COMP 388-002/488-002 Biometrics

Daniel Moreira Fall 2024



Today we will...

Get to know Iris acquisition and enhancement.



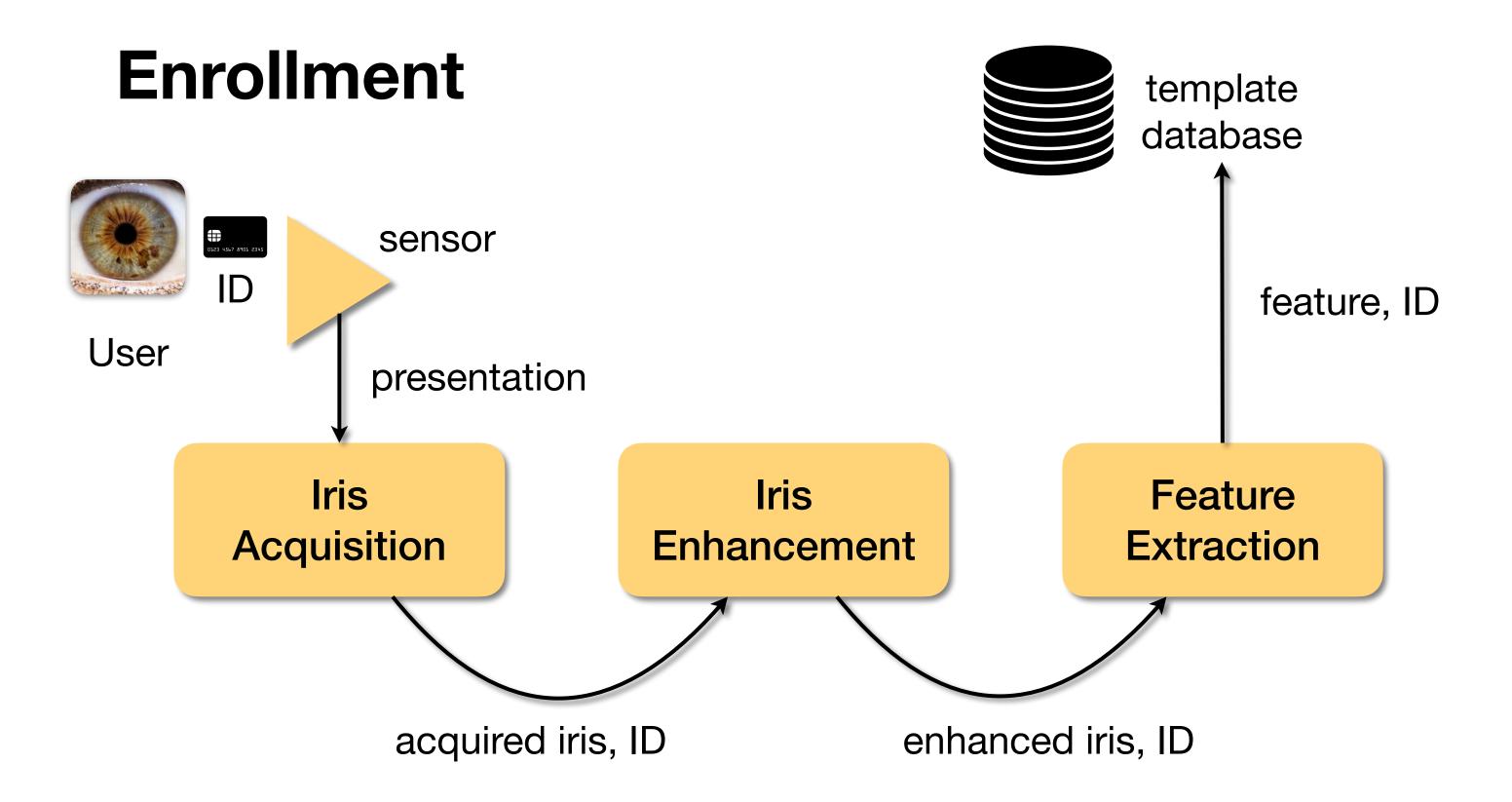
Today's Attendance

Please fill out the form

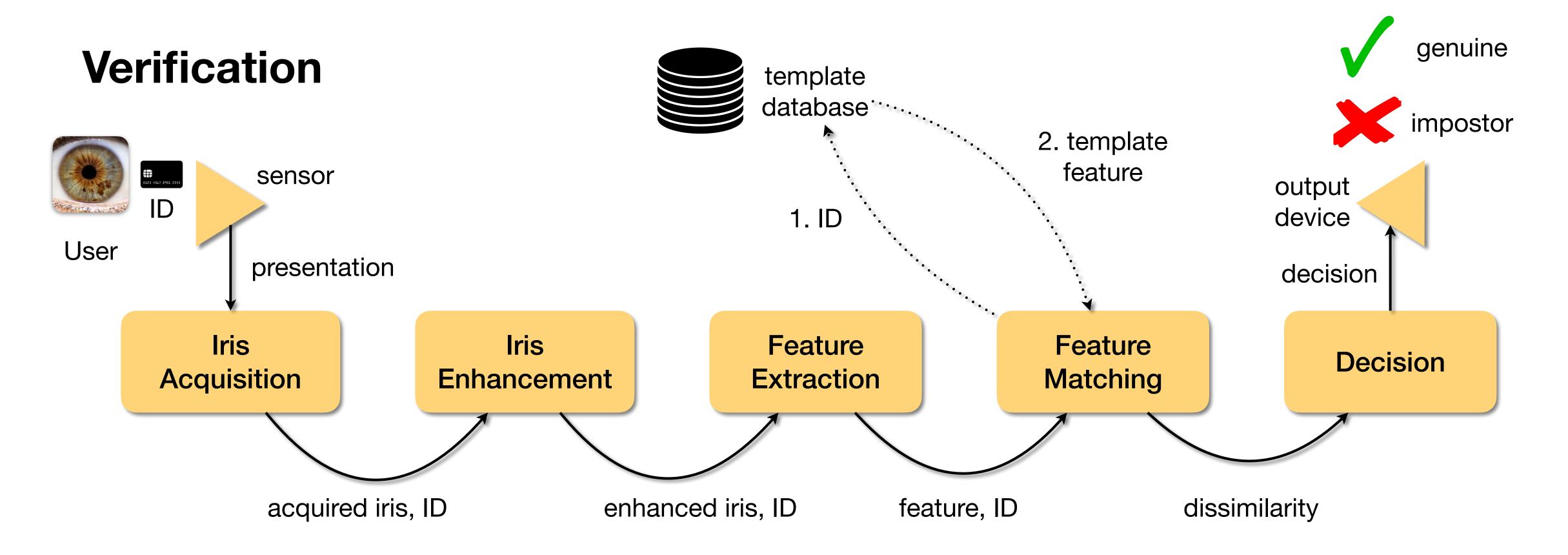
https://forms.gle/LwQxV9ZoKeVwwnWZ8



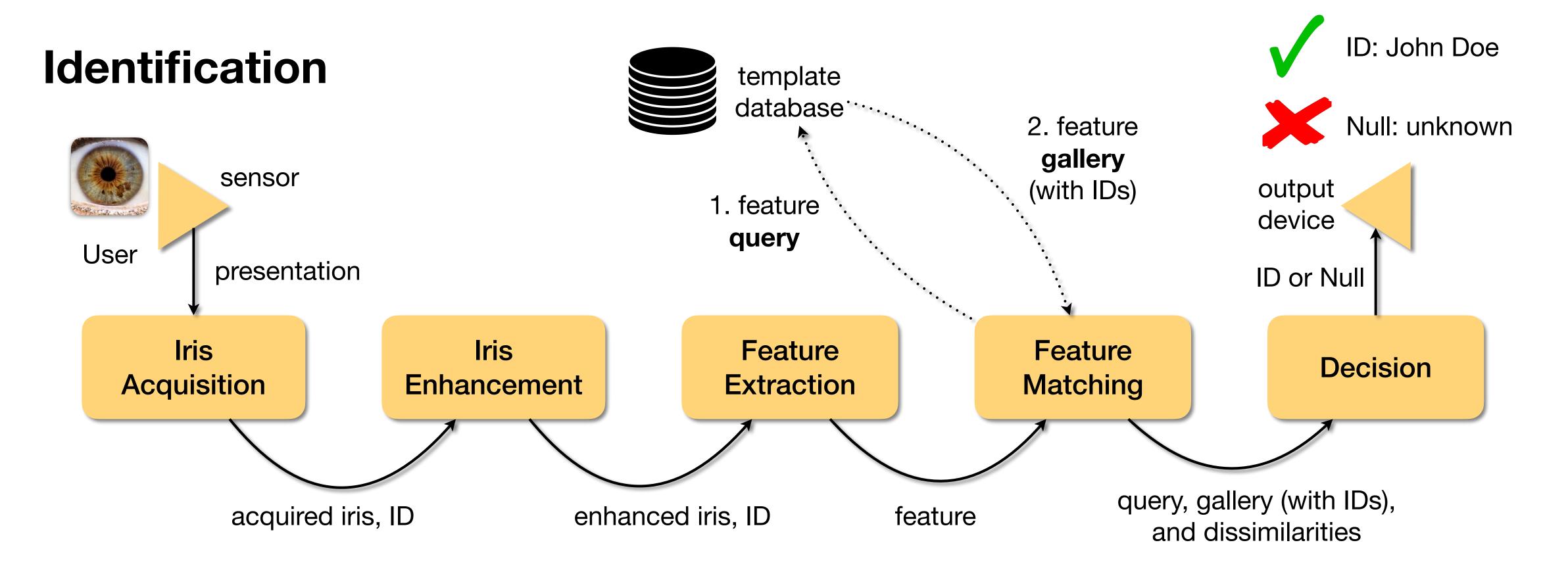




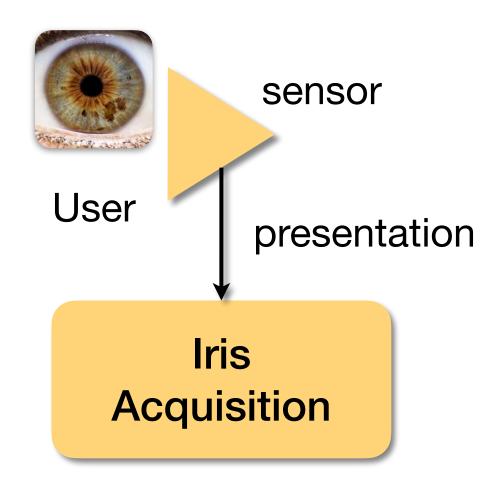






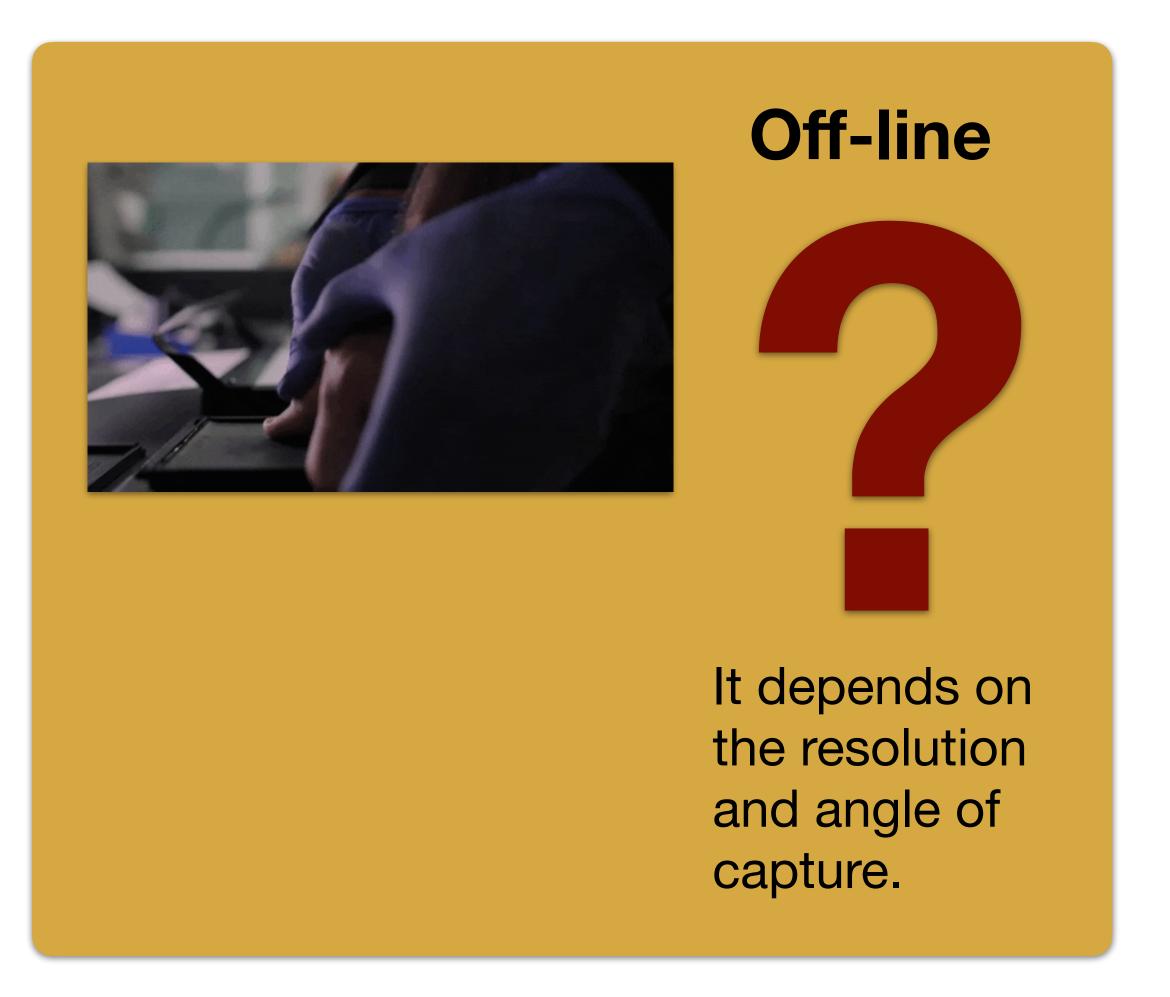








