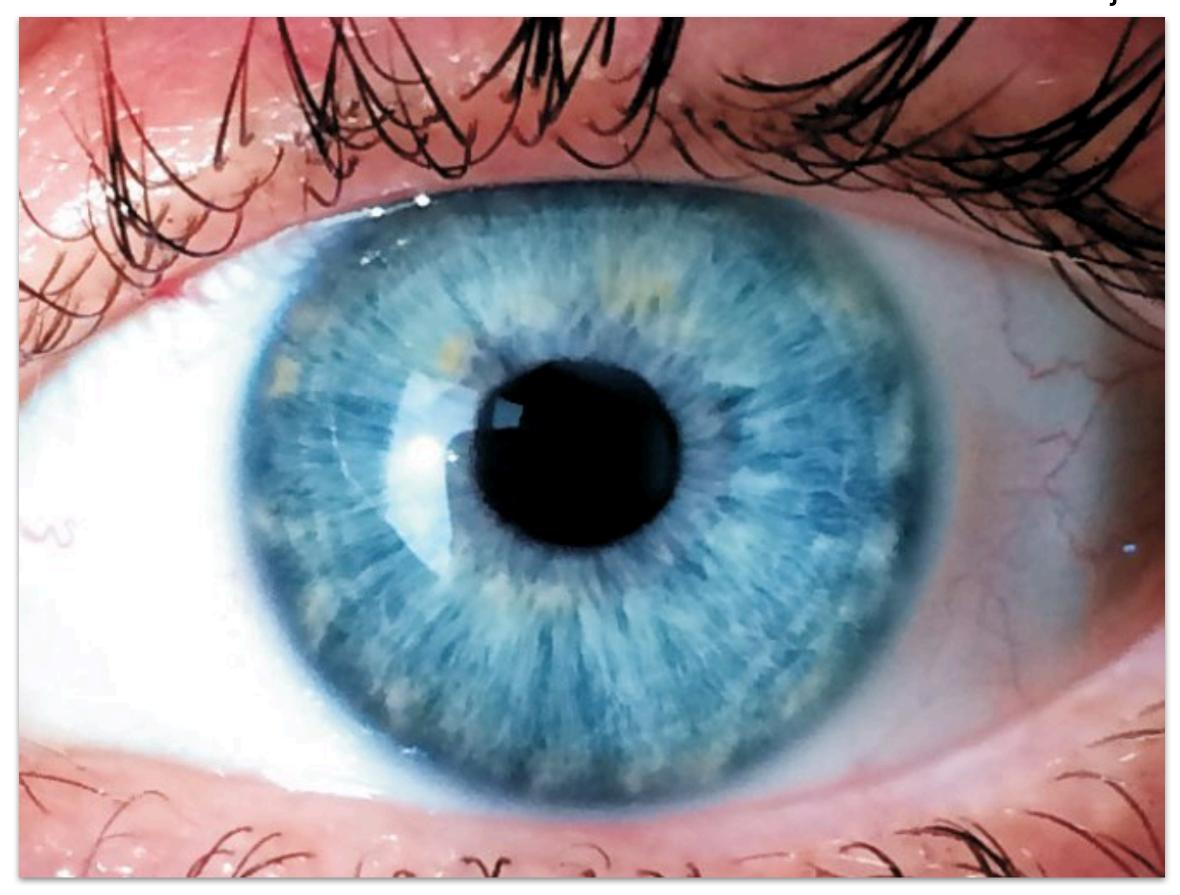




Dr. Adam Czajka

Iris Capture
Visible light.

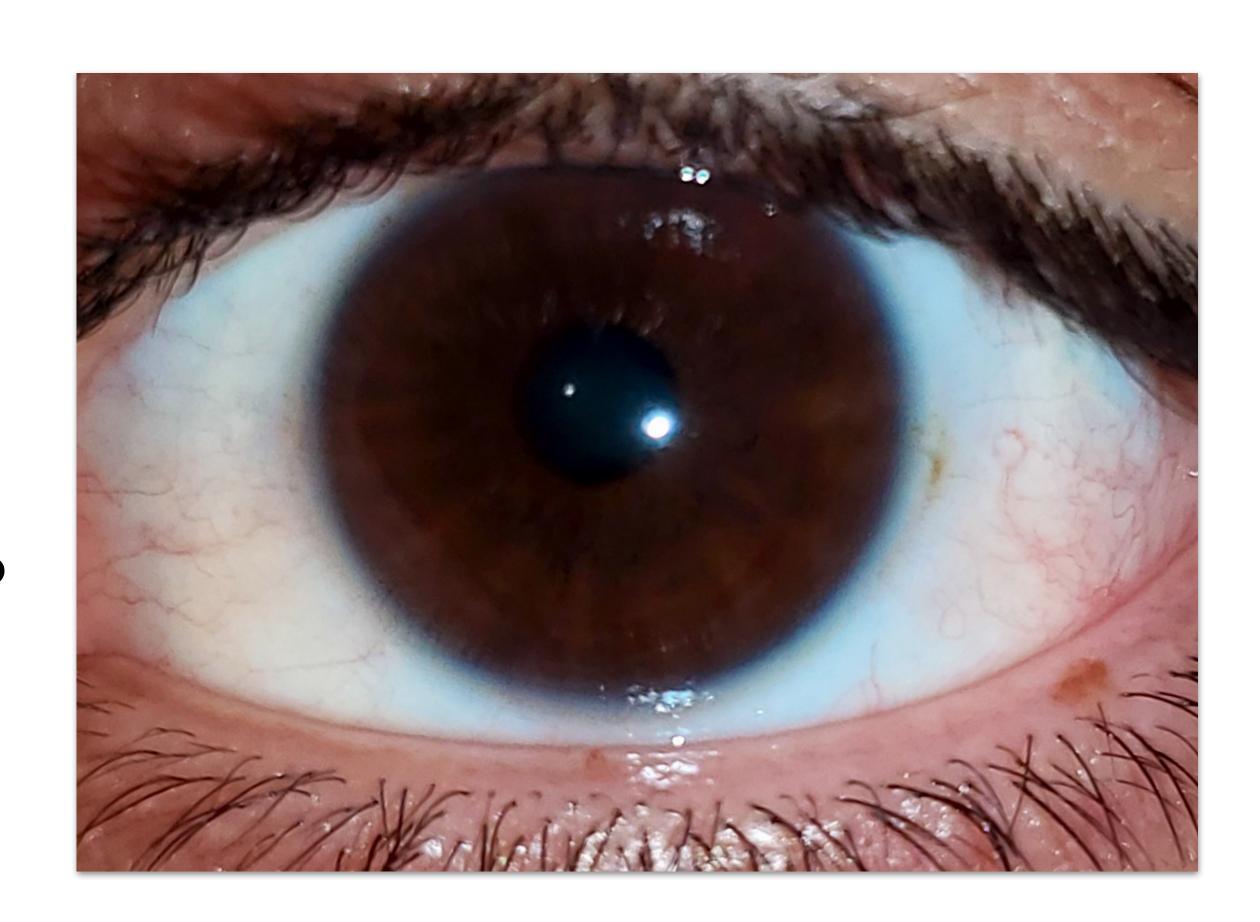
Can you see the iris texture (crypts, furrows, and collarette)?





Iris Capture
Visible light.

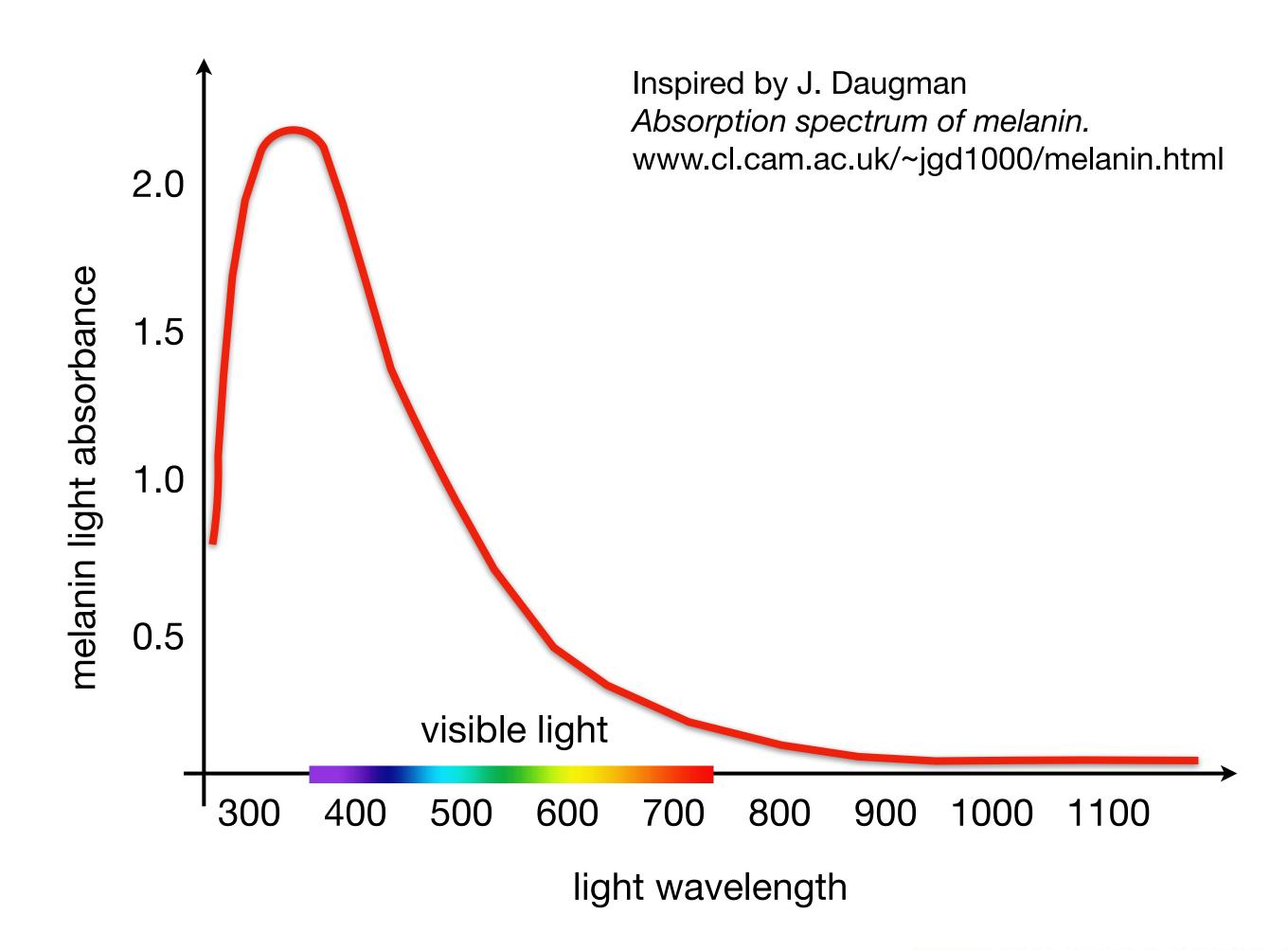
Can you see the iris texture (crypts, furrows, and collarette)?





Iris Capture
Visible light.

Melanin poses a challenge to visible-light iris recognition.