On-line Schiphol Airport

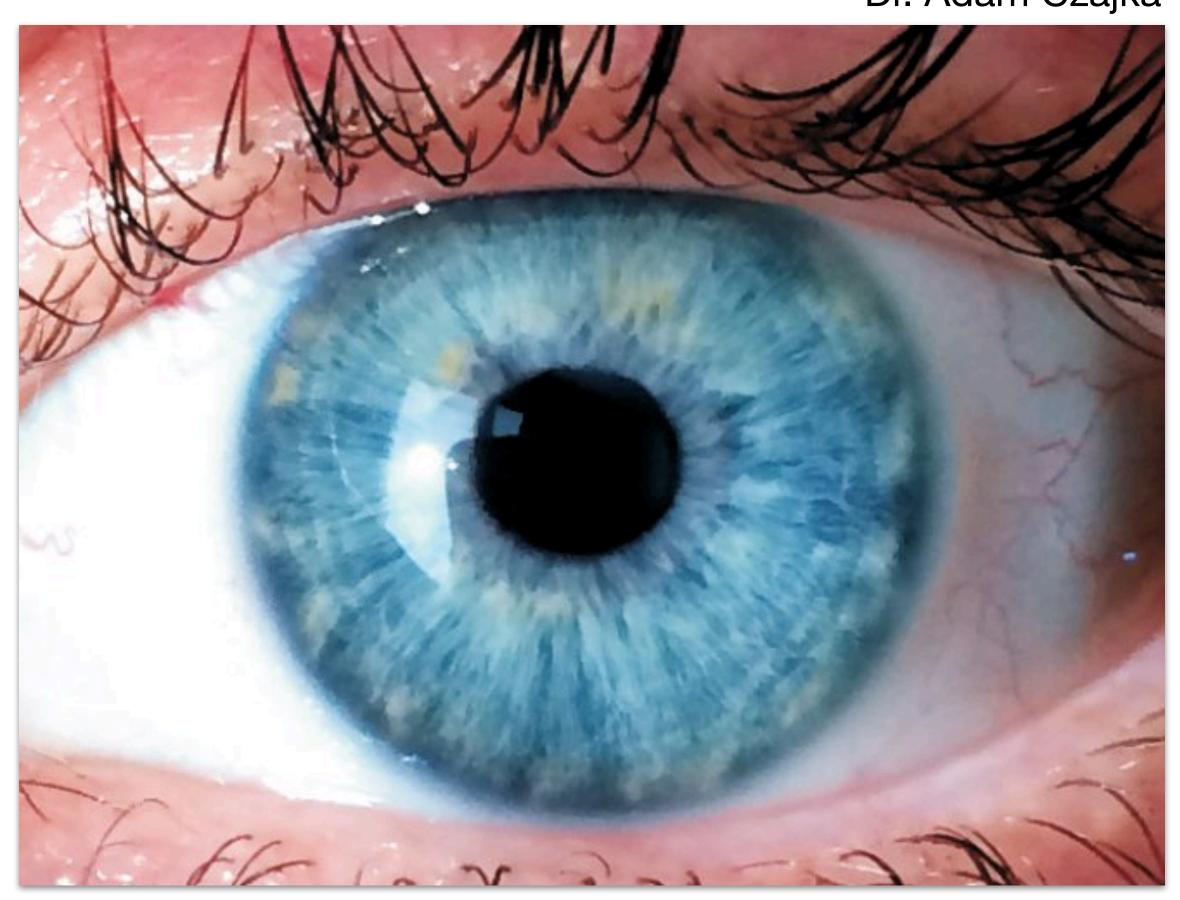




Dr. Adam Czajka

Iris Capture
Visible light.

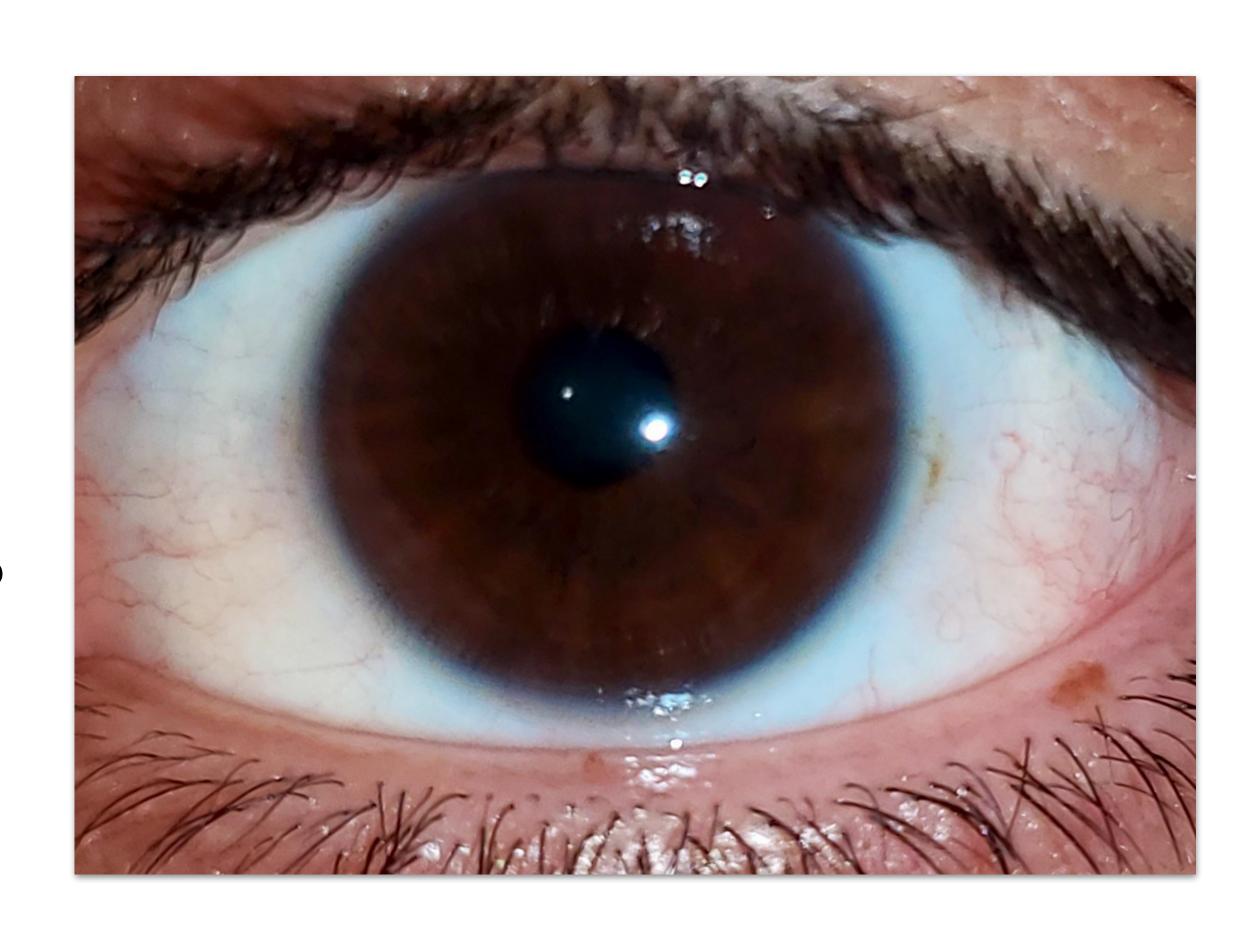
Can you see the iris texture (crypts, furrows, and collarette)?





Iris Capture
Visible light.

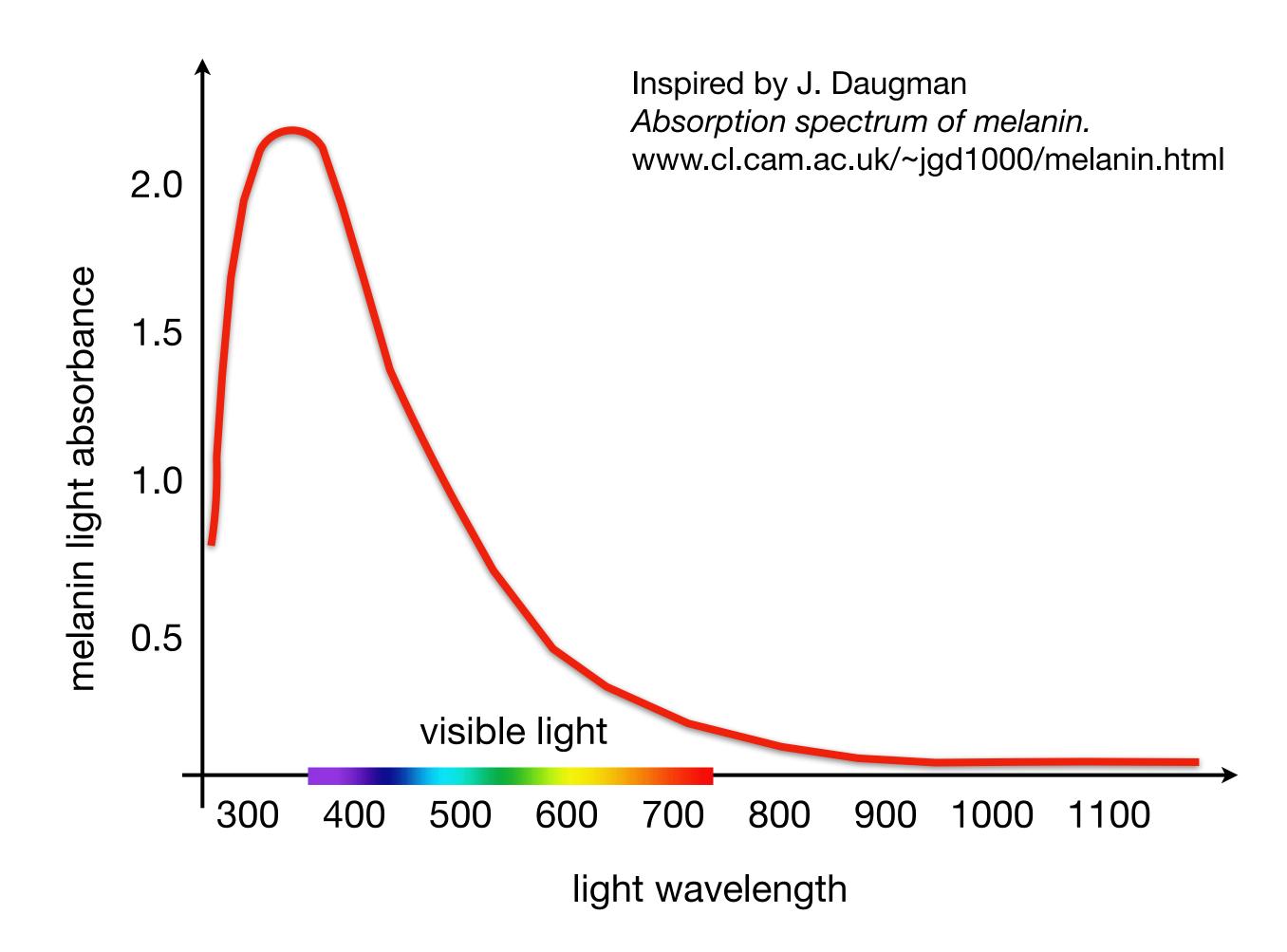
Can you see the iris texture (crypts, furrows, and collarette)?





Iris Capture
Visible light.

Melanin poses a challenge to visible-light iris recognition.

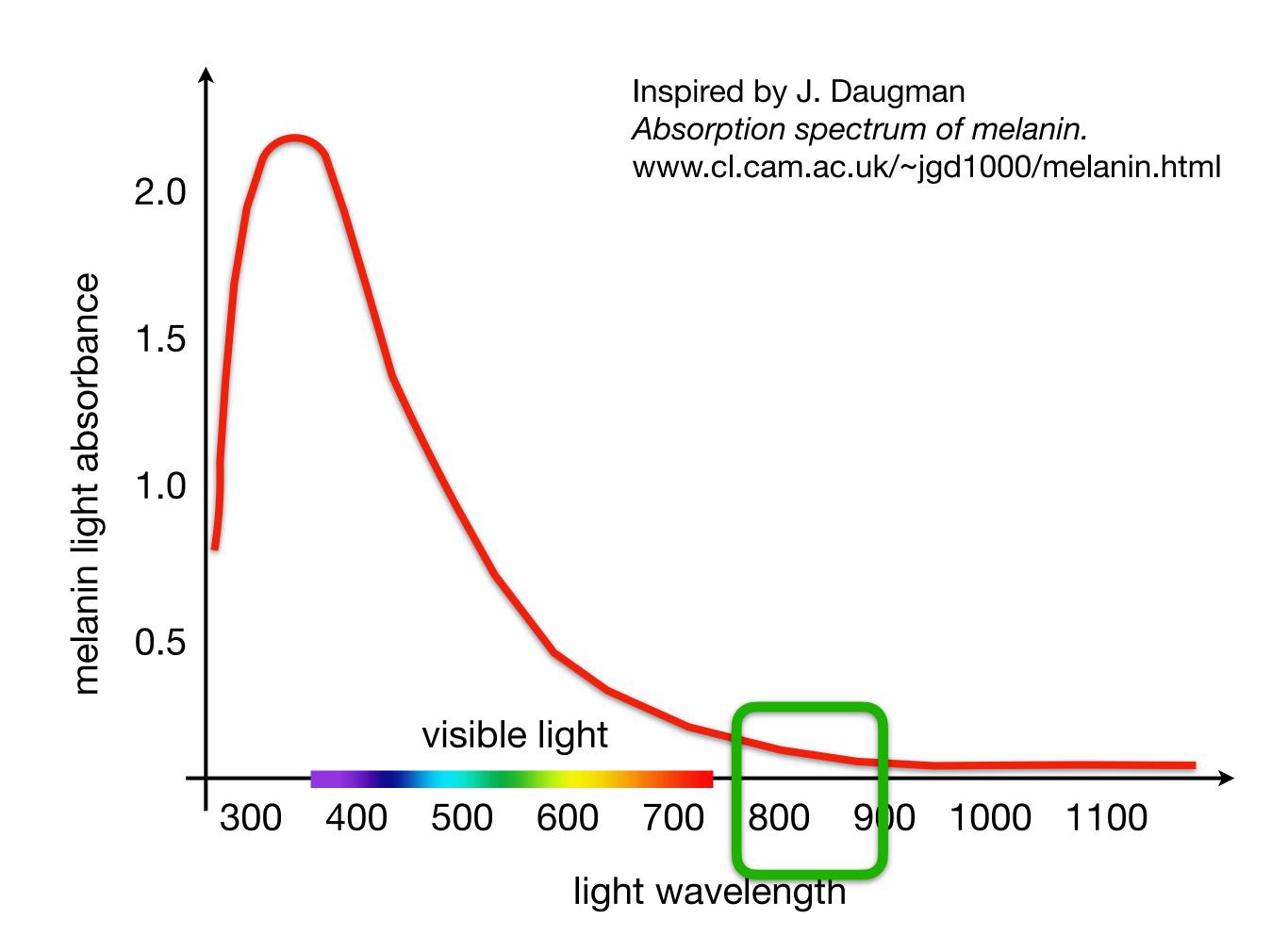




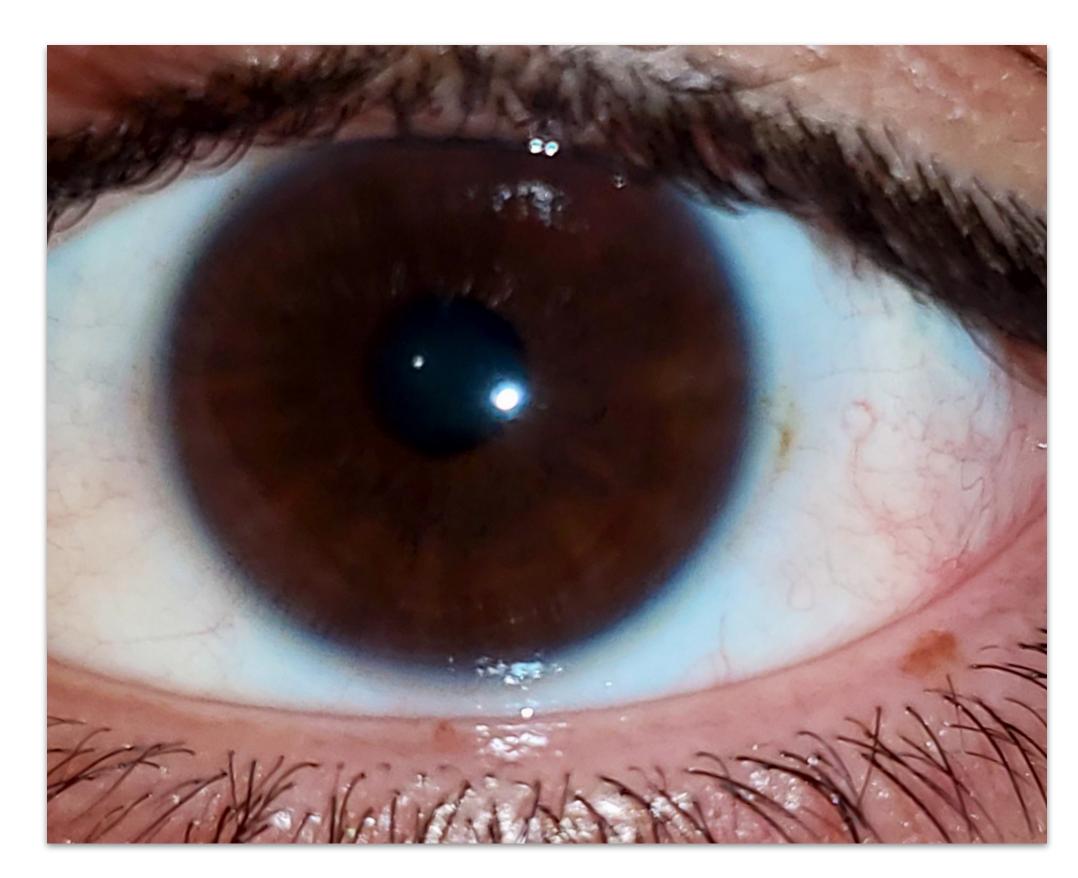
Iris Capture

Solution: near-infrared (NIR) light.

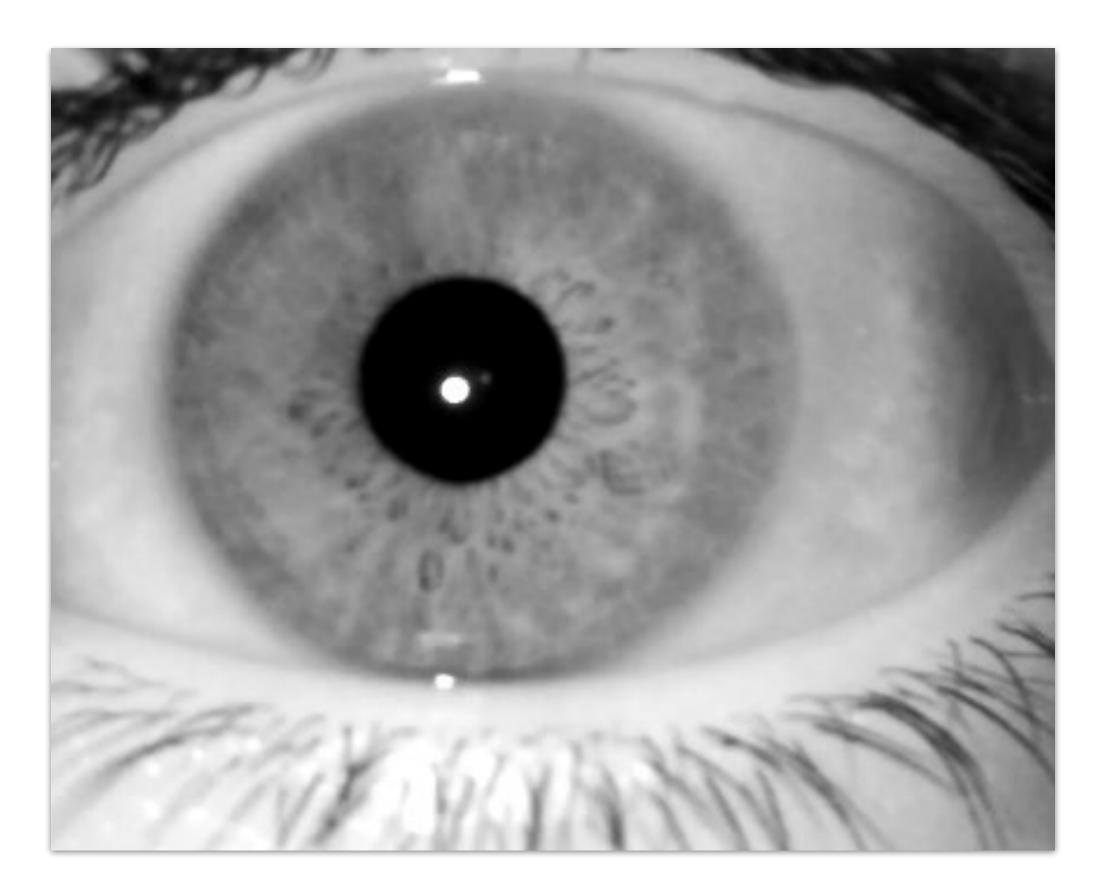
Typical wavelengths used by sensors: 750-890 nm.







visible light



NIR



Standards

Eye Safety

IEC 60825-1:1993

(+ addendum A1:1997 and A2:2001),

ANSI RP-27.1-96



 $MPE < 0.1 \times MPE_{max}$

eye damage due to light exposure





Standards

Image Quality
ISO/IEC 19794-6 and ISO/IEC 29794-6

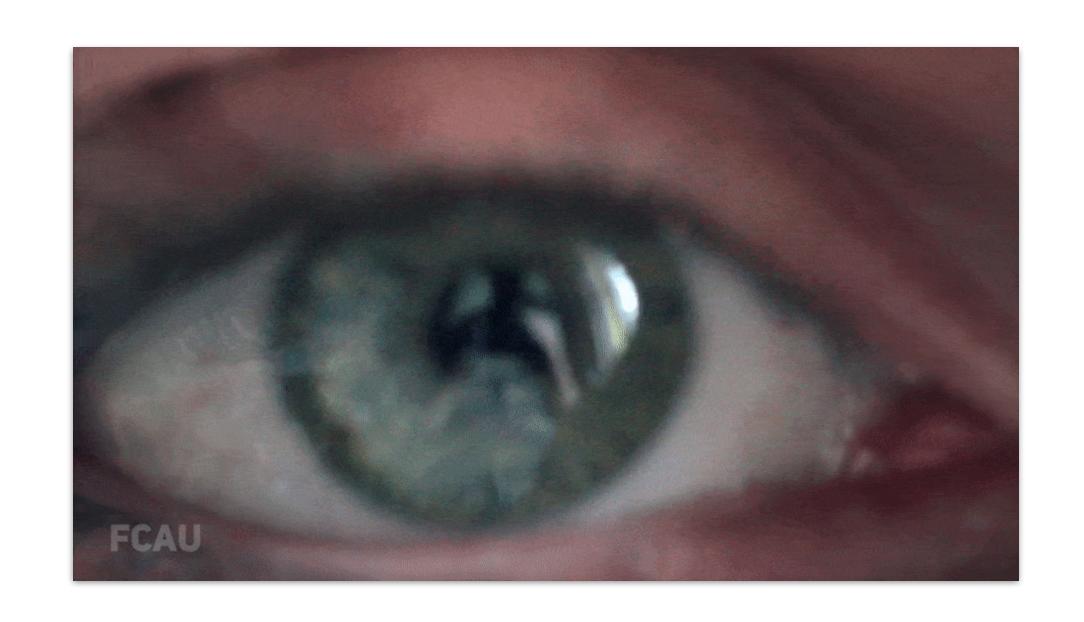
wavelength: 700-900 nm

resolution: ≥ 20 lines per iris diameter

non-occluded iris area: ≥ 70%

gray scale: ≥ 6 bits

typical resolution: 640 x 480 pixels





SensorsWith cooperation.

Jim Wilson / The New York Times



LG Iris Access 3000

Dr. Adam Czajka



CrossMatch

Dr. Adam Czajka



IG-AD100



Sensors

With almost no cooperation.

Multiple-Resolution Cameras

Wide-angle camera for face detection. Narrow-angle cameras for iris capture.

https://www.youtube.com/watch?v=bolNgCrCZW0



Sarnoff Corp., Iris-on-the-move Gate



Dr. Adam Czajka

Sensors

With almost no cooperation.