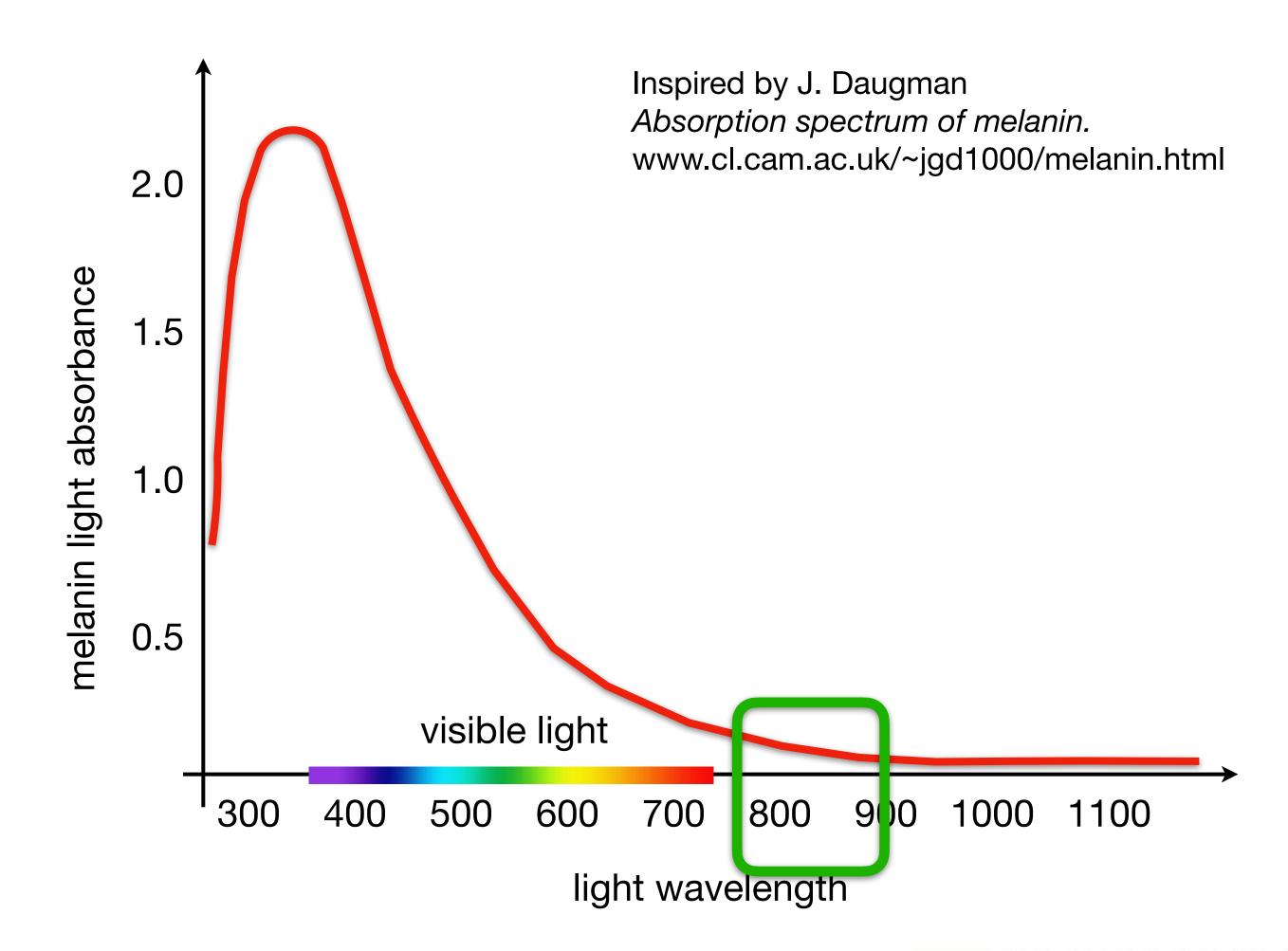




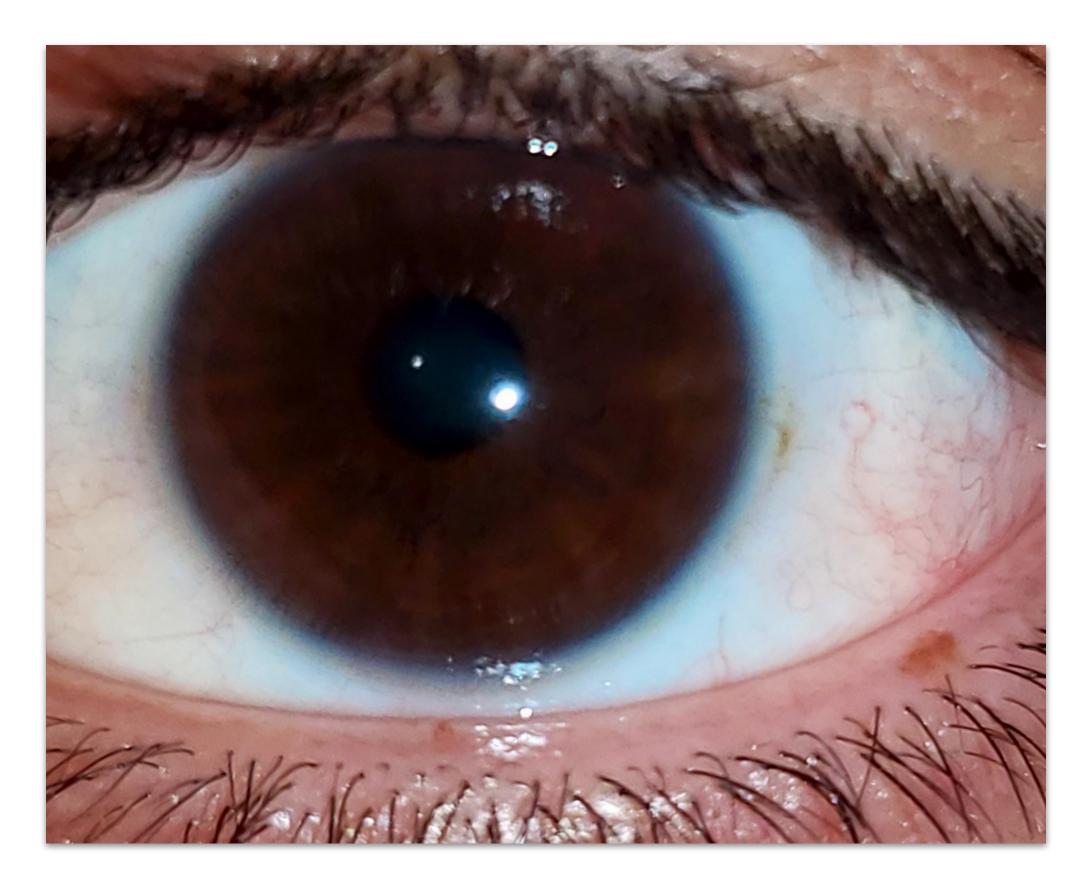
#### **Iris Capture**

Solution: near-infrared (NIR) light.

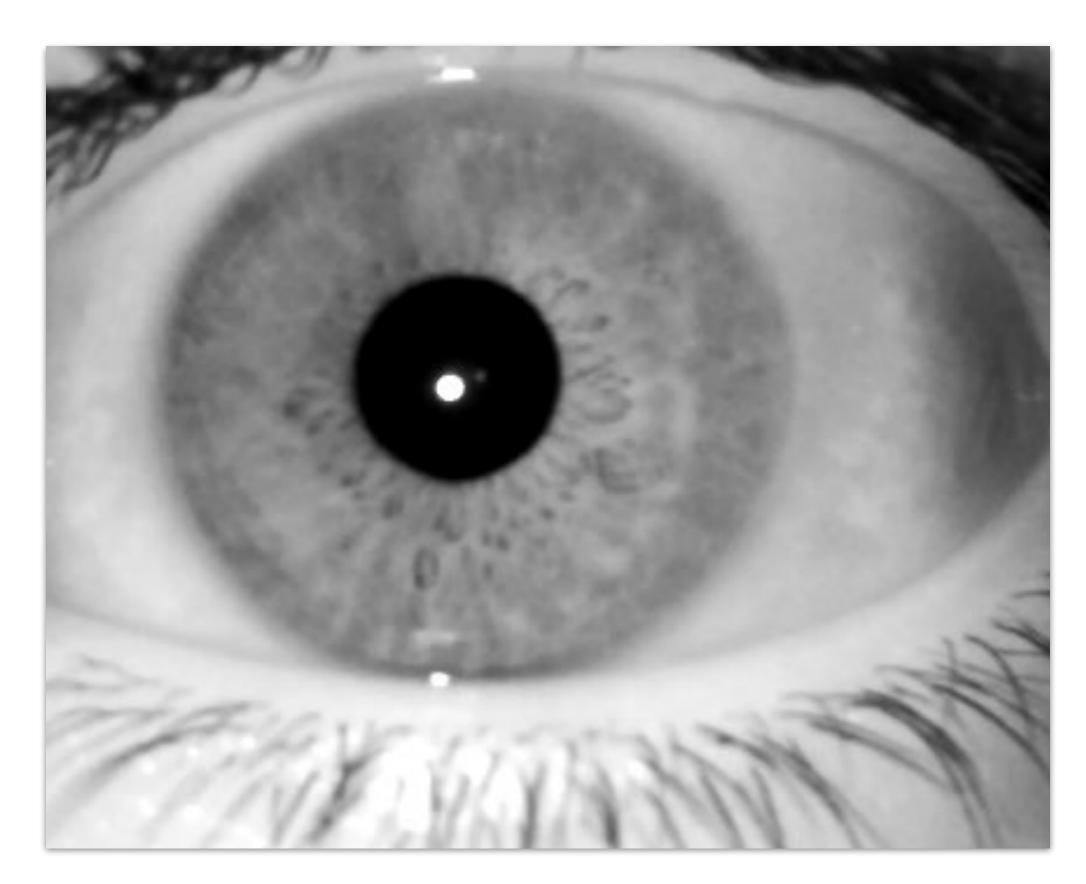
Typical wavelengths used by sensors: 750-890 nm.







visible light



NIR



#### **Standards**

#### **Eye Safety**

IEC 60825-1:1993

(+ addendum A1:1997 and A2:2001),

ANSI RP-27.1-96



 $MPE < 0.1 \times MPE_{max}$ 

eye damage due to light exposure





#### **Standards**

Image Quality
ISO/IEC 19794-6 and ISO/IEC 29794-6

wavelength: 700-900 nm

resolution: ≥ 20 lines per iris diameter

non-occluded iris area: ≥ 70%

gray scale: ≥ 6 bits

typical resolution: 640 x 480 pixels





# **Sensors**With cooperation.

Jim Wilson / The New York Times



LG Iris Access 3000

Dr. Adam Czajka



CrossMatch

Dr. Adam Czajka



IG-AD100



#### Sensors

With almost no cooperation.

#### **Multiple-Resolution Cameras**

Wide-angle camera for face detection. Narrow-angle cameras for iris capture.

https://www.youtube.com/watch?v=bolNgCrCZW0



Sarnoff Corp., Iris-on-the-move Gate



Dr. Adam Czajka

#### Sensors

With almost no cooperation.

#### **Deformable Mirrors**

Similar to astronomical telescopes.

Fast adaptation at presentation time.

Capture at 1.5-2.5m

of distance.







AOptix Insight SD, 2008



#### Sensors

Current trend: miniaturization.

#### Example 1

Android-based *Fidelys* smartwatch.



linuxgizmos.com/ worlds-first-iris-recognition-smartwatch-runs-android



#### Sensors

Current trend: miniaturization.

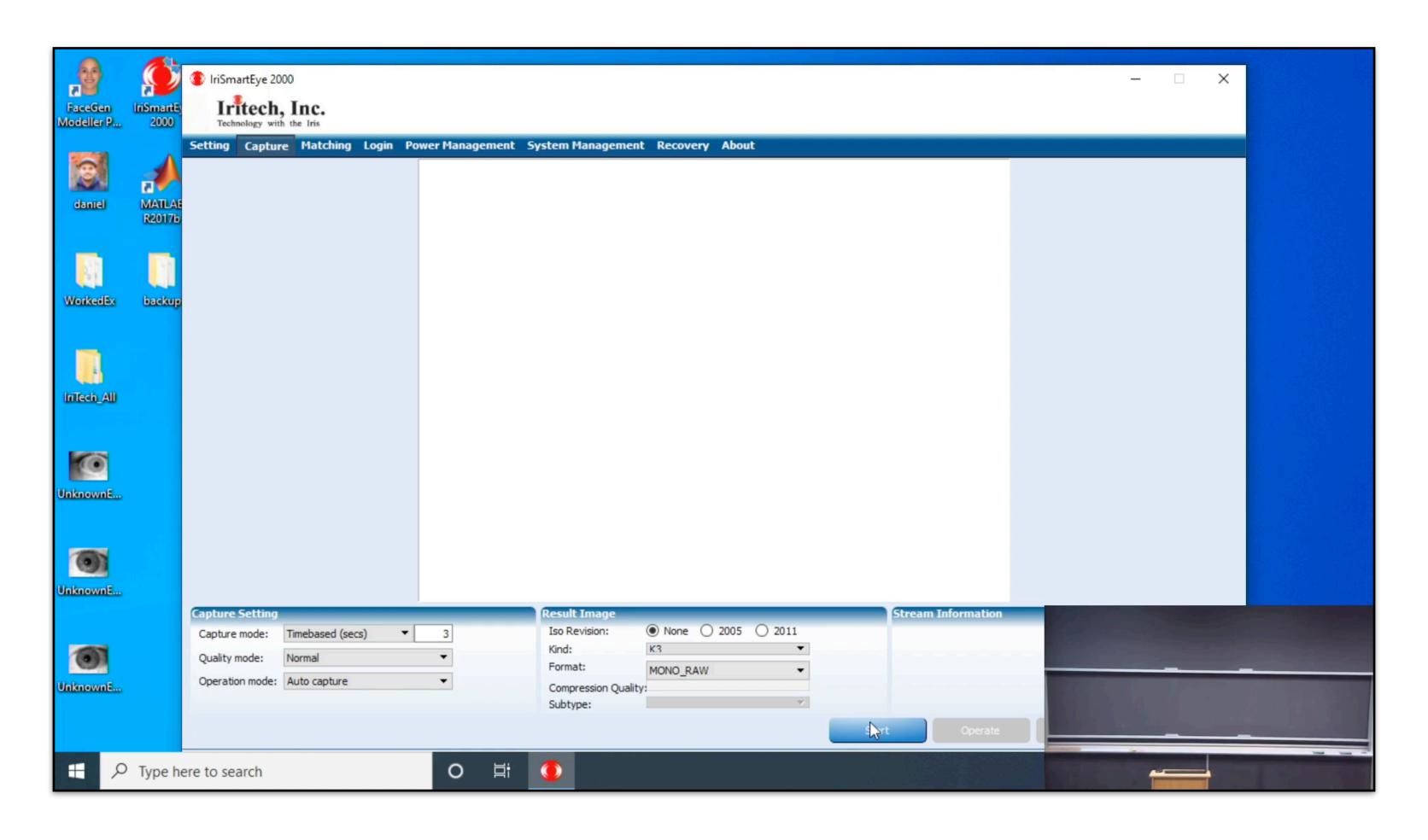
### Example 2 IriShield USB

This is the one we'll use to collect data.



https://urvashicomputers.com/irishield-mk-2120-series/







#### Challenges

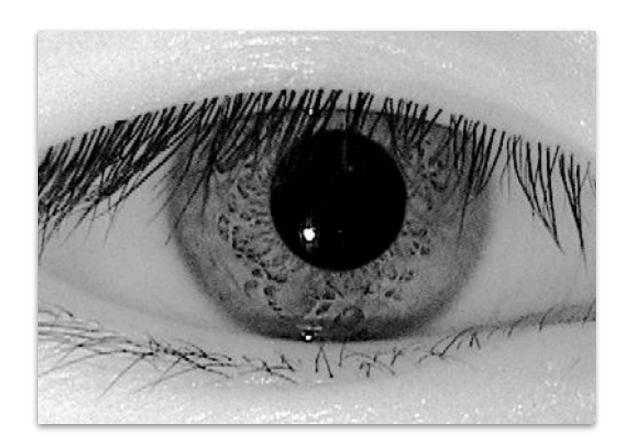
**Deformations and Occlusions** 

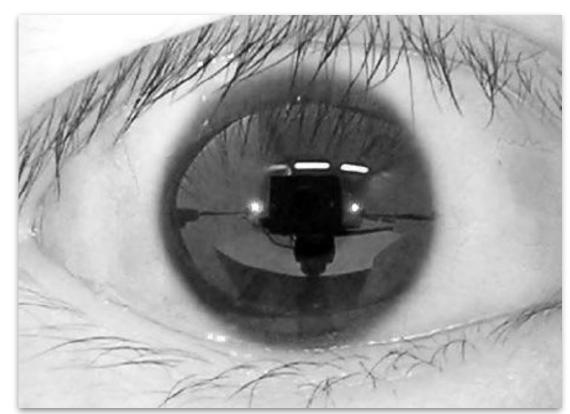
Eyelids and eyelashes.