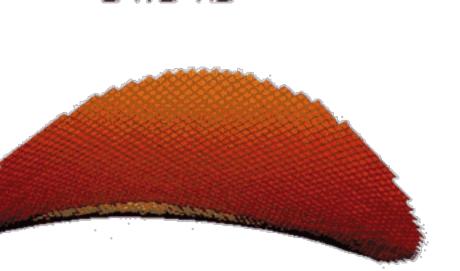
Deformable Mirrors

Similar to astronomical telescopes.

Fast adaptation at presentation time.

Capture at 1.5-2.5m

of distance.







AOptix Insight SD, 2008



Sensors

Current trend: miniaturization.

Example 1

Android-based *Fidelys* smartwatch.



linuxgizmos.com/ worlds-first-iris-recognition-smartwatch-runs-android



Sensors

Current trend: miniaturization.

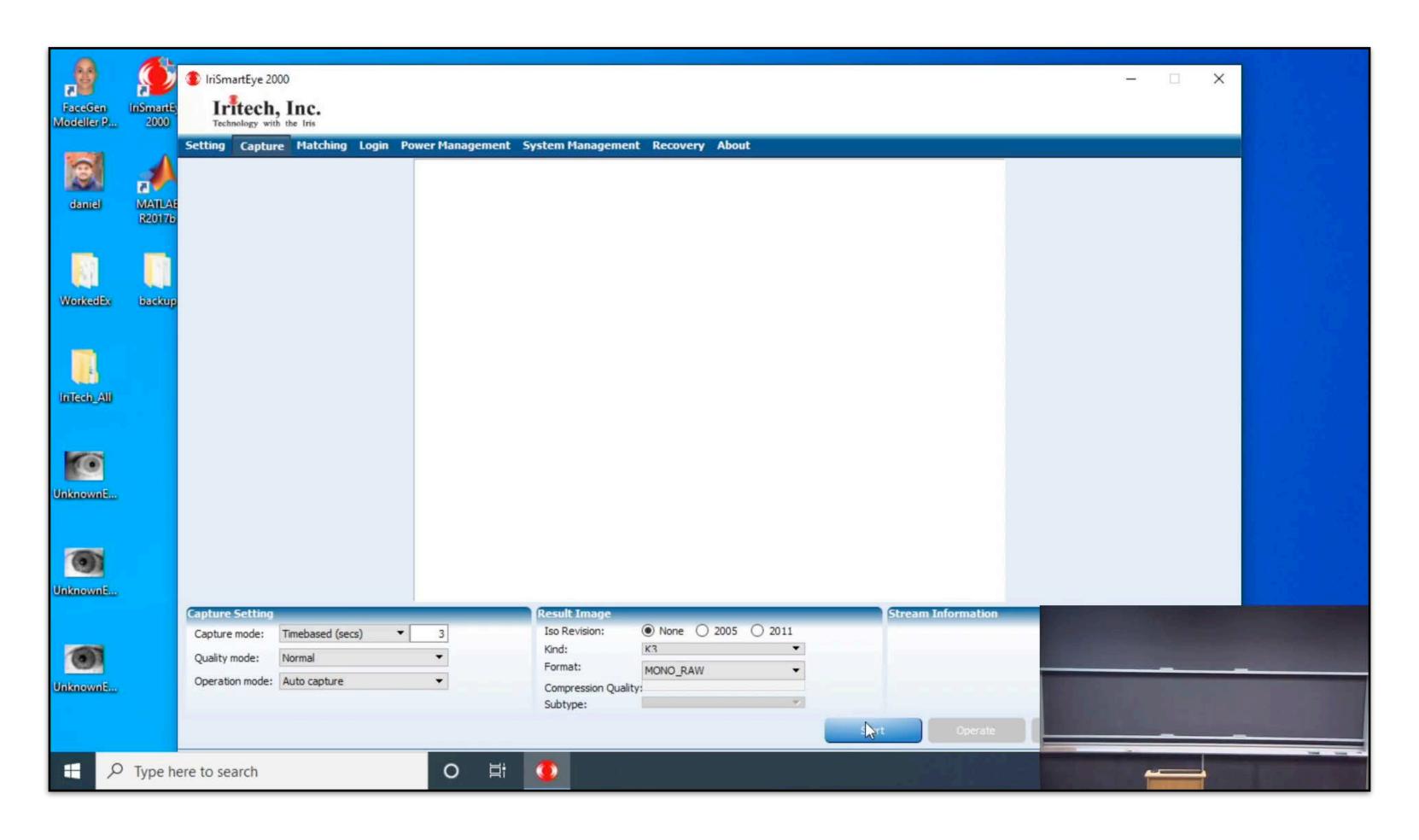
Example 2 IriShield USB

This is the one we'll use to collect data.



https://urvashicomputers.com/irishield-mk-2120-series/







Challenges

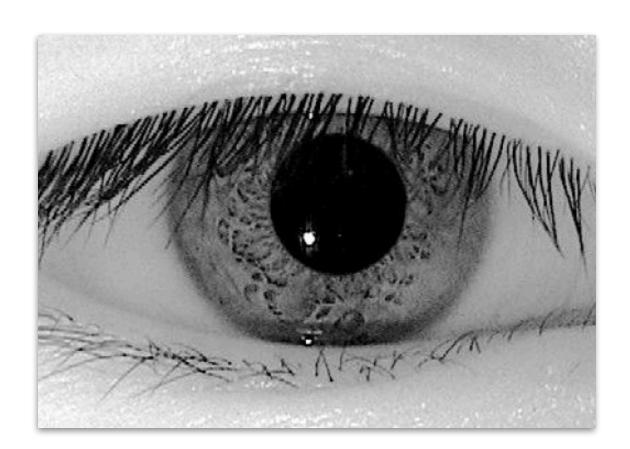
Deformations and Occlusions

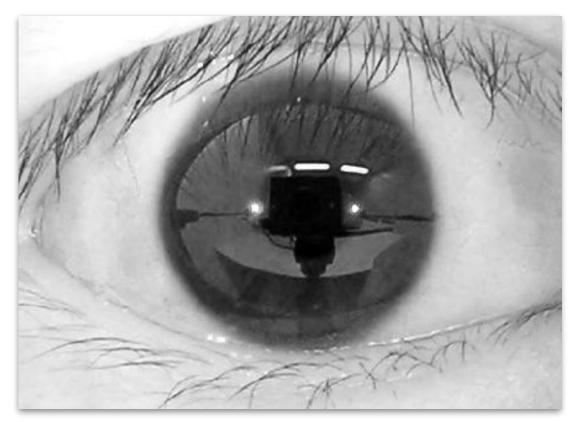
Eyelids and eyelashes.

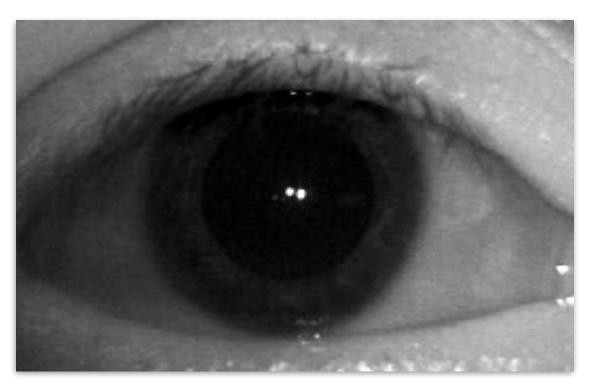
Specular reflections.

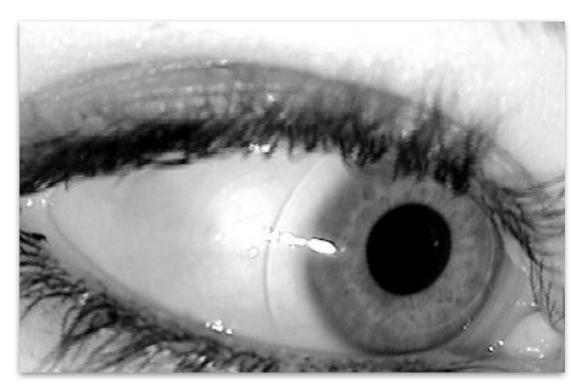
Pupil dilation.

Head movement, off-axis gaze.









http://www.cse.nd.edu/BTAS_07/John_Daugman_BTAS.pdf



Challenges

User Cooperation
It is easy for people to protect their irises from capture.





Challenges

Diseases

E.g., cataracts, conjunctivitis. Is iris visible? Is the disease contagious?

commons.wikimedia.org



E.g., cataracts.



Challenges

Attacks

Obfuscation with texturized contact lenses.

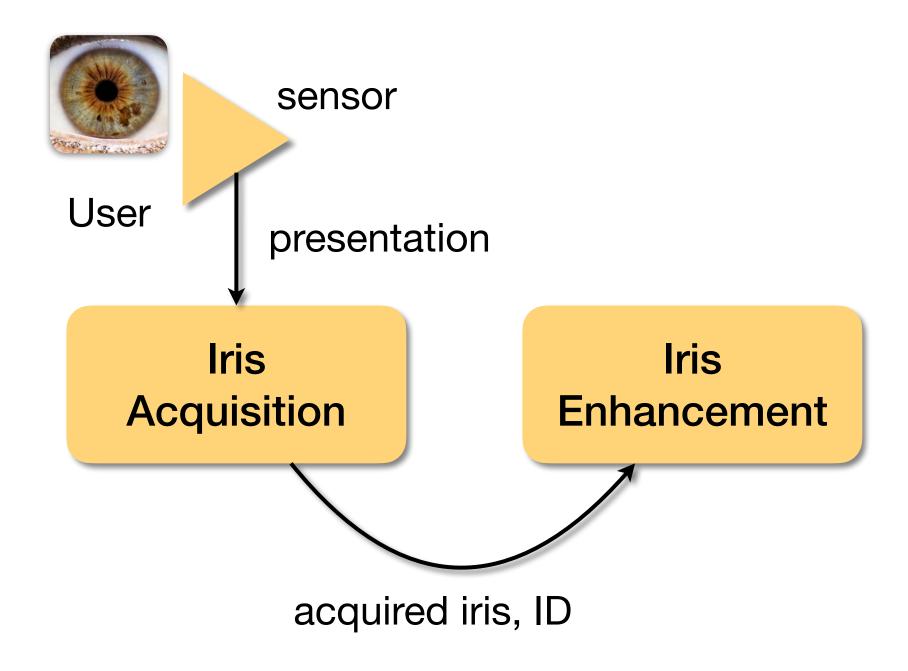
Presentation attack.





Jain, Ross, and Nadakumar Introduction to Biometrics Springer Books, 2011







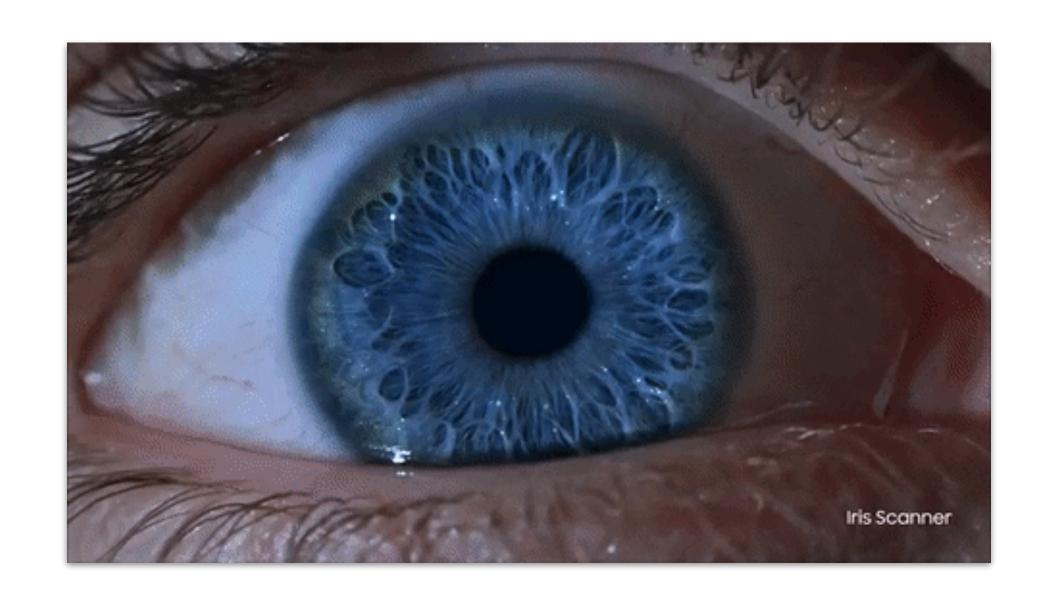
Steps

Segmentation

Keep only useful information (iris texture).