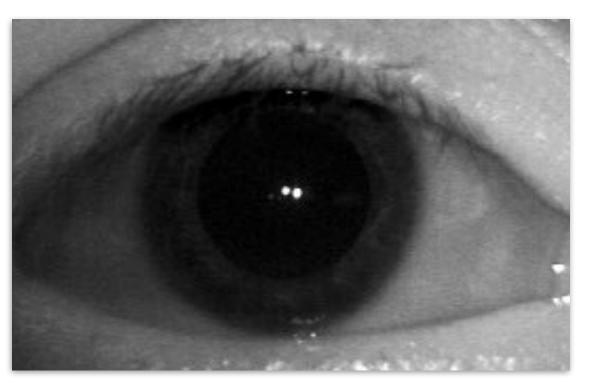
Specular reflections.

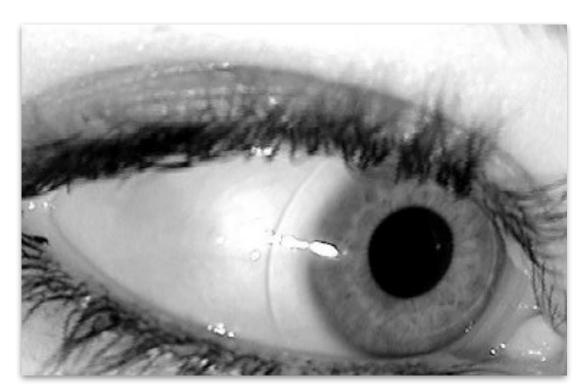
Pupil dilation.

Head movement, off-axis gaze.









http://www.cse.nd.edu/BTAS\_07/John\_Daugman\_BTAS.pdf



#### Challenges

User Cooperation
It is easy for people to protect their irises from capture.



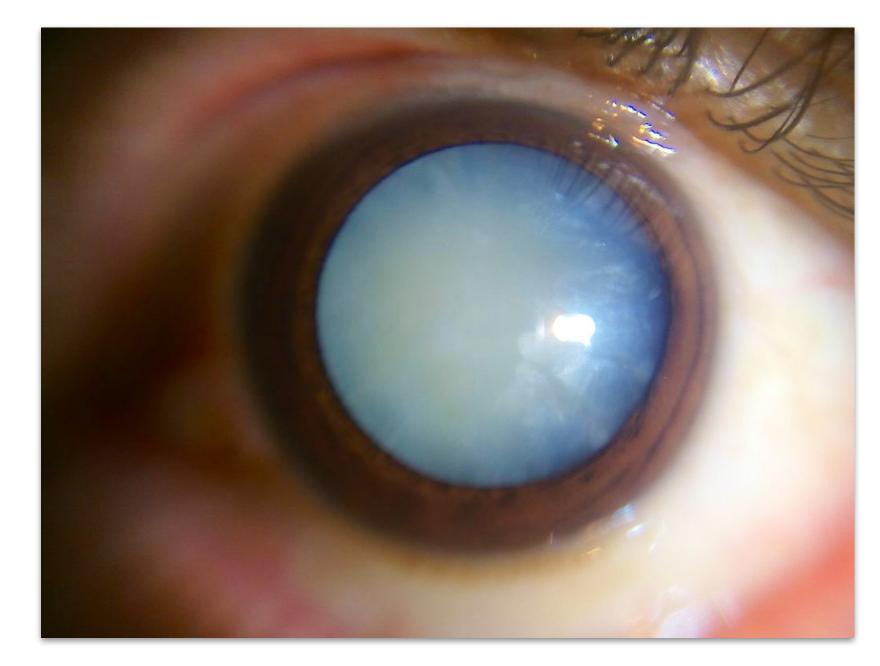


#### Challenges

#### **Diseases**

E.g., cataracts, conjunctivitis. Is iris visible? Is the disease contagious?

commons.wikimedia.org



E.g., cataracts.

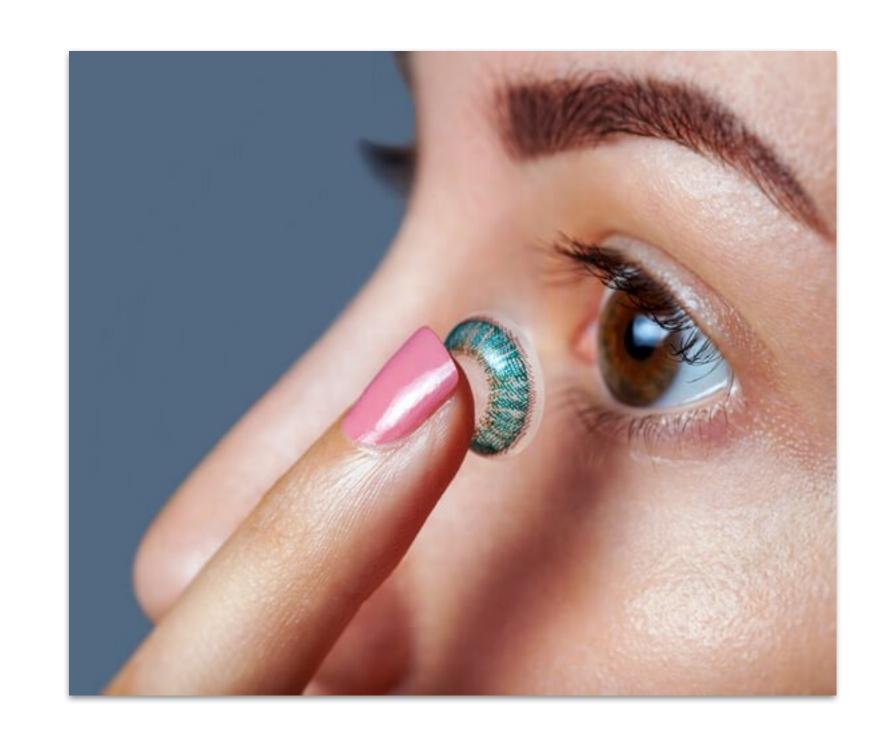


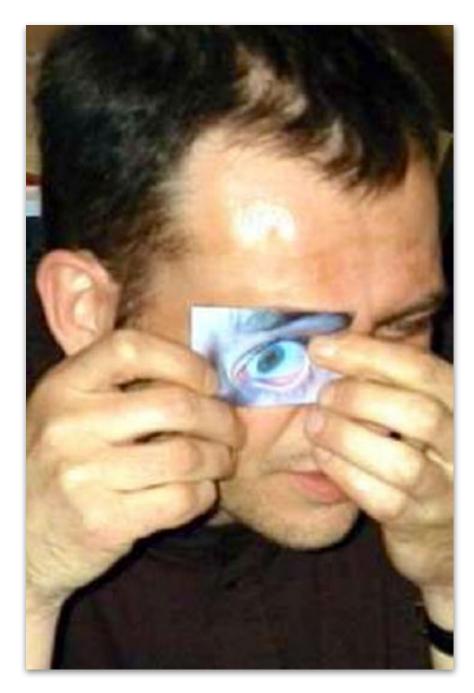
#### Challenges

#### **Attacks**

Obfuscation with texturized contact lenses.

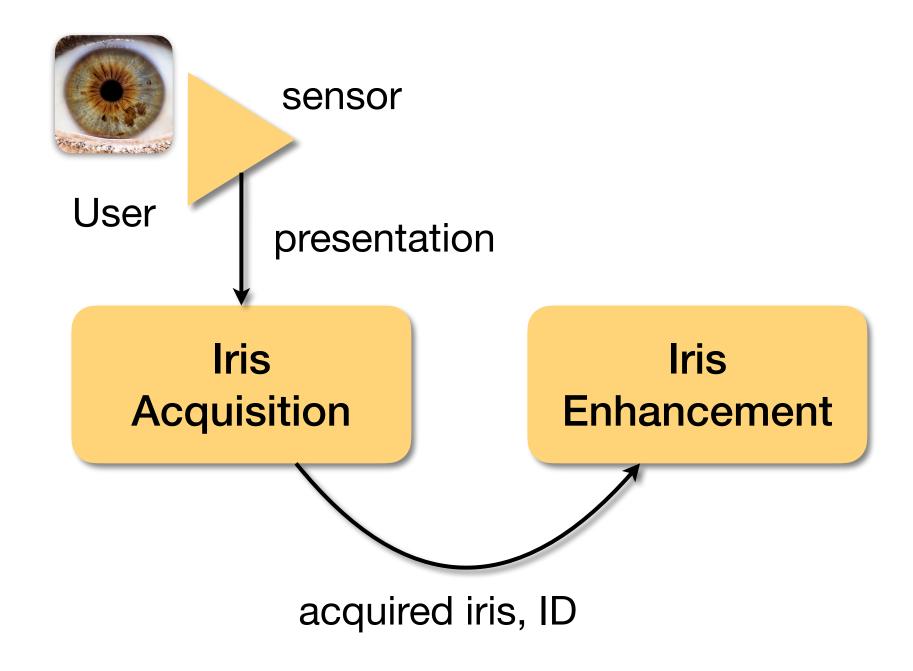
Presentation attack (see demonstration).





Jain, Ross, and Nadakumar Introduction to Biometrics Springer Books, 2011







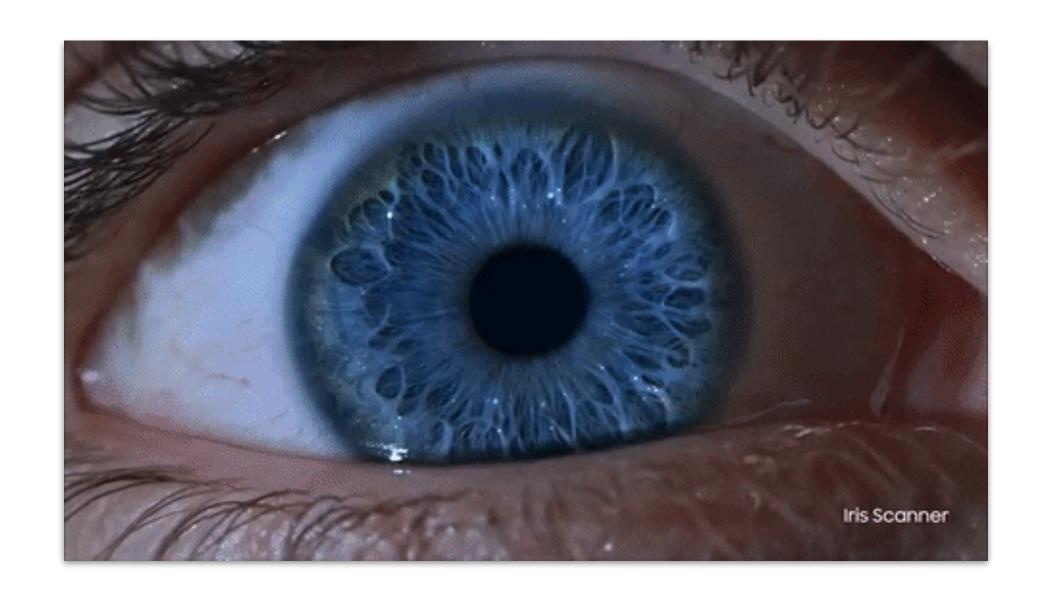
#### **Steps**

#### Segmentation

Keep only useful information (iris texture).

#### Normalization

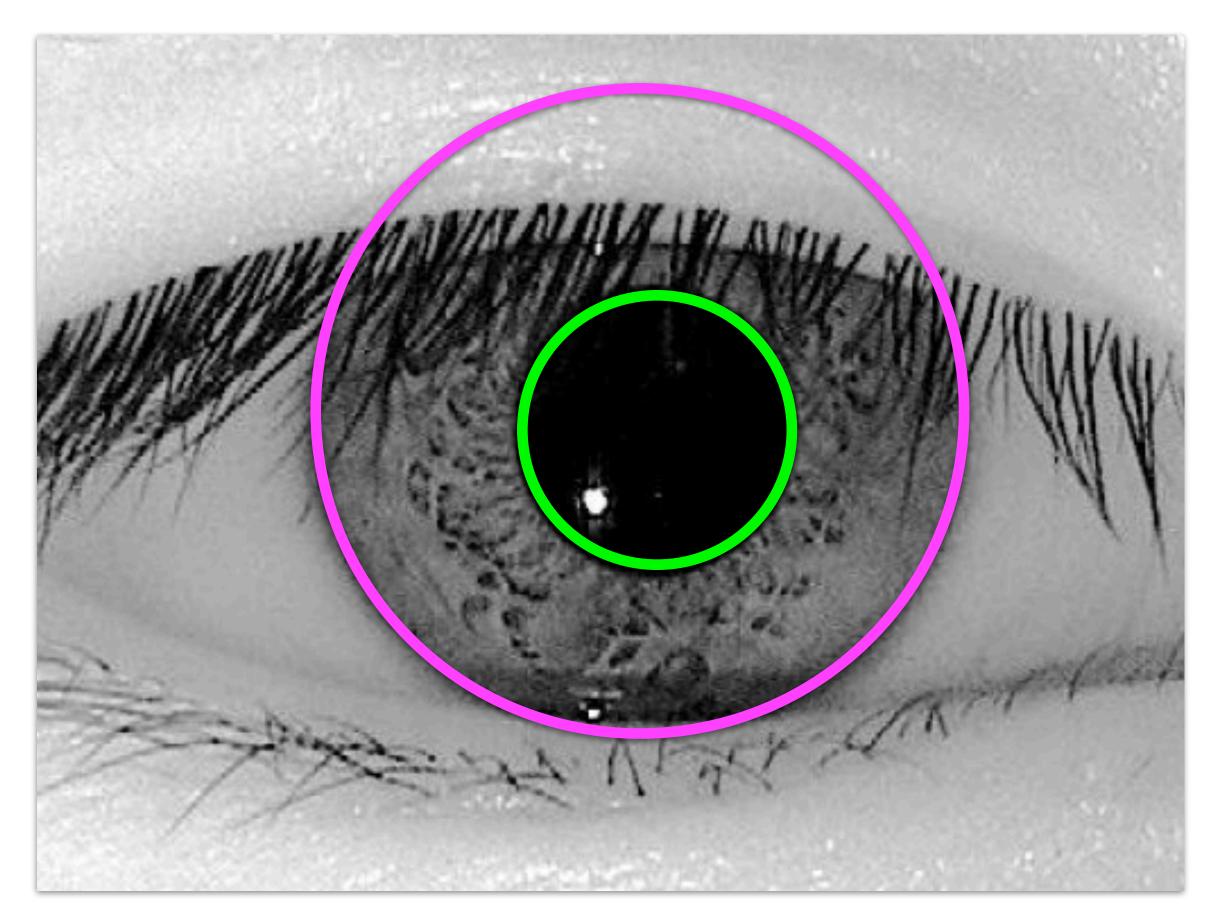
Make different captures of the same iris look as similar as possible.