Normalization

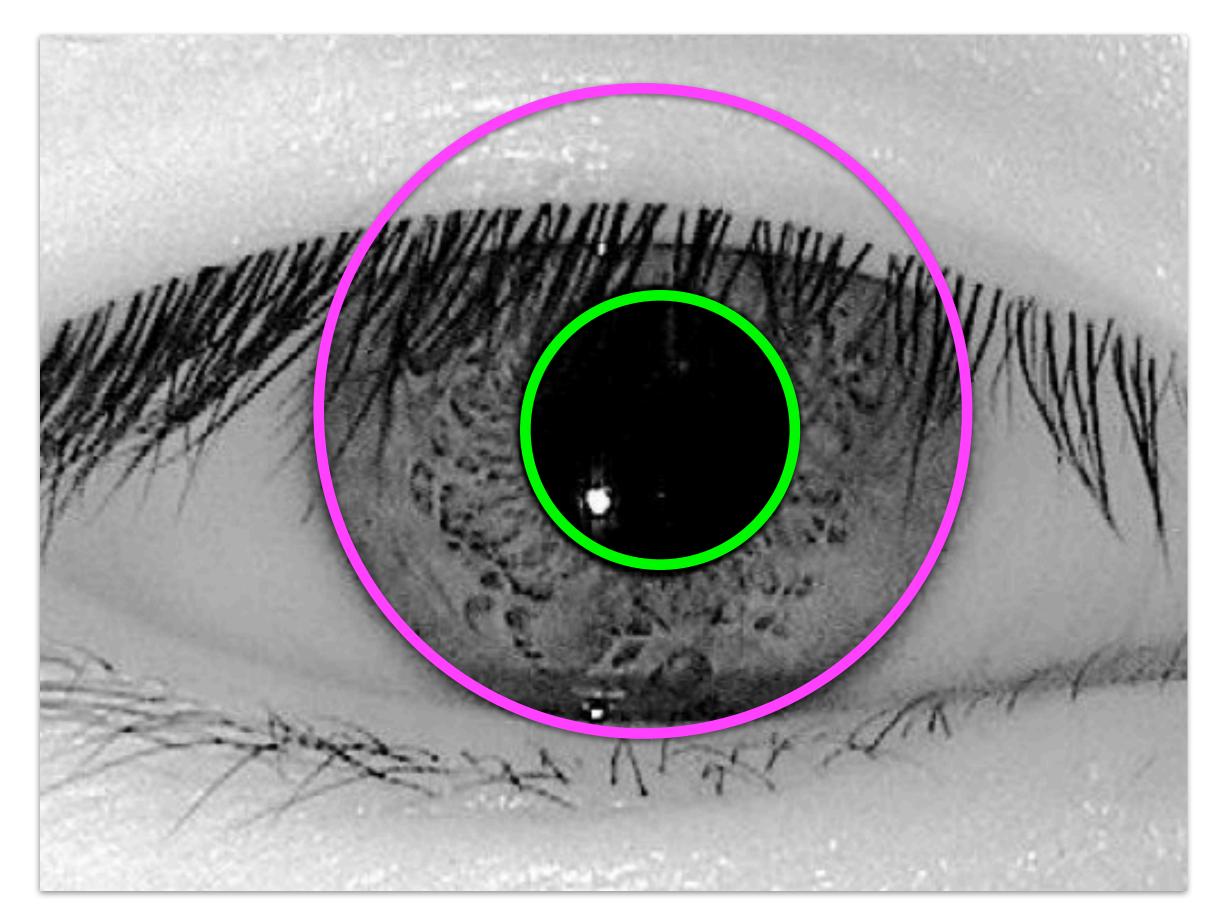
Make different captures of the same iris look as similar as possible.





Segmentation (1/2)

Iris and Pupil Localization Localize limbus and pupillary boundaries.



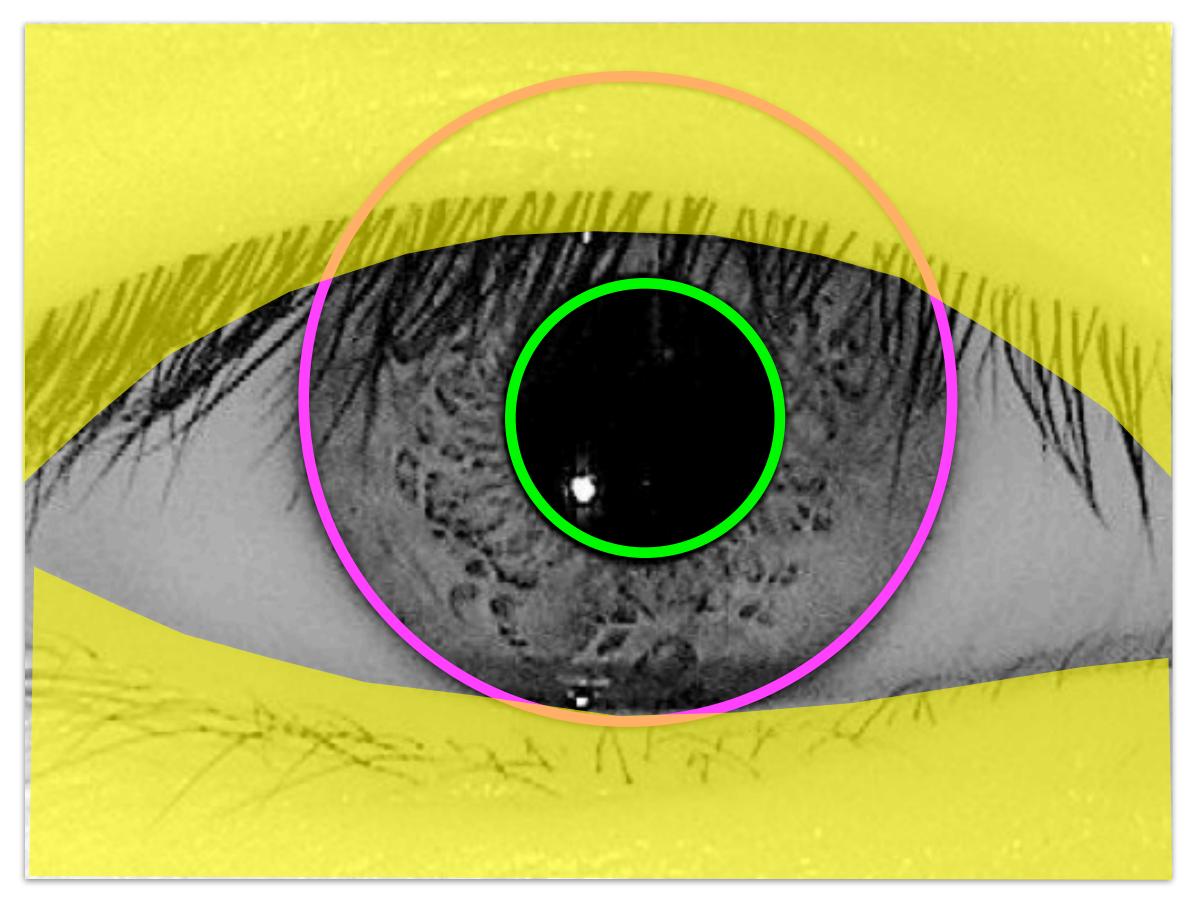
http://www.cse.nd.edu/BTAS_07/John_Daugman_BTAS.pdf



Segmentation (1/2)

Iris and Pupil Localization Localize limbus and pupillary boundaries.

Eyelid, Eyelash, and
Specular Reflection Detection
Deal with iris texture occlusions.



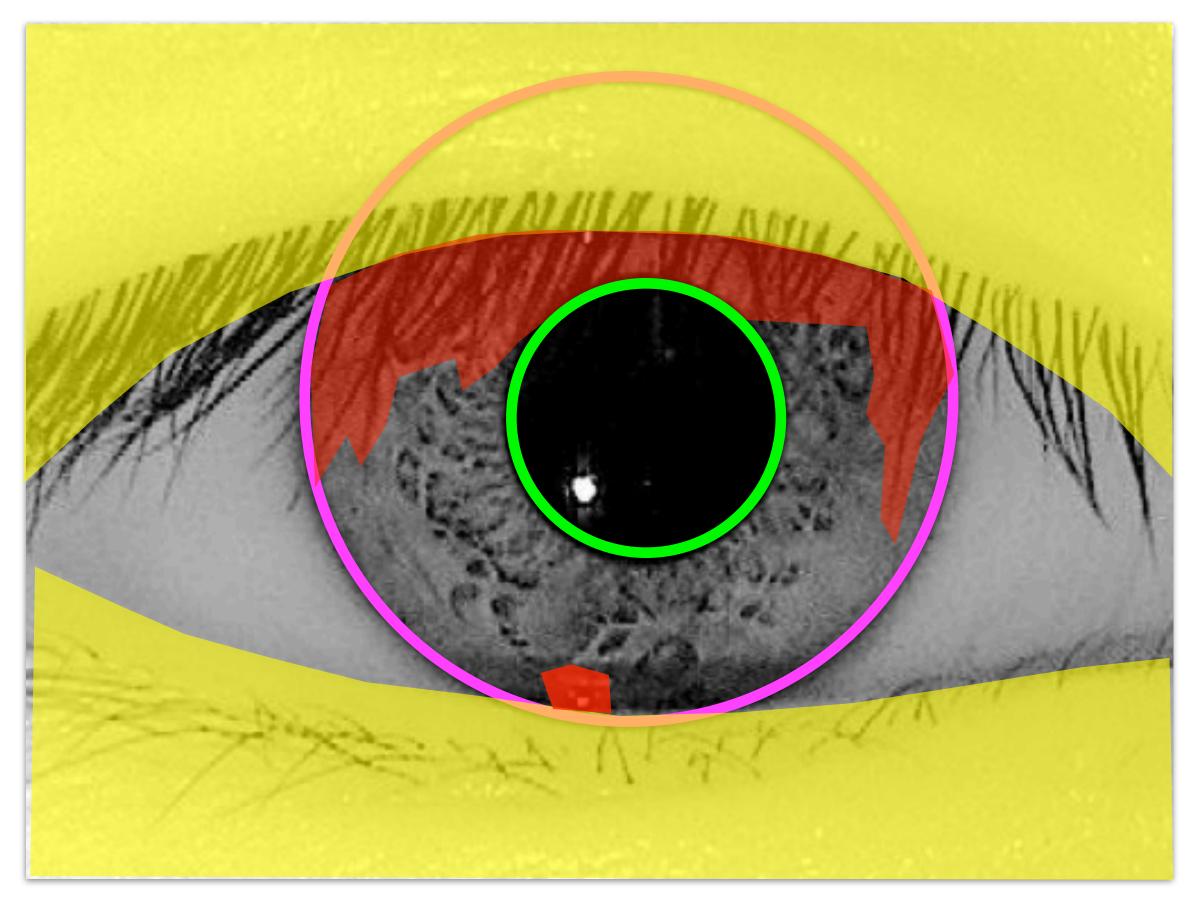
http://www.cse.nd.edu/BTAS_07/John_Daugman_BTAS.pdf



Segmentation (1/2)

Iris and Pupil Localization Localize limbus and pupillary boundaries.

Eyelid, Eyelash, and
Specular Reflection Detection
Deal with iris texture occlusions.



http://www.cse.nd.edu/BTAS_07/John_Daugman_BTAS.pdf

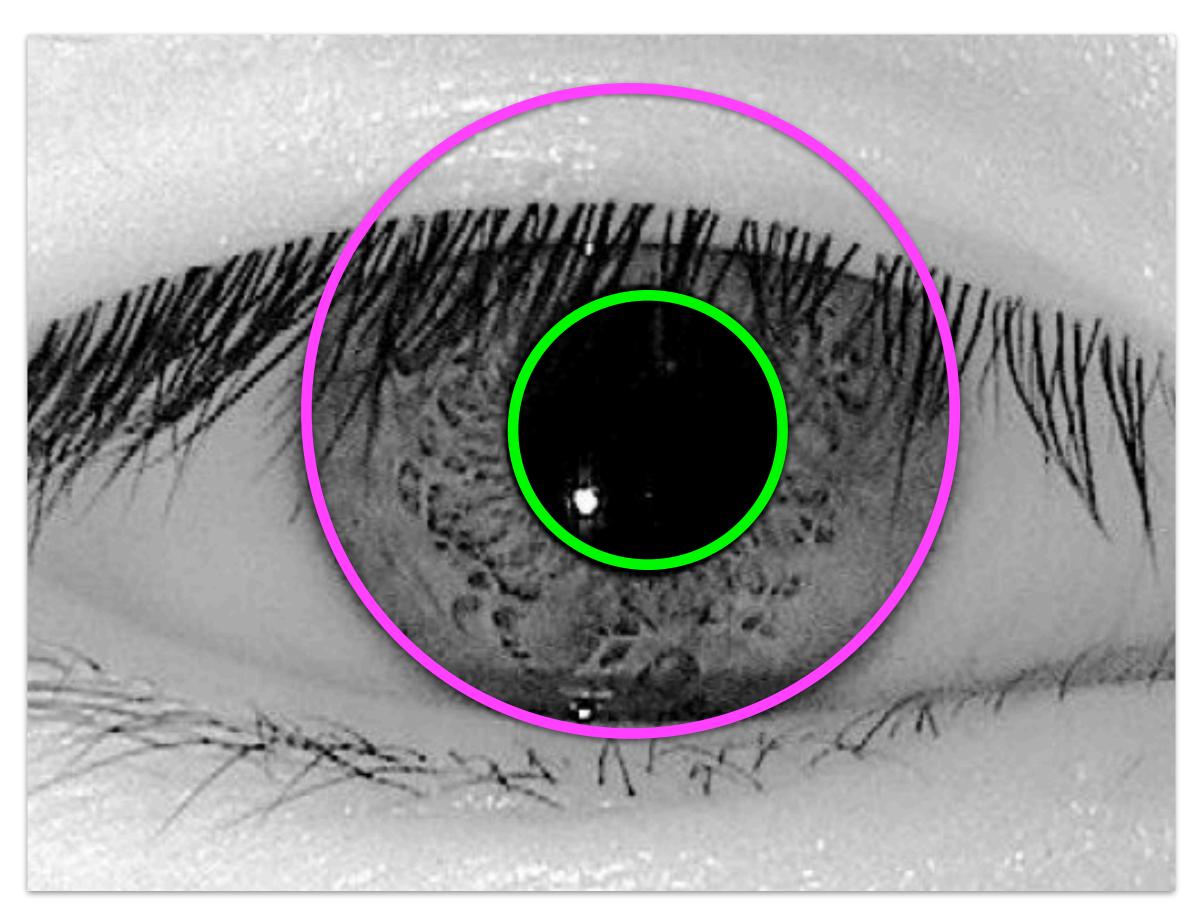


Segmentation (1/2)

Iris and Pupil Localization
Method 1: Integral-differential
operator

Objective:

Find (r, x_0, y_0) of **limbus** and (r, x_0, y_0) of **pupillary** boundaries.



http://www.cse.nd.edu/BTAS_07/John_Daugman_BTAS.pdf



Segmentation (1/2)

Iris and Pupil Localization

Method 1: Integral-differential operator

Strategy:

Try various values for (r, x_0, y_0) .