### Segmentation (1/2)

Iris and Pupil Localization Localize limbus and pupillary boundaries.



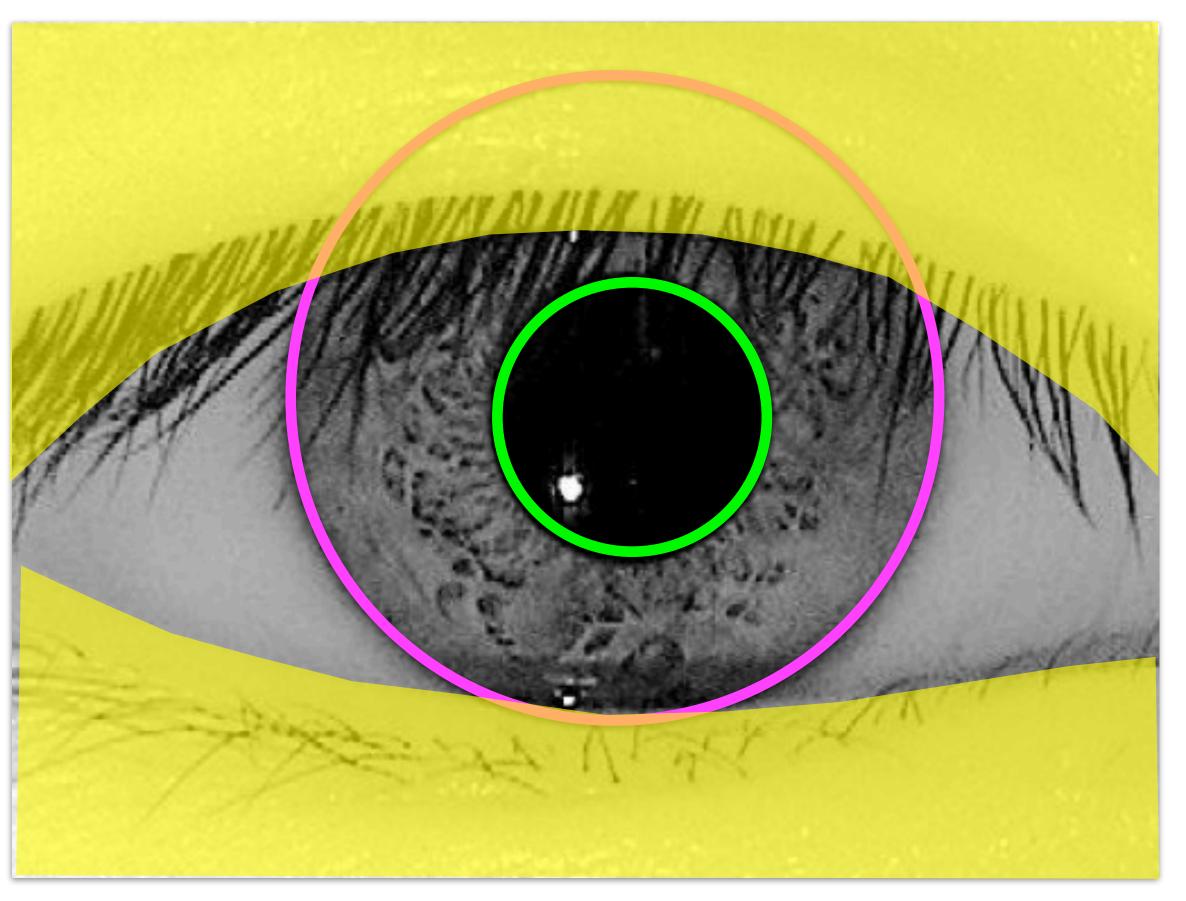
http://www.cse.nd.edu/BTAS\_07/John\_Daugman\_BTAS.pdf



#### Segmentation (1/2)

Iris and Pupil Localization Localize limbus and pupillary boundaries.

Eyelid, Eyelash, and
Specular Reflection Detection
Deal with iris texture occlusions.



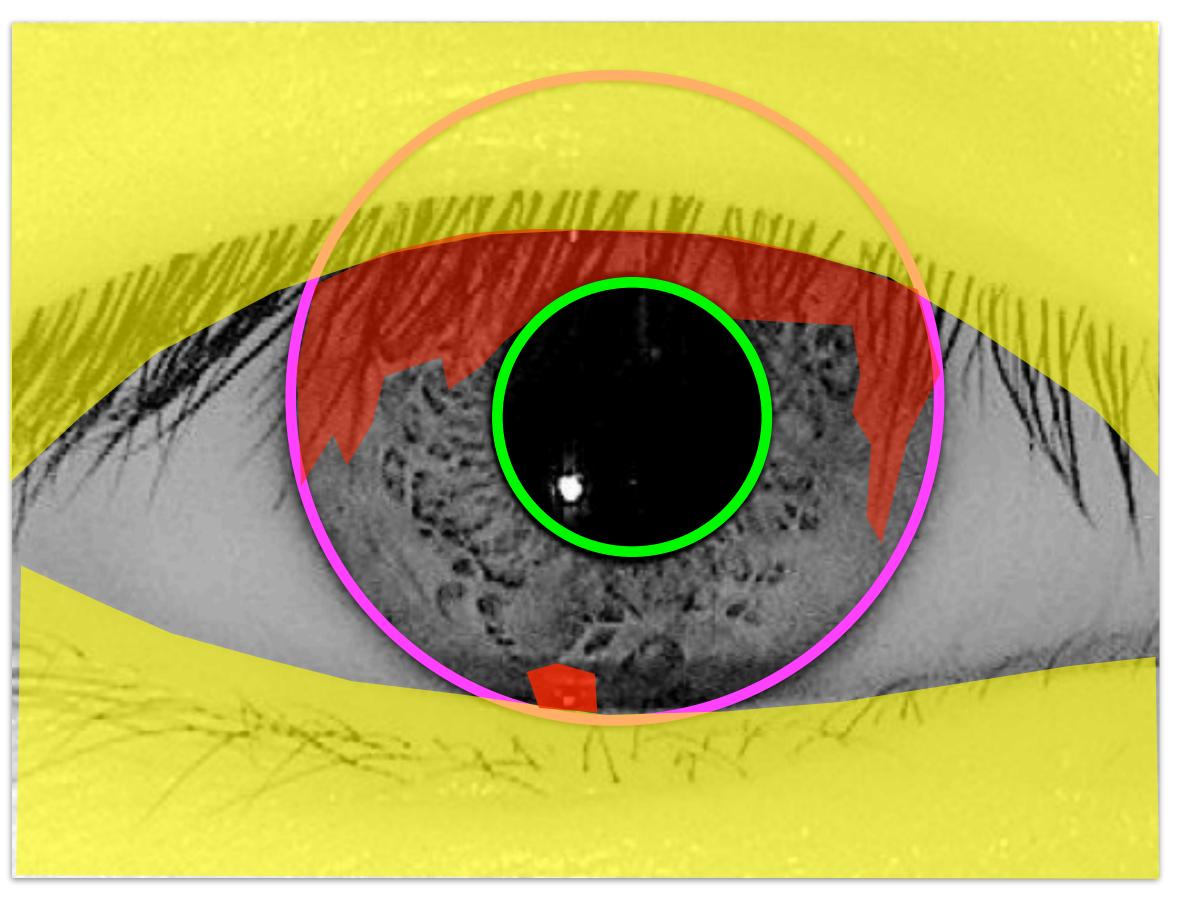
http://www.cse.nd.edu/BTAS\_07/John\_Daugman\_BTAS.pdf



#### Segmentation (1/2)

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http://www.cse.nd.edu/BTAS\_07/John\_Daugman\_BTAS.pdf

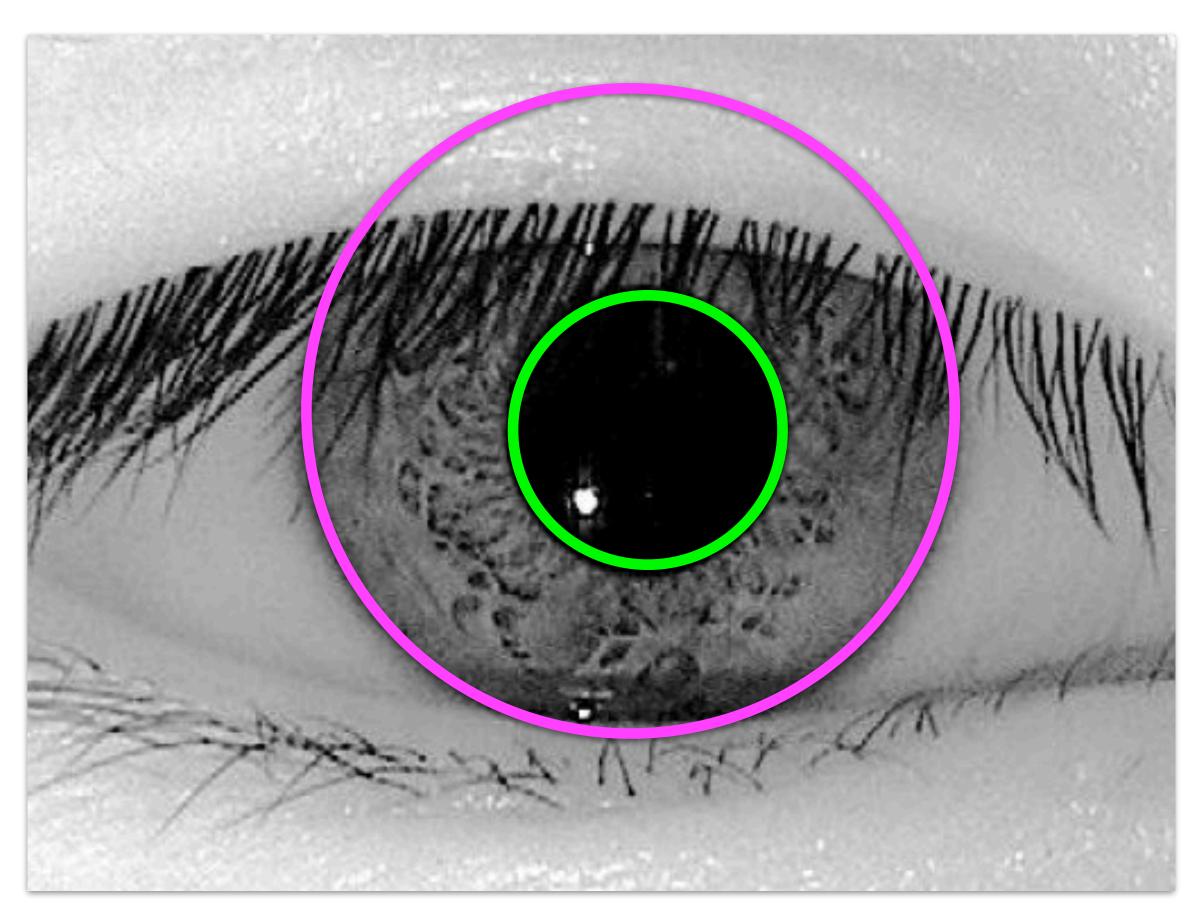


#### Segmentation (1/2)

Iris and Pupil Localization
Method 1: Integral-differential
operator

#### Objective:

Find  $(r, x_0, y_0)$  of **limbus** and  $(r, x_0, y_0)$  of **pupillary** boundaries.



http://www.cse.nd.edu/BTAS\_07/John\_Daugman\_BTAS.pdf



### Segmentation (1/2)

**Iris and Pupil Localization** 

Method 1: Integral-differential operator

Strategy:

Try various values for  $(r, x_0, y_0)$ .