3. derivative of integral

2. integral of circle with radius r

1. pixel values

$$\max_{r,x_0,y_0} \left| g_{\sigma}(r) * \frac{\delta}{\delta r} \oint_{r,x_0,y_0} \frac{I(x,y)}{2\pi r} ds \right|$$

5. get the (r, x_0, y_0) configuration with maximum values

4. smoothing function (gaussian)



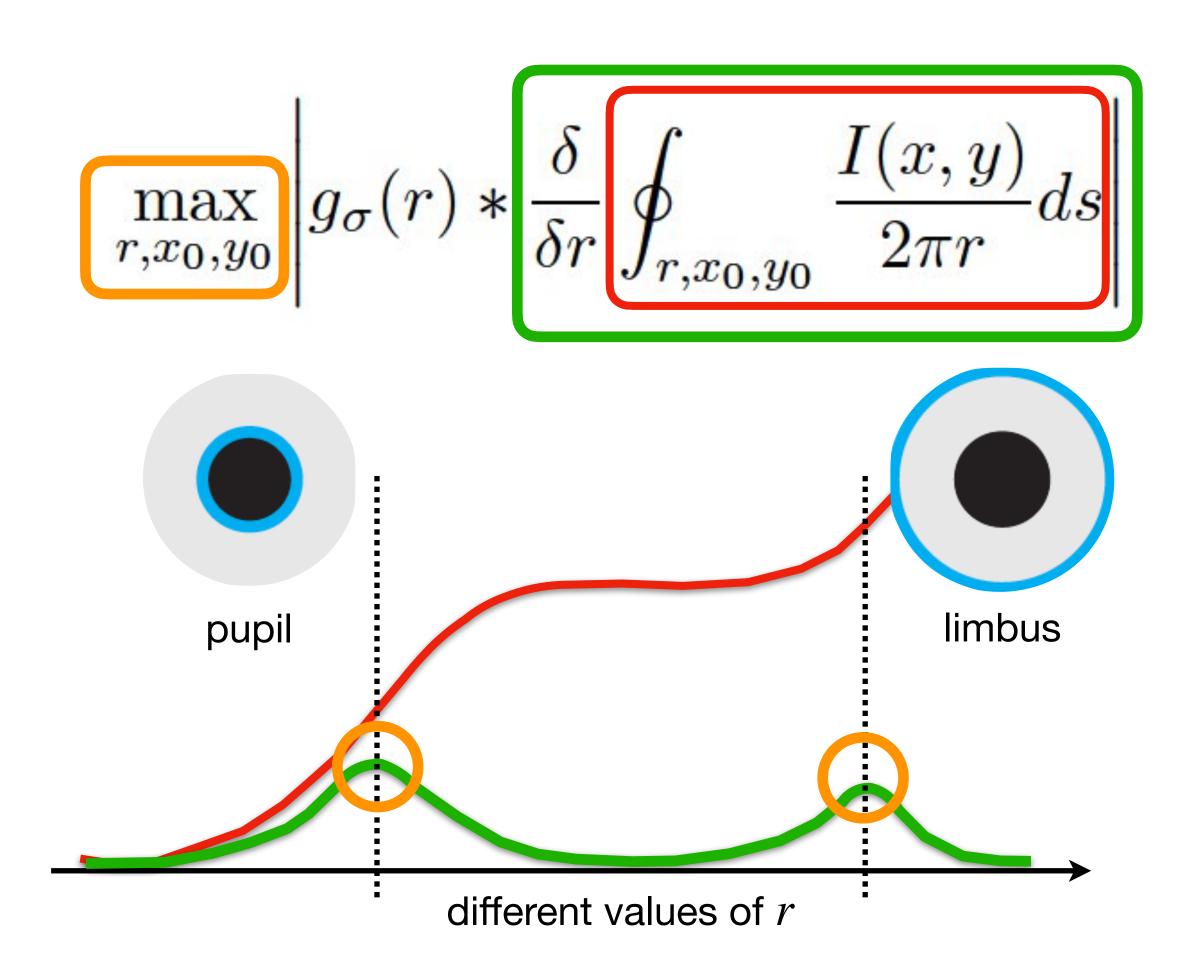
Segmentation (1/2)

Iris and Pupil Localization

Method 1: Integral-differential operator

Strategy:

Try various values for (r, x_0, y_0) .



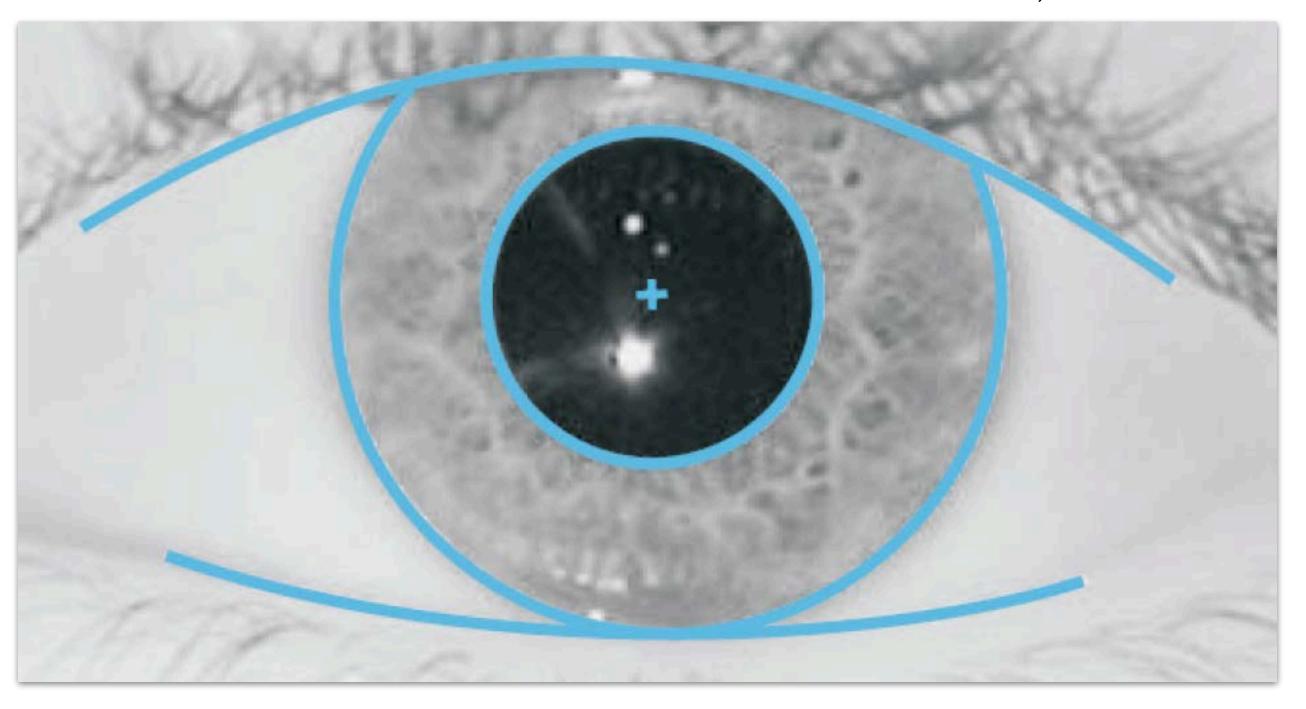


Segmentation (1/2)

Iris and Pupil Localization Method 1: Integral-differential operator

J. Daugman

How Iris Recognition Works
IEEE TCSVT, 2004

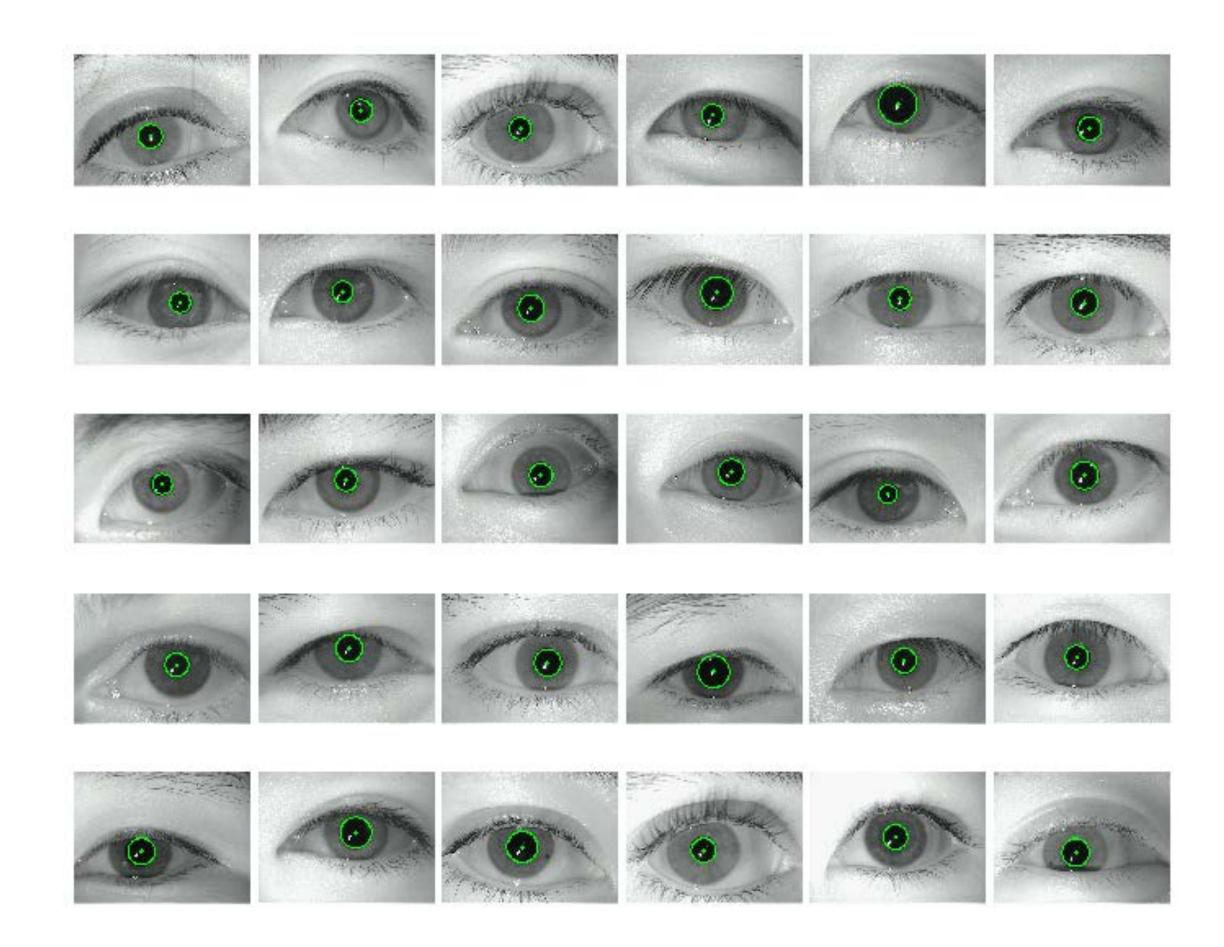


result example



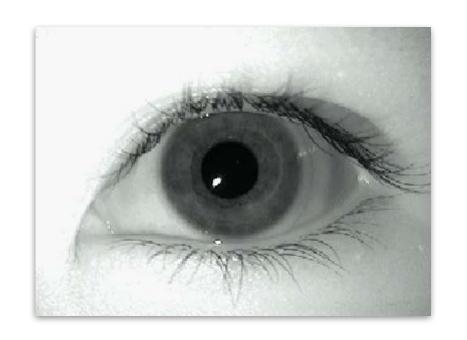
Segmentation (1/2)

Iris and Pupil Localization
Method 2: Image processing
ending with Hough circle
transform.