3. derivative of integral

2. integral of circle with radius r

1. pixel values

$$\max_{r,x_0,y_0} \left| g_{\sigma}(r) * \frac{\delta}{\delta r} \oint_{r,x_0,y_0} \frac{I(x,y)}{2\pi r} ds \right|$$

5. get the  $(r, x_0, y_0)$  configuration with maximum values

4. smoothing function (gaussian)



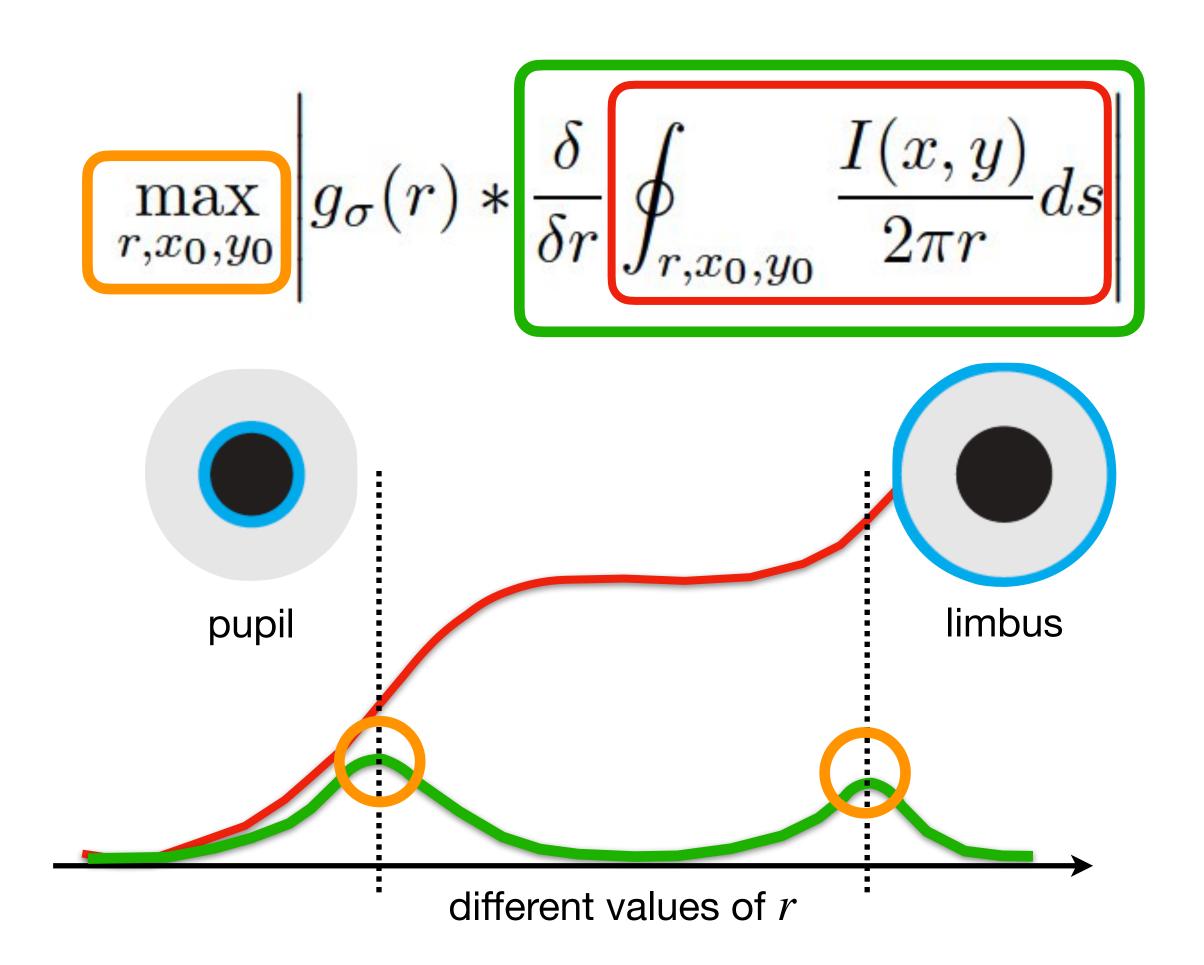
### Segmentation (1/2)

Iris and Pupil Localization

Method 1: Integral-differential operator

Strategy:

Try various values for  $(r, x_0, y_0)$ .



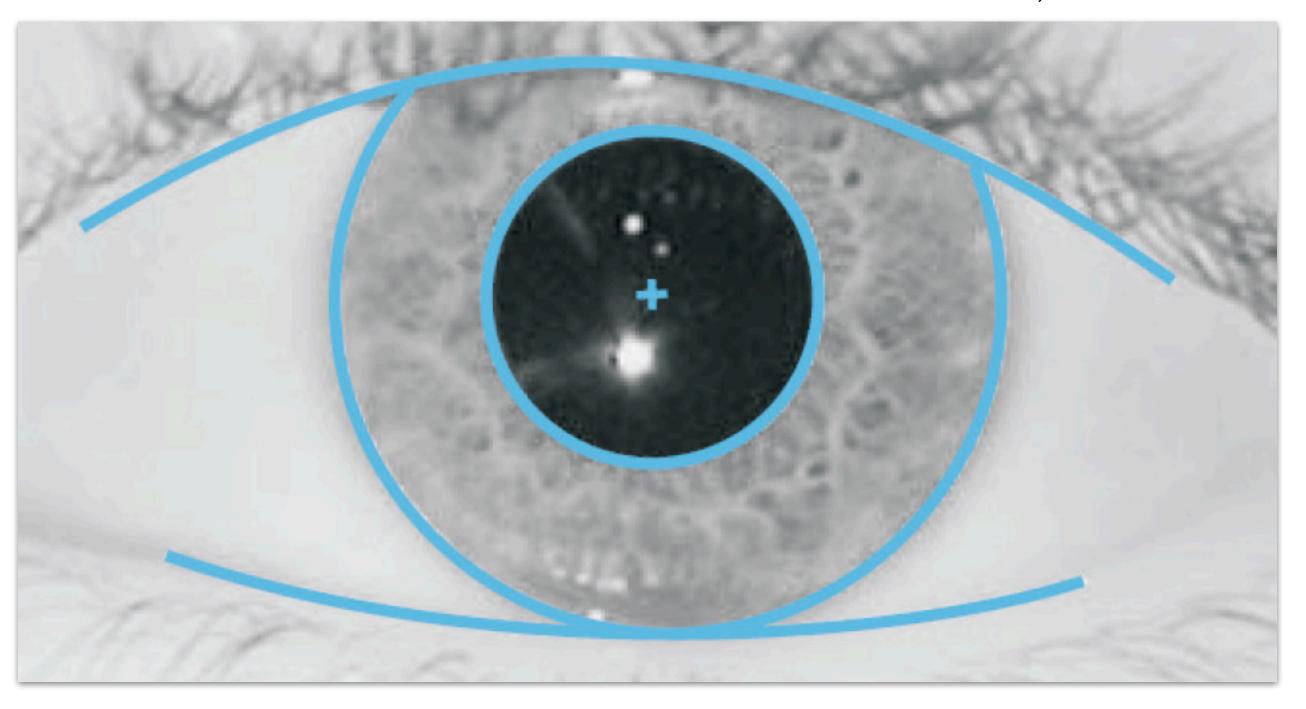


### Segmentation (1/2)

Iris and Pupil Localization Method 1: Integral-differential operator

J. Daugman

How Iris Recognition Works
IEEE TCSVT, 2004

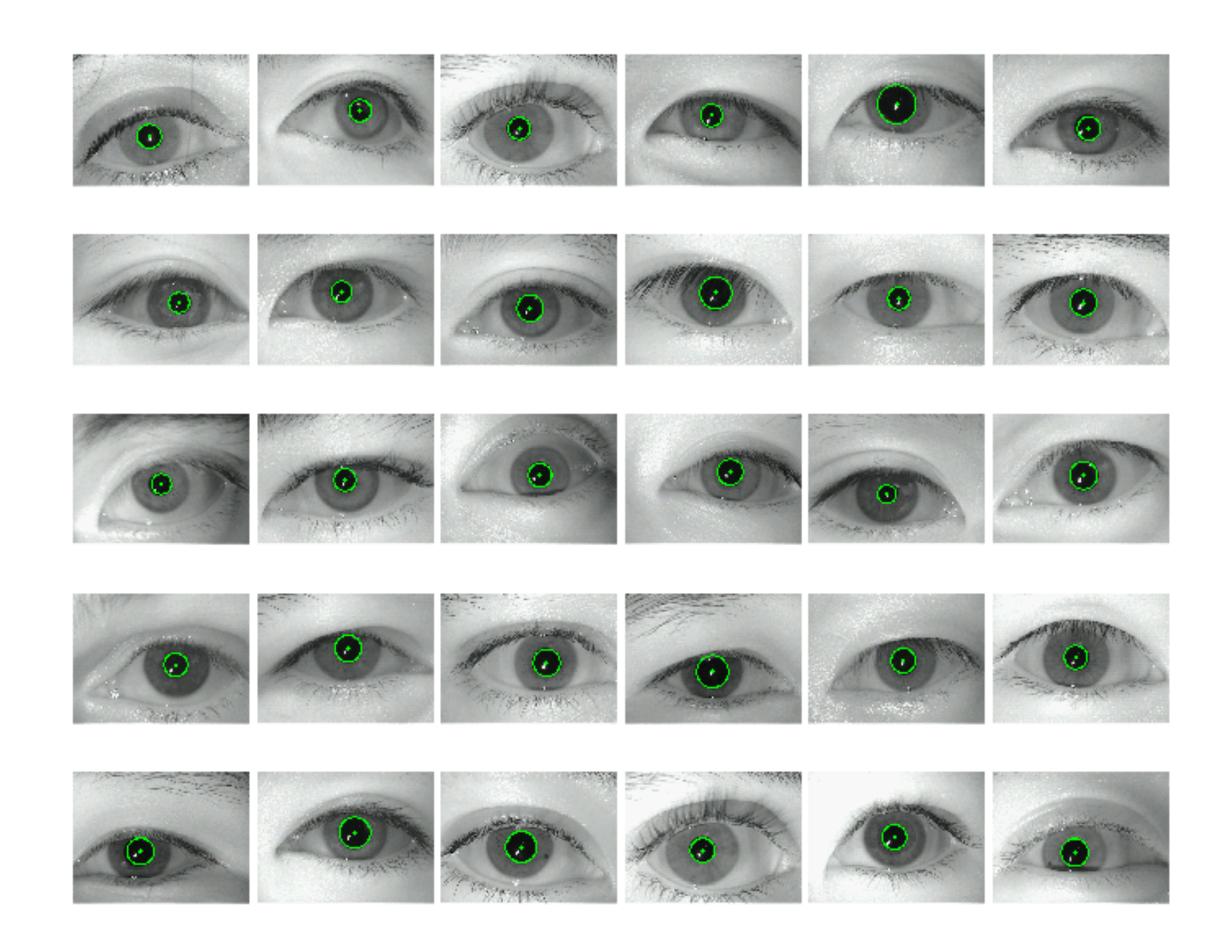


result example



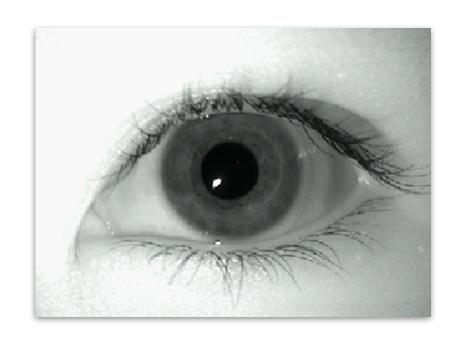
#### Segmentation (1/2)

Iris and Pupil Localization
Method 2: Image processing
ending with Hough circle
transform.

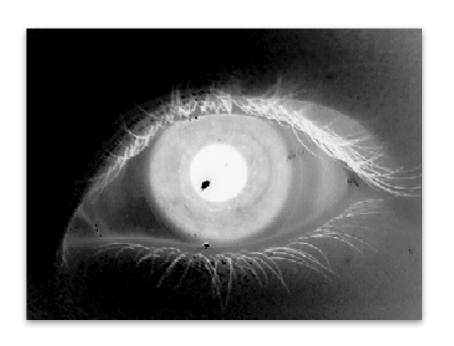


https://github.com/olesiamidiana/iris-recognition-py

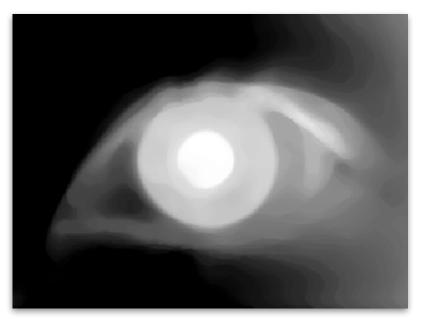




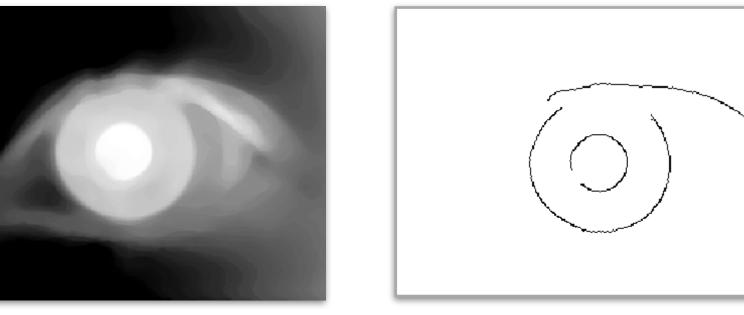
1.grayscale



2. inverted

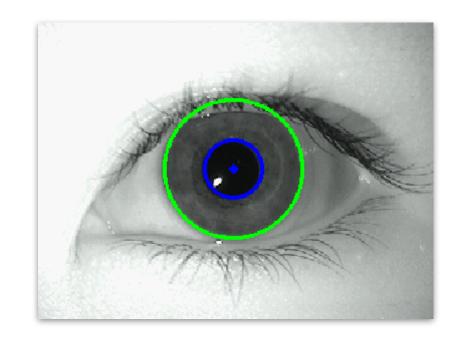


3. median blur



4. Canny edge detector

https://github.com/olesiamidiana/iris-recognition-py



5. Hough circle transform



### Segmentation (1/2)

Eyelids, eyelashes, specular highlights

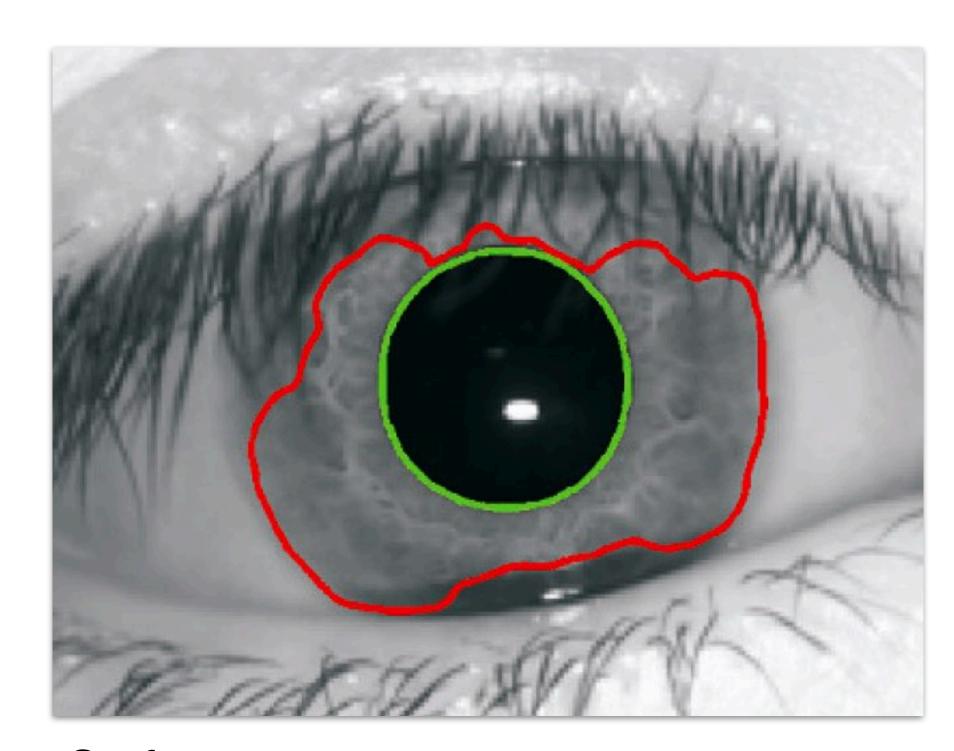
Fit of parabolic curves for eyelids.

Active contours (curve evolution)

to avoid eyelashes.

Fit of elliptical curves for specular highlights.

Machine learning from annotated examples.

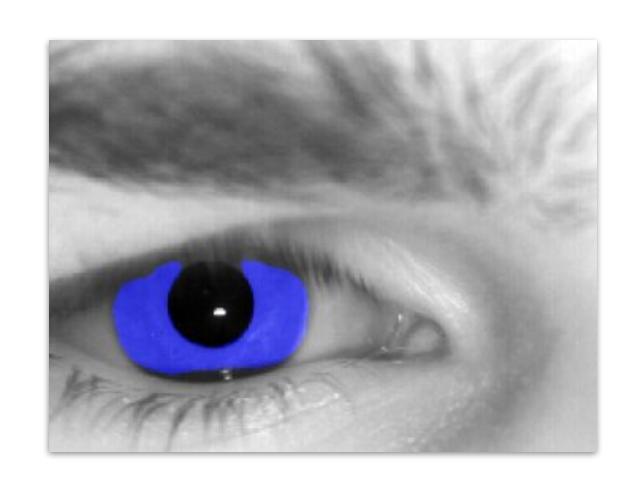


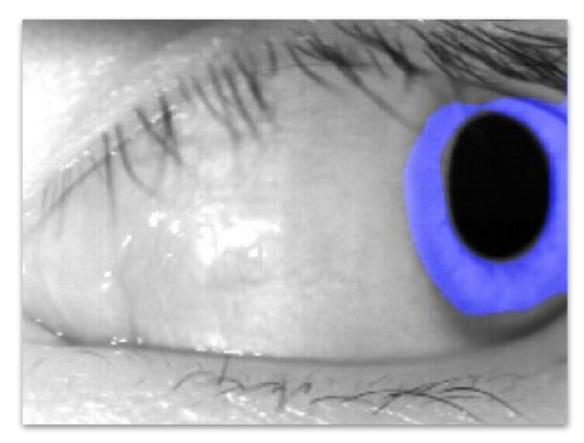
Gutfeter Active contours for iris segmentation. BSc Thesis, WUT, 2010



#### Segmentation (1/2)

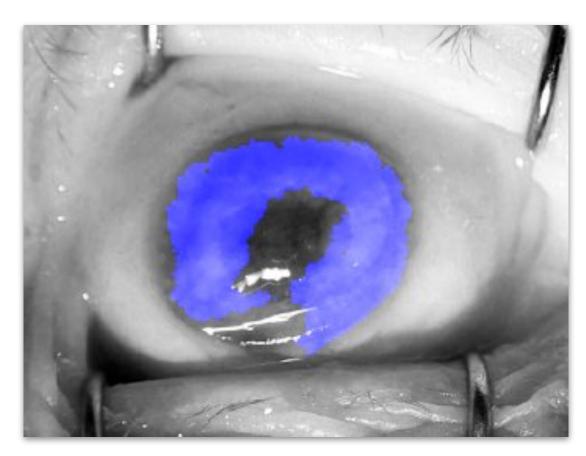
# Iris Localization Convolutional Neural Networks (machine learning trained with annotation examples).





Kerrigan et al.

Iris Recognition with Image
Segmentation Employing
Retrained Off-the-Shelf Deep Neural
Networks
https://arxiv.org/abs/1901.01028, 2019





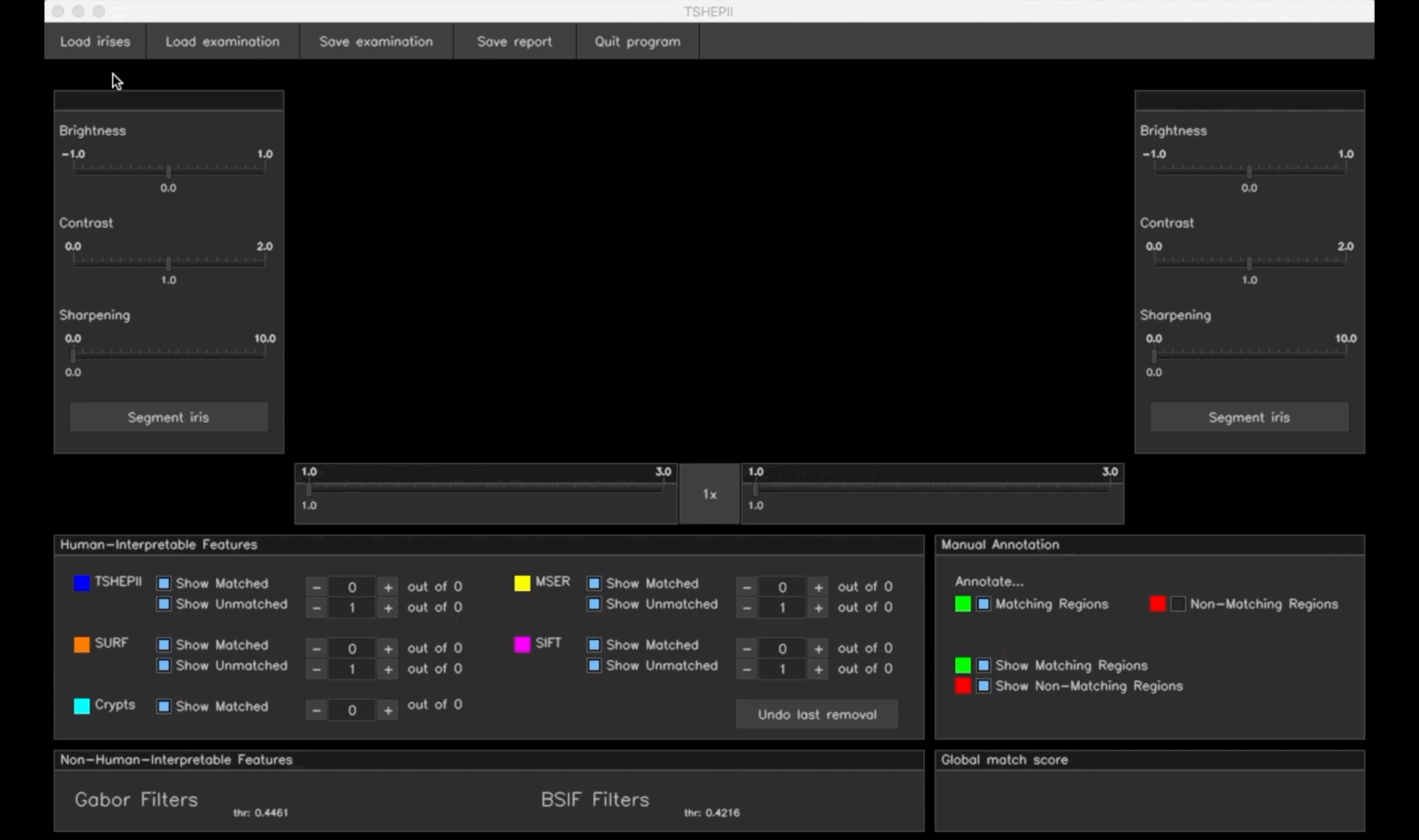
#### Segmentation (1/2)

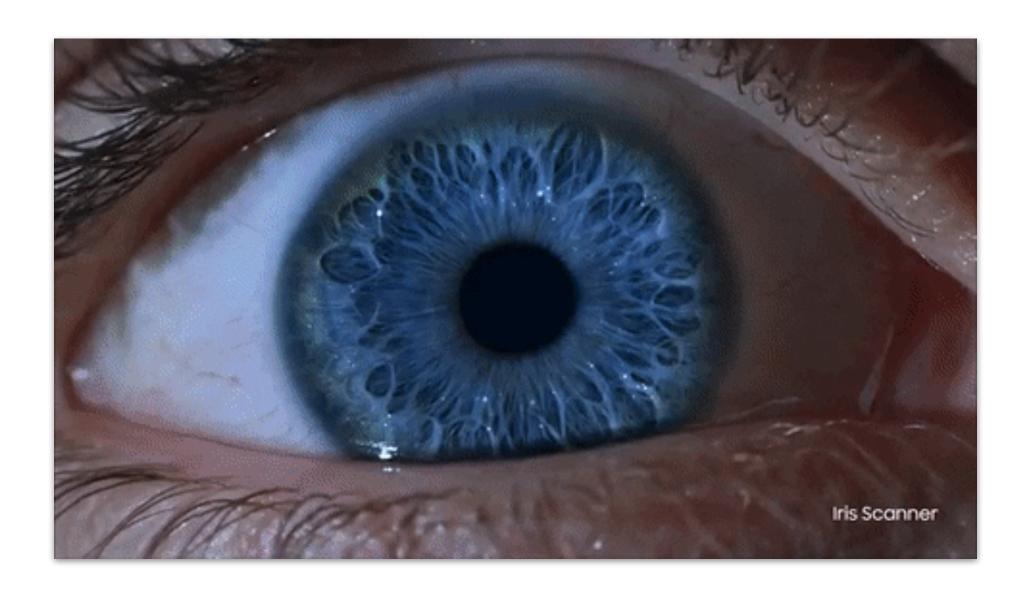
#### **Manual Segmentation**

Next slide: iris recognition tool that we have developed at Notre Dame.