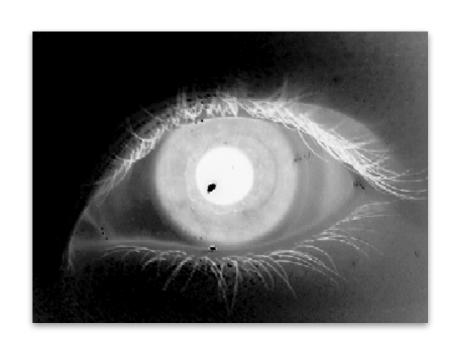


https://github.com/olesiamidiana/iris-recognition-py

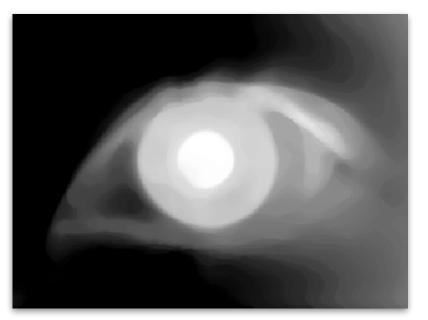




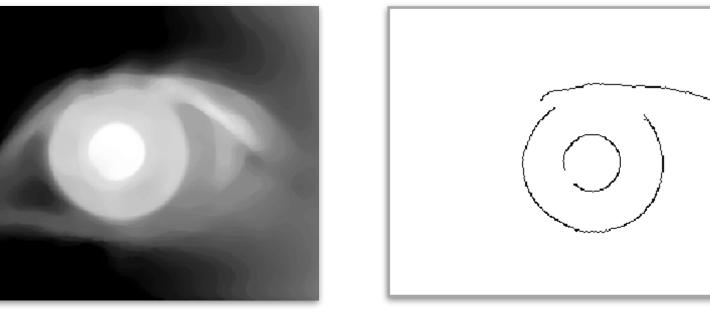
1.grayscale



2. inverted

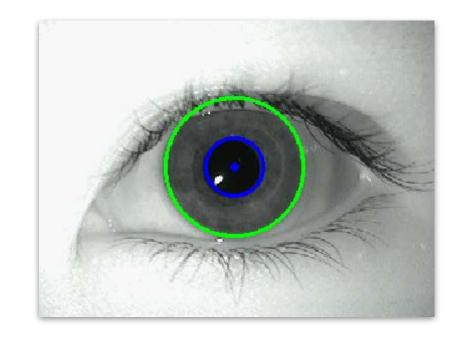


3. median blur



4. Canny edge detector

https://github.com/olesiamidiana/iris-recognition-py



5. Hough circle transform



Segmentation (1/2)

Eyelids, eyelashes, specular highlights

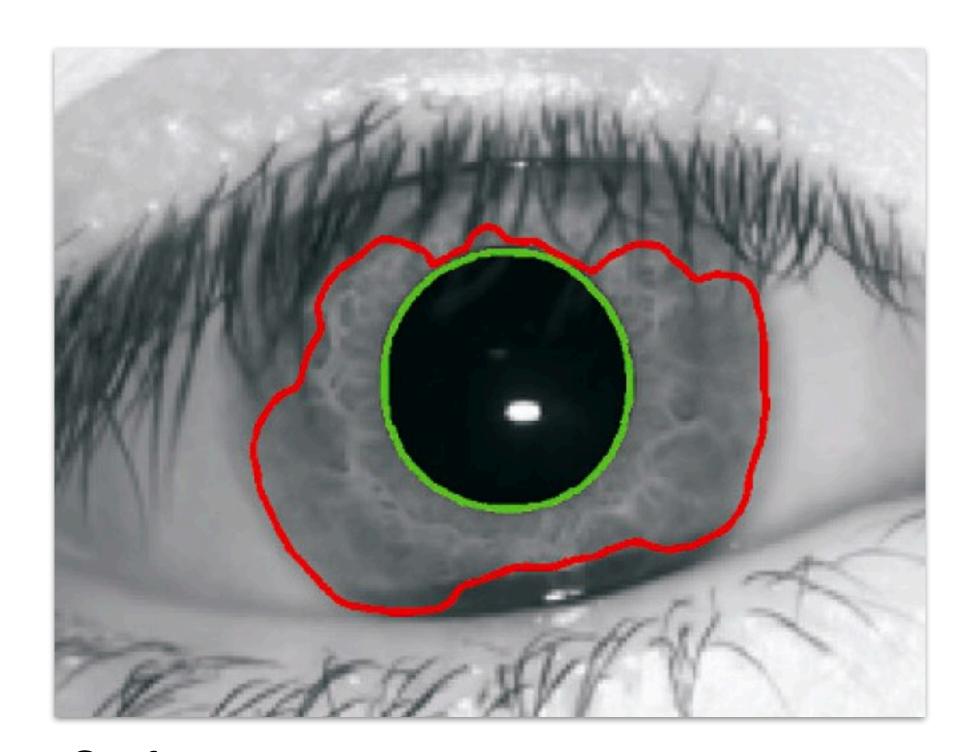
Fit of parabolic curves for eyelids.

Active contours (curve evolution)

to avoid eyelashes.

Fit of elliptical curves for specular highlights.

Machine learning from annotated examples.



Gutfeter

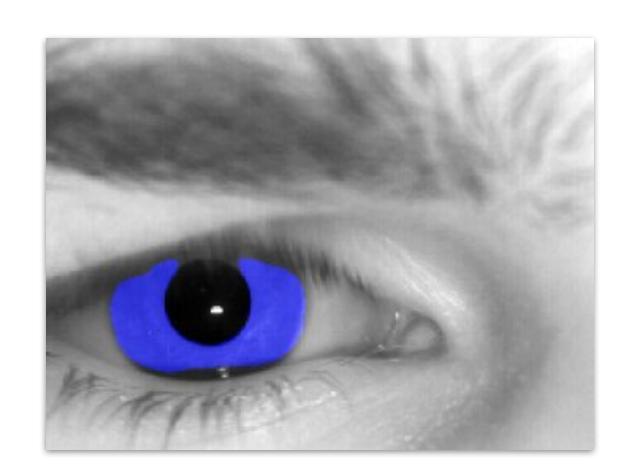
Active contours for iris segmentation.

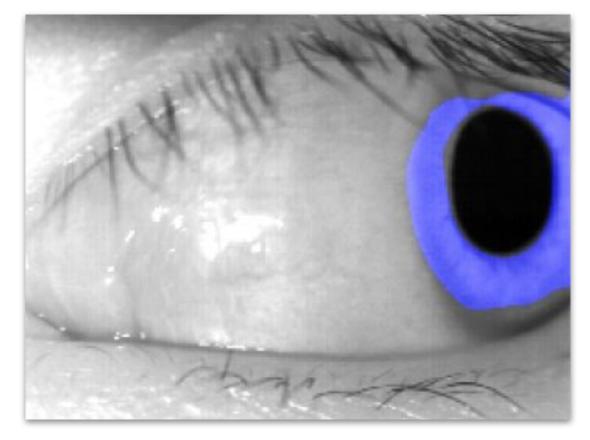
BSc Thesis, WUT, 2010



Segmentation (1/2)

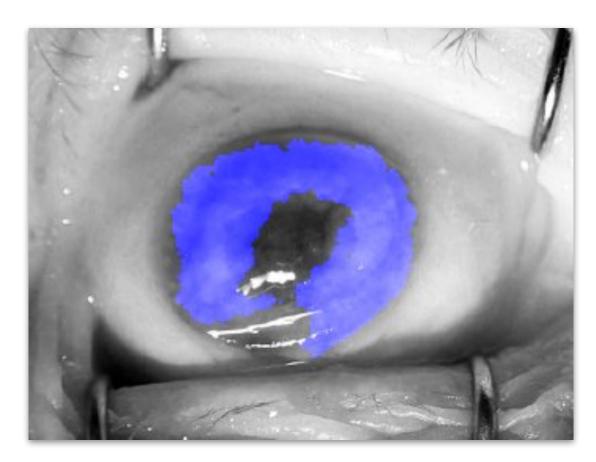
Iris Localization Convolutional Neural Networks (machine learning trained with annotation examples).





Kerrigan et al.

Iris Recognition with Image
Segmentation Employing
Retrained Off-the-Shelf Deep Neural
Networks
https://arxiv.org/abs/1901.01028, 2019





Segmentation (1/2)

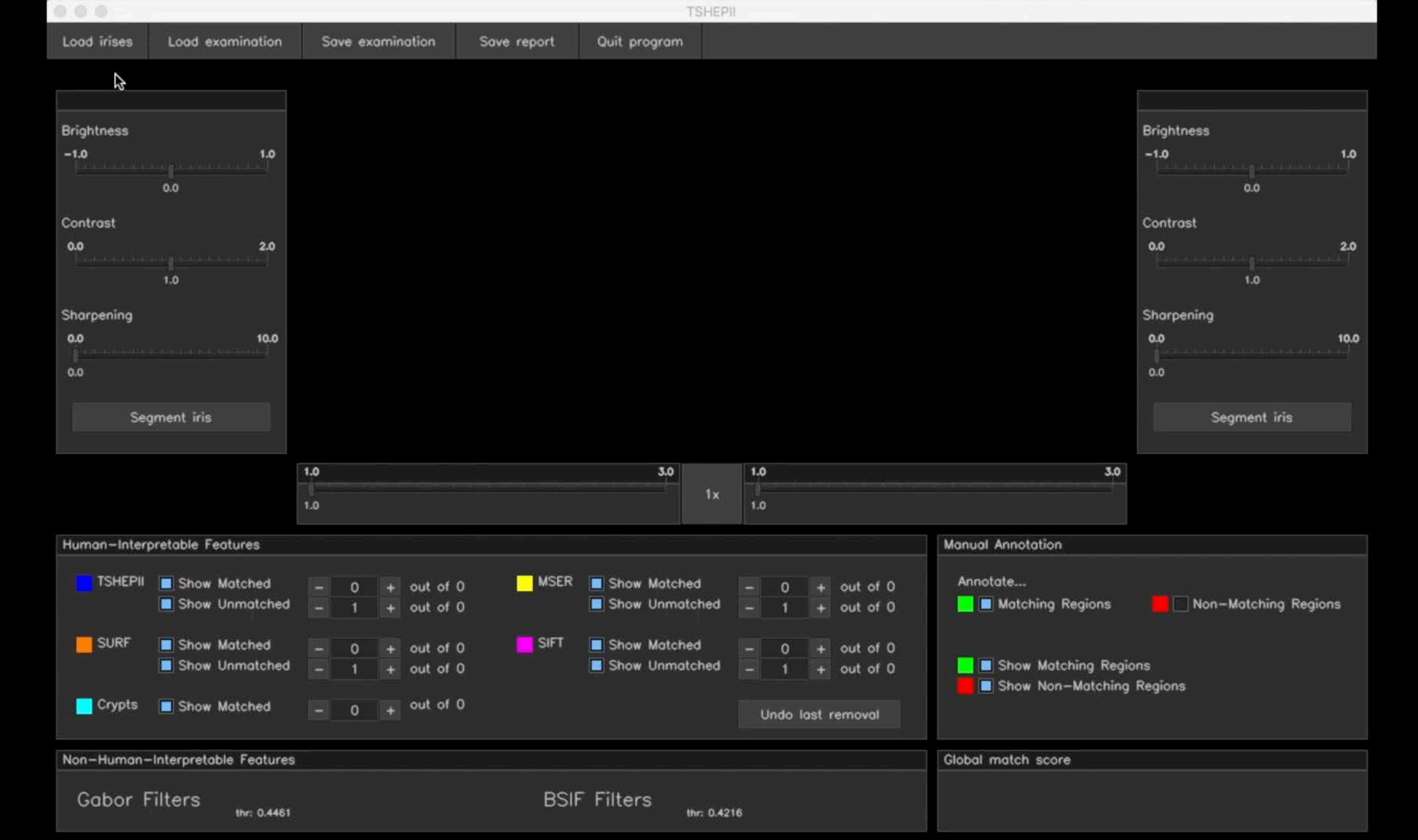
Manual Segmentation

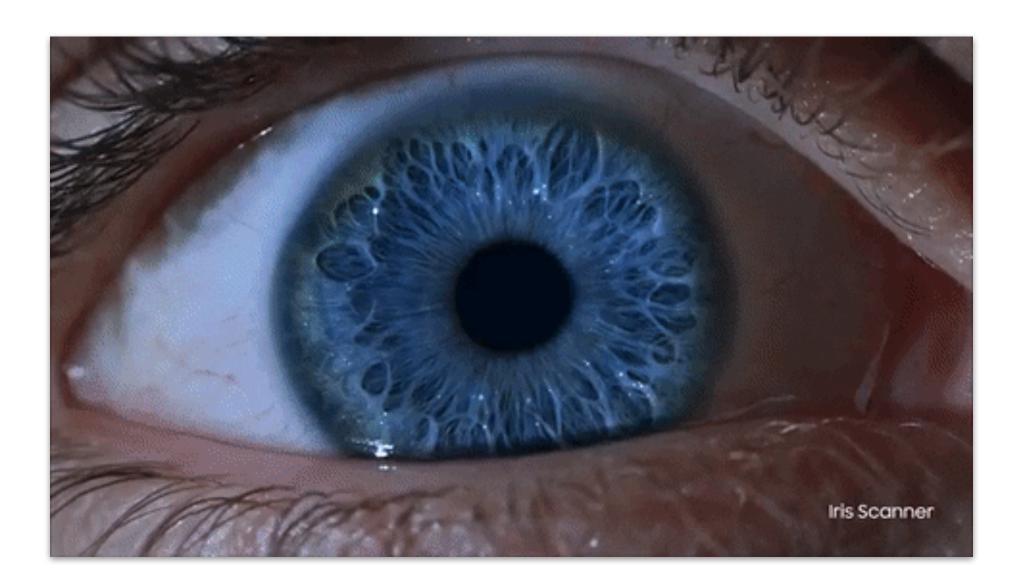
Next slide: iris recognition tool

developed at Notre Dame.