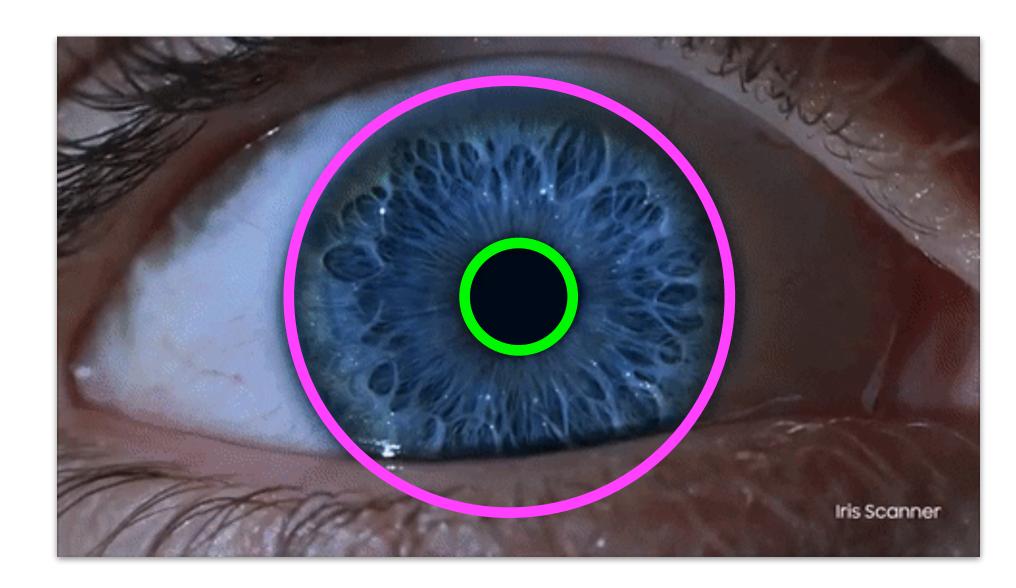


source

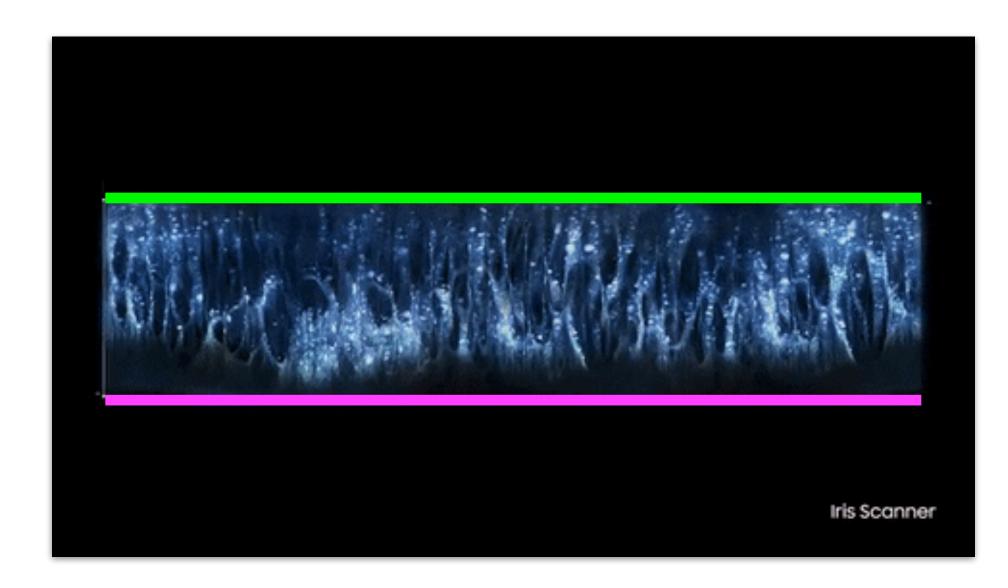


target



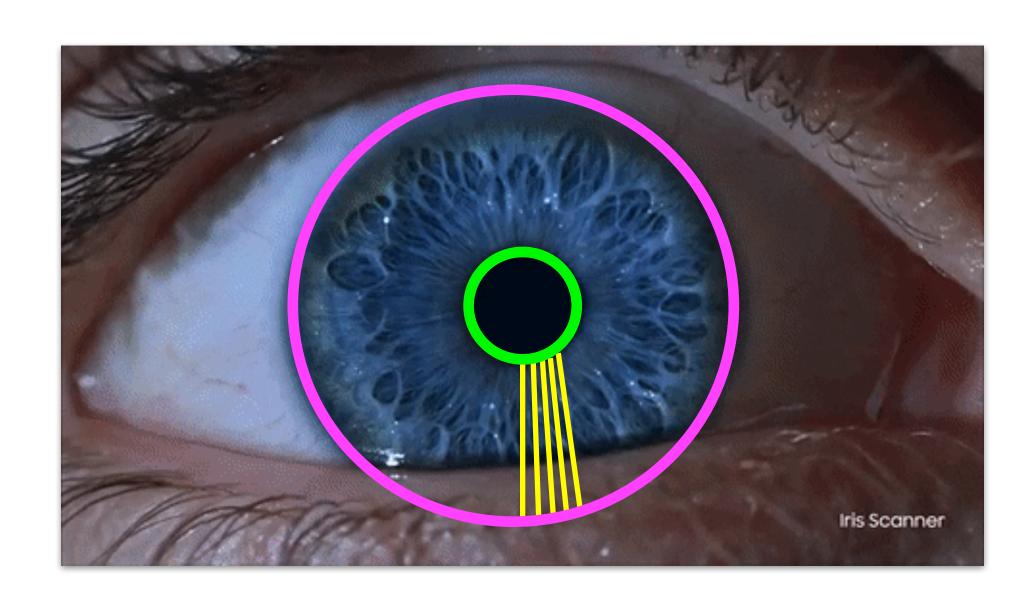


source

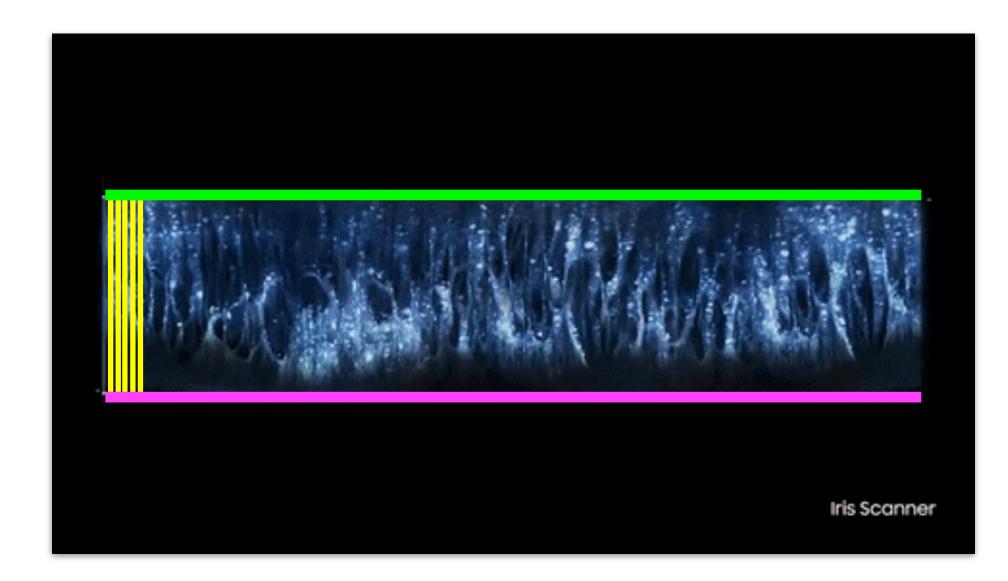


target



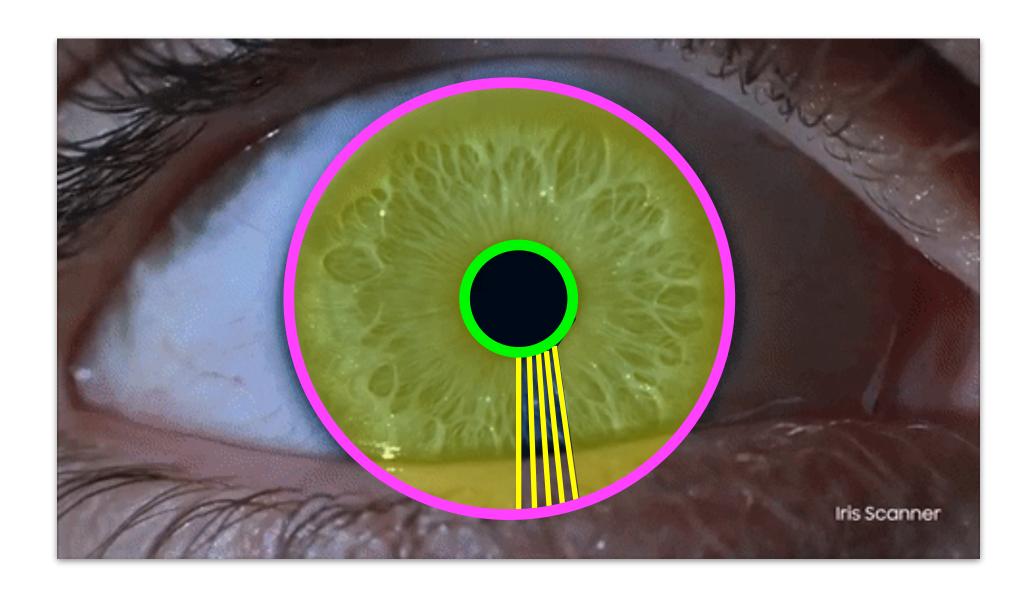


source

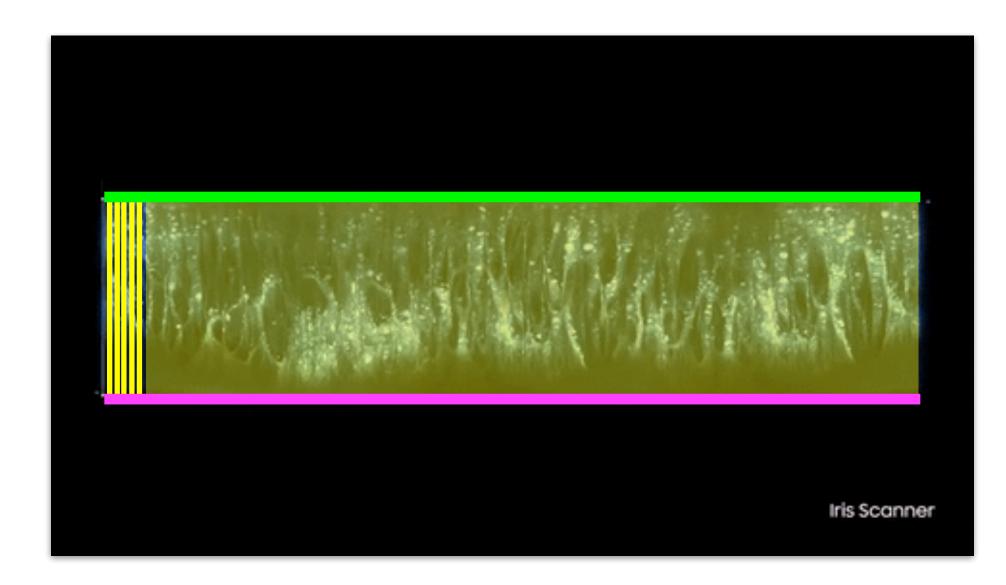


target



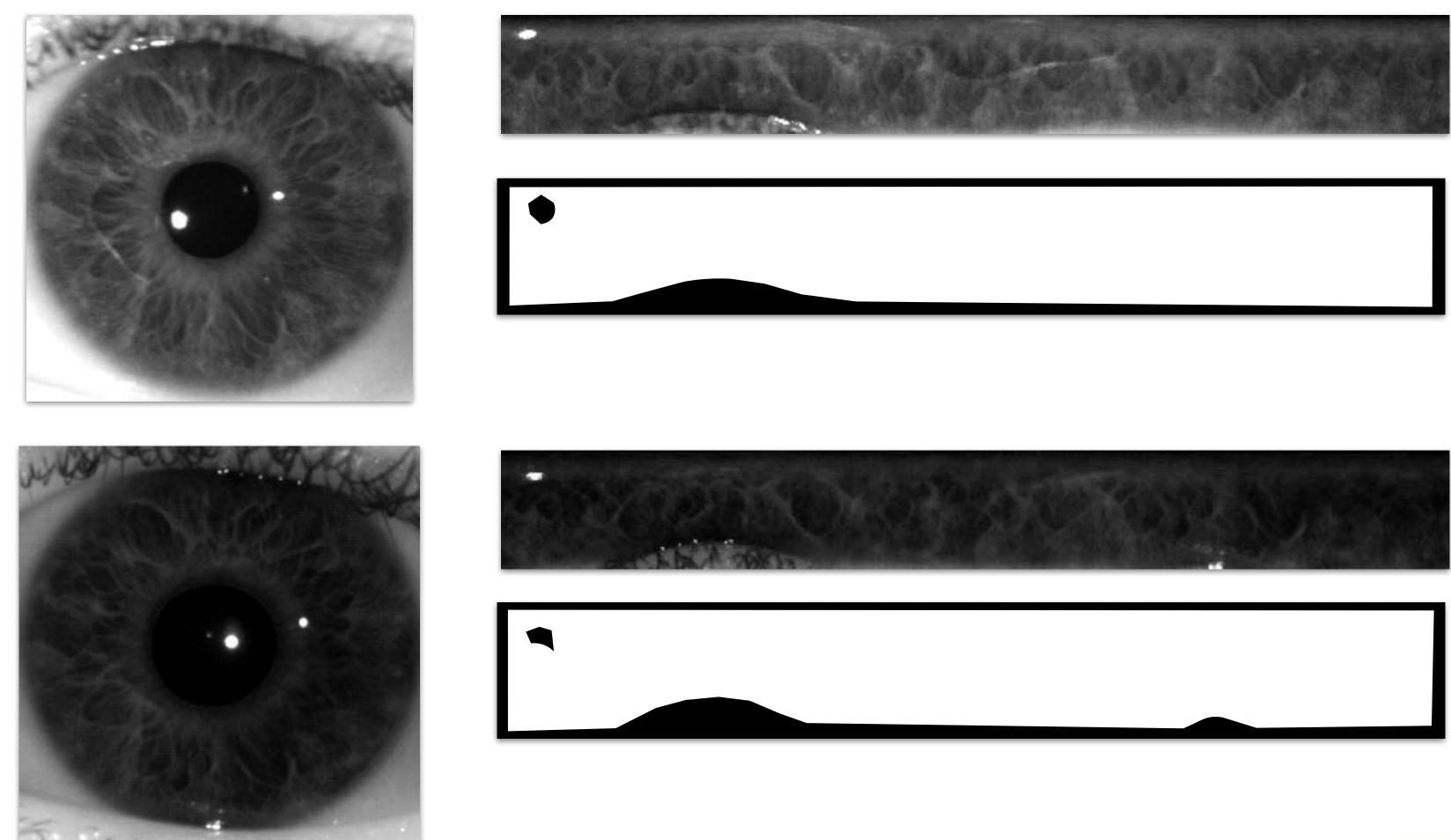


source



target







#### Limitations

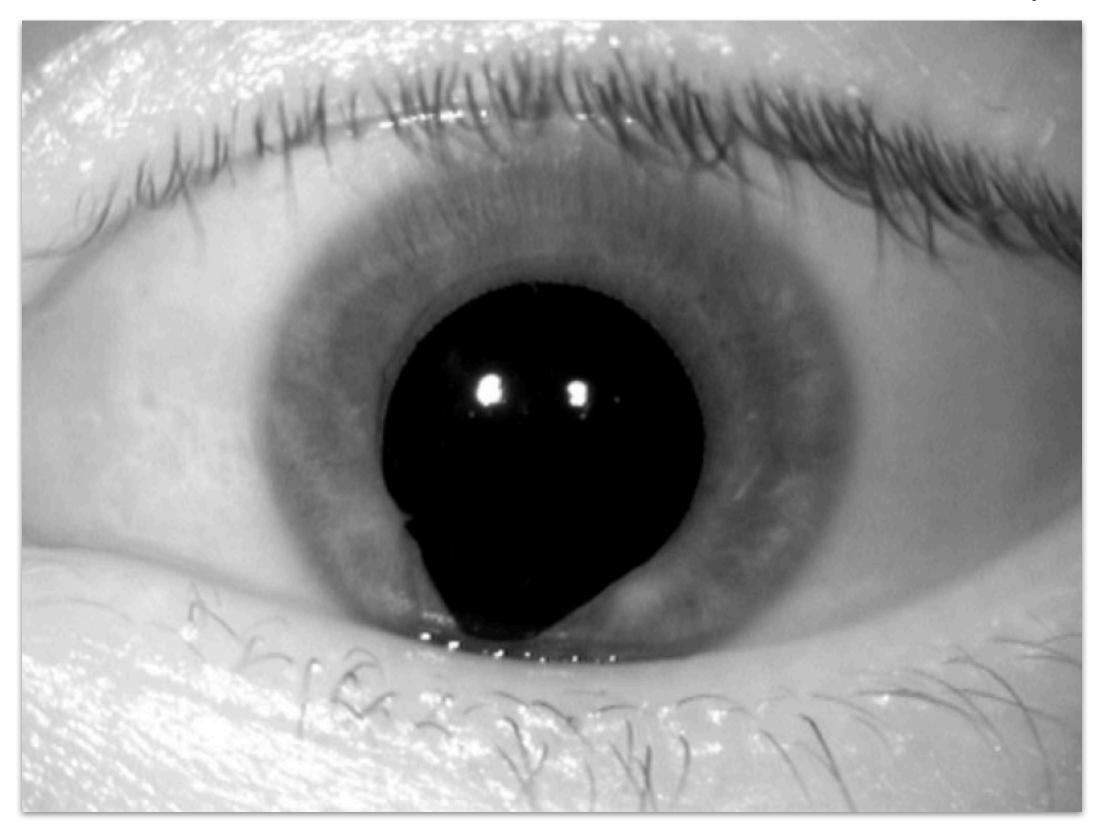
#### Segmentation

Pupil and iris are not concentric (pupils are slightly shifted to the nasal corner). They are not perfectly round.



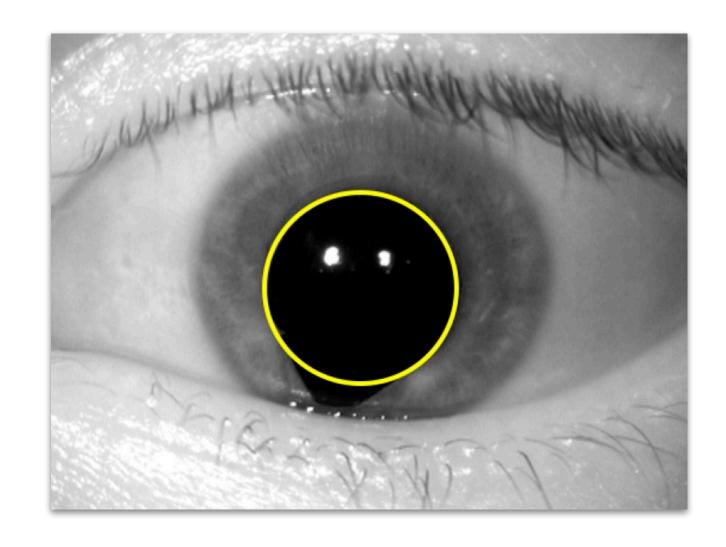


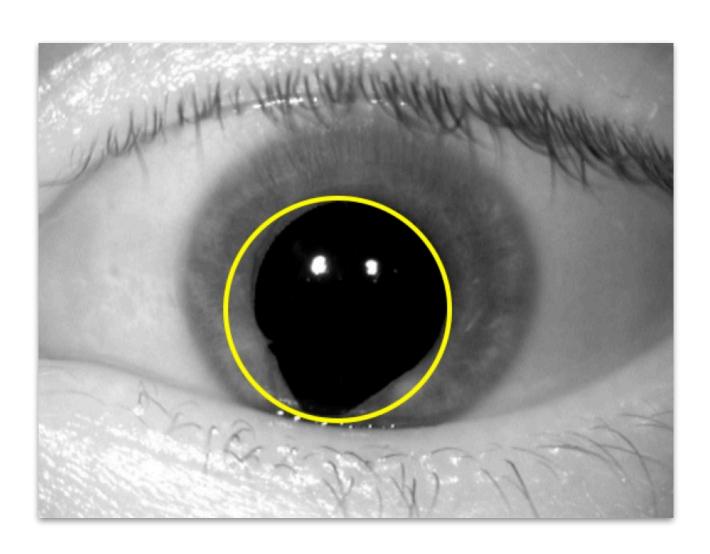
Dr. Adam Czajka



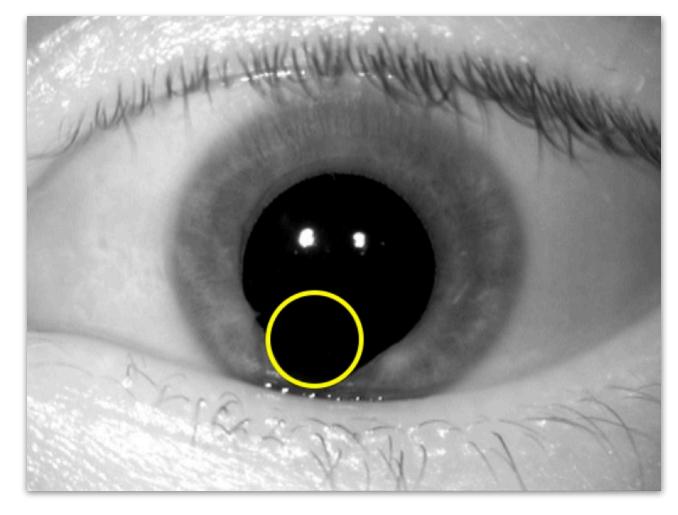
coloboma condition







Dr. Adam Czajka

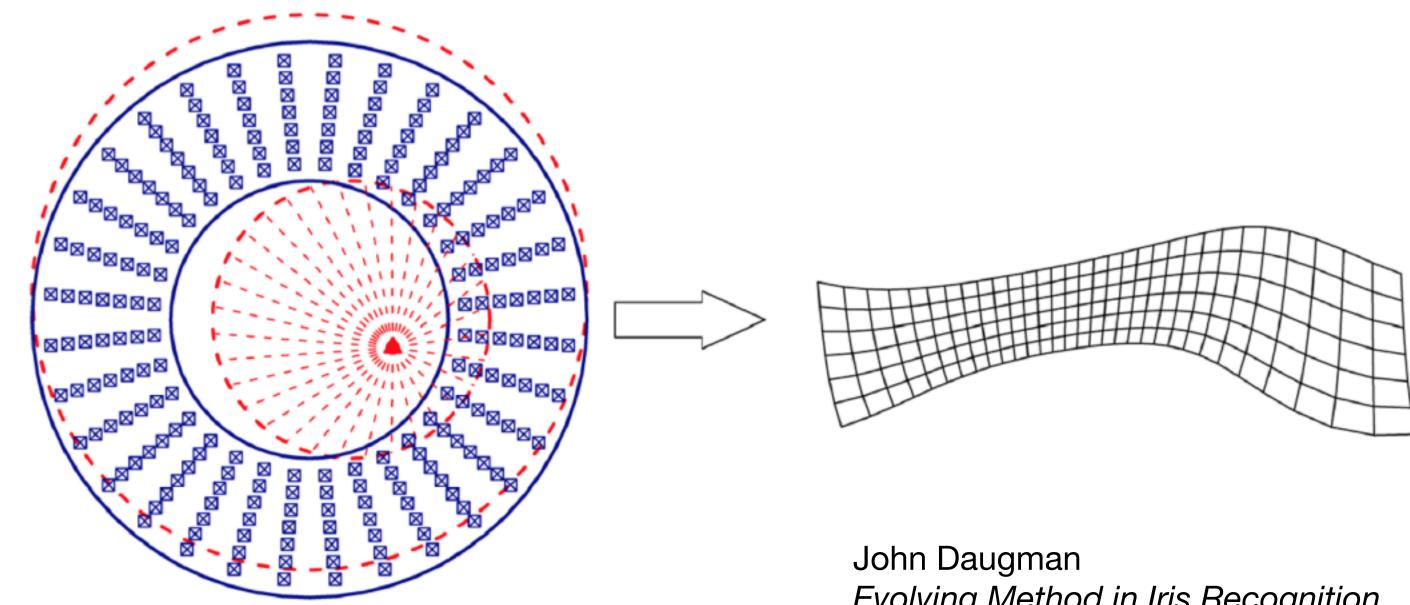




#### Limitations

#### Normalization

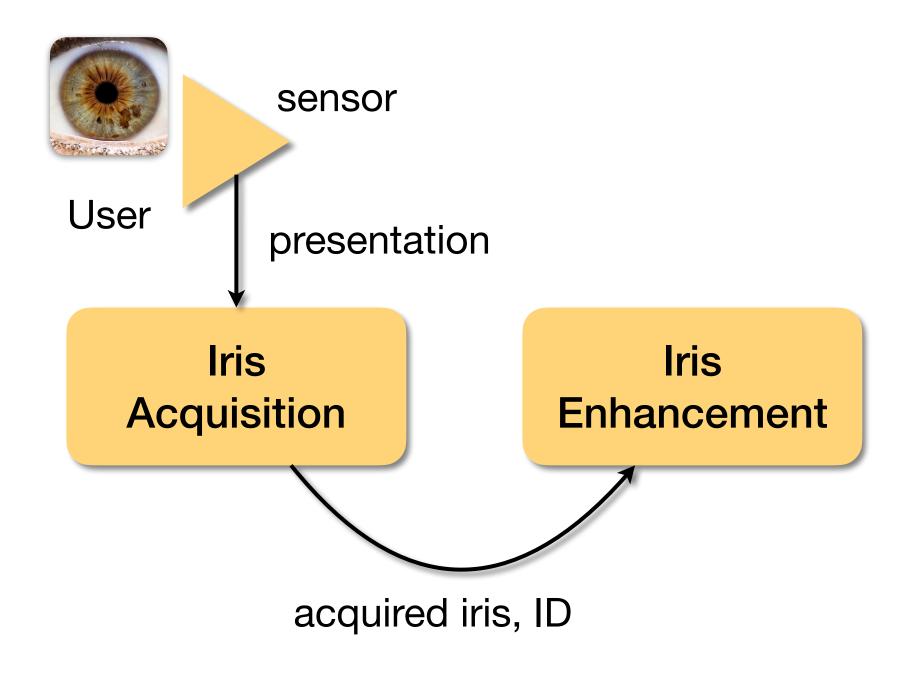
Forcing circular models may lead to poor mapping.



Evolving Method in Iris Recognition BTAS, 2012

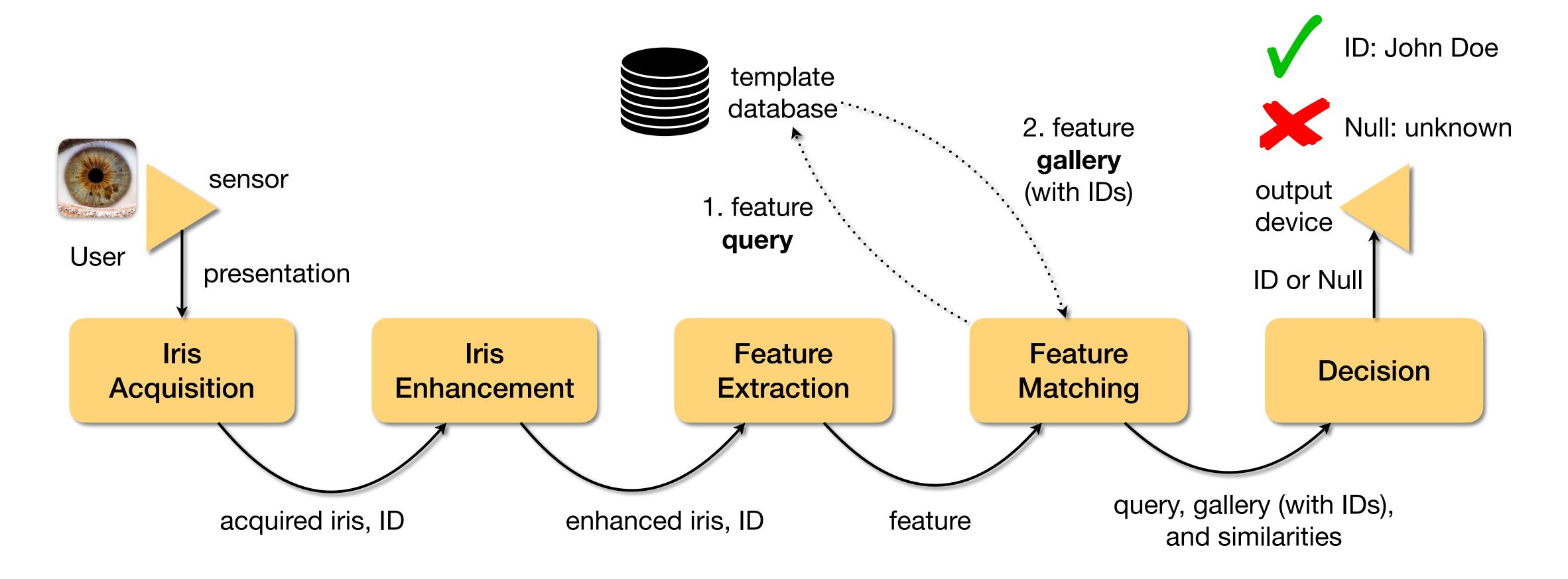


# Iris Recognition





# Iris Recognition





## S'up Next?

Iris Description and Matching