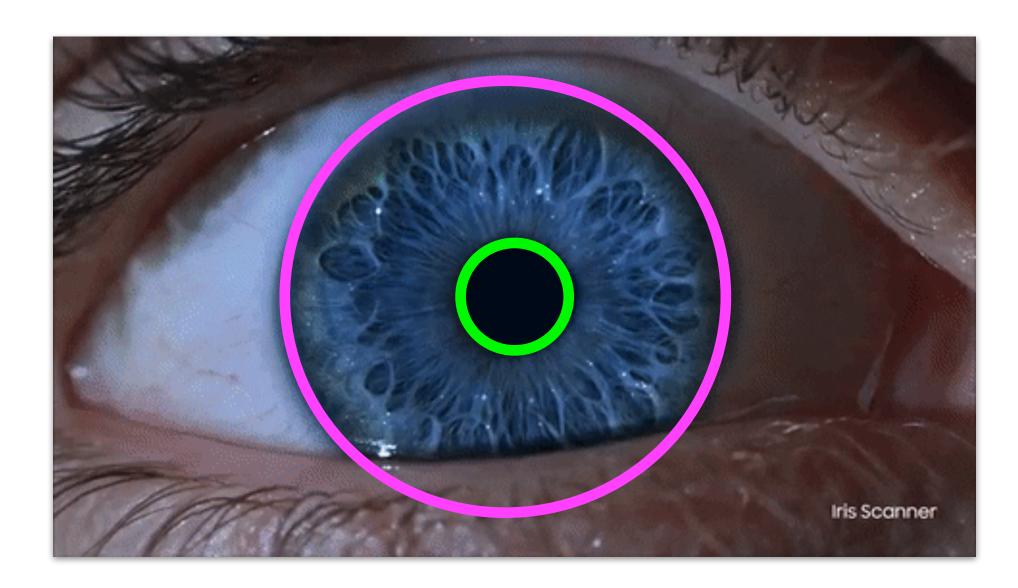


source

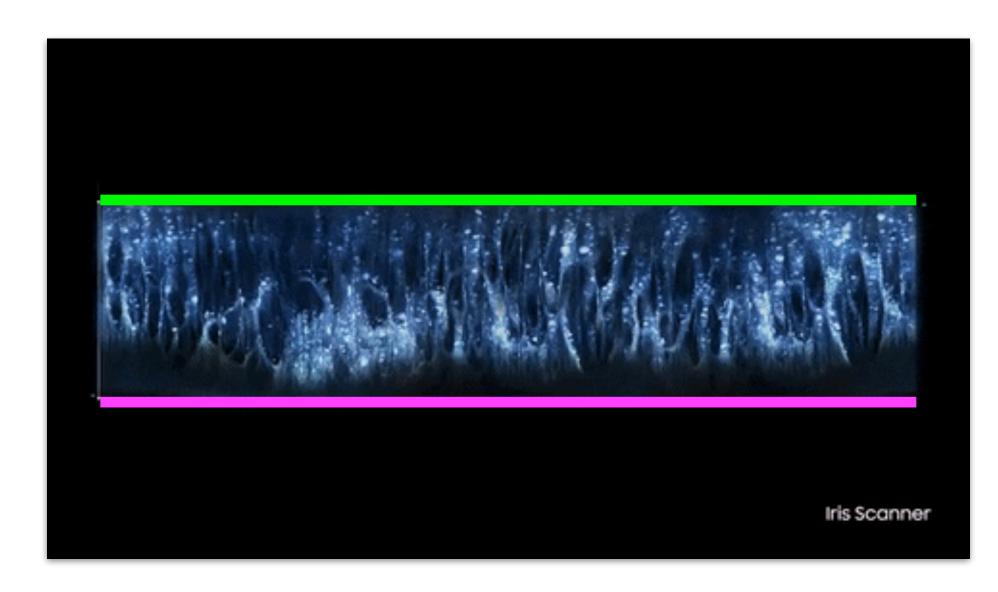


target



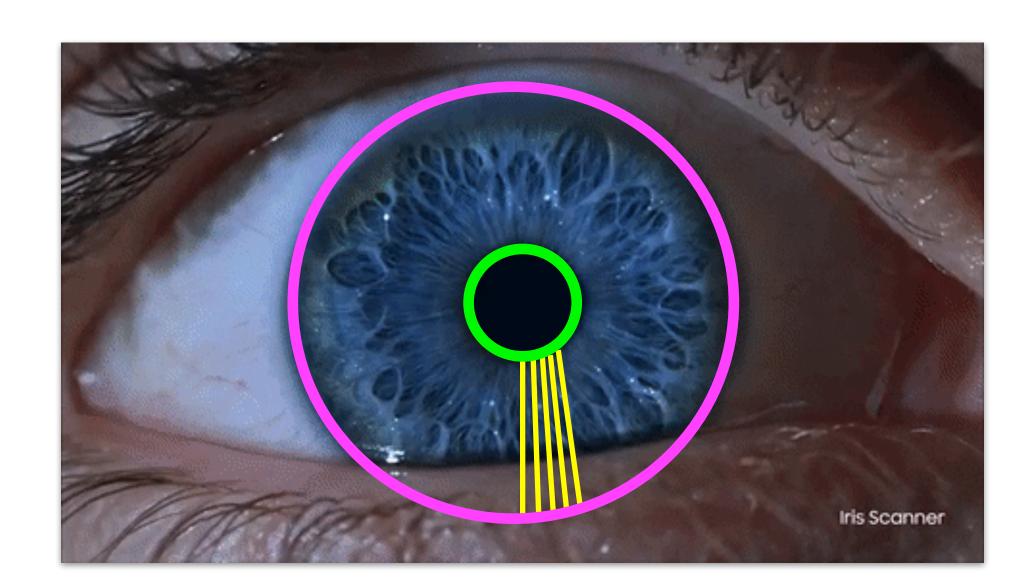


source

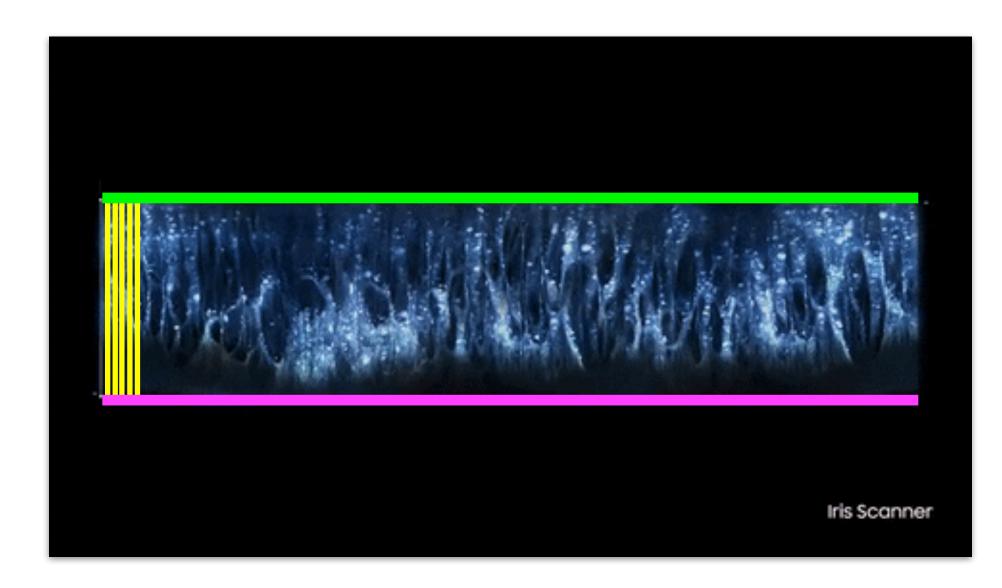


target



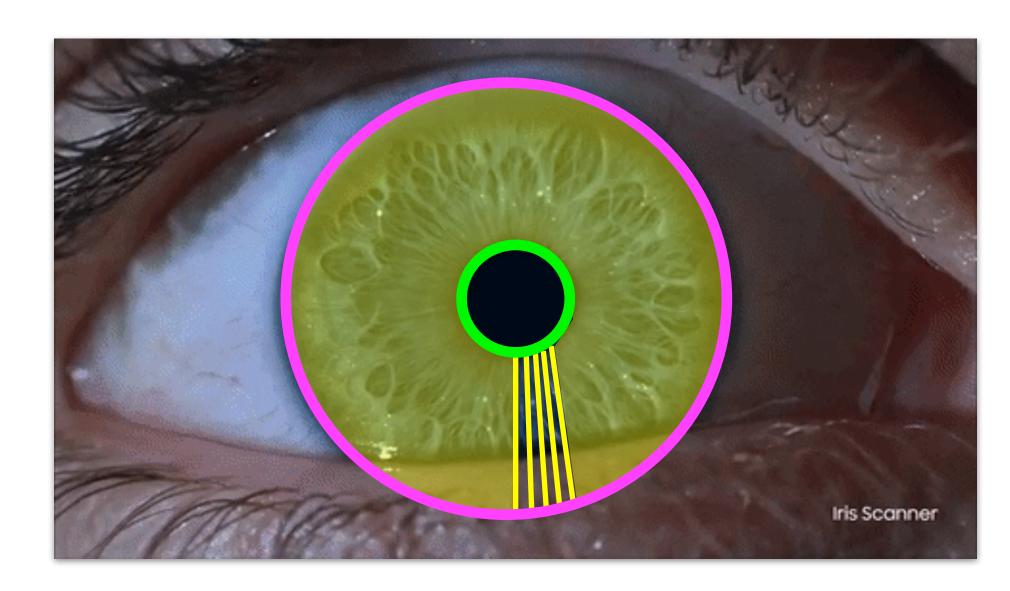


source

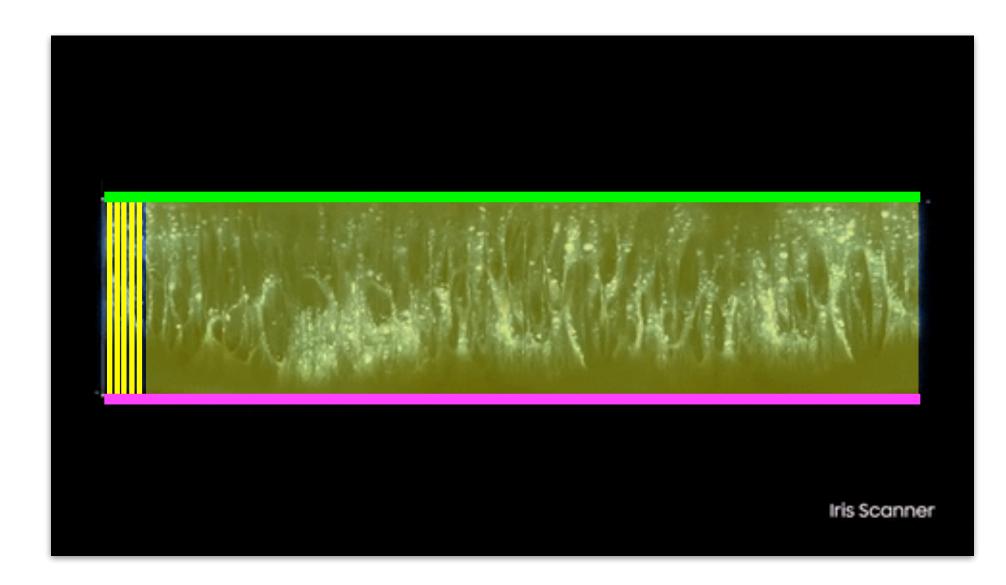


target



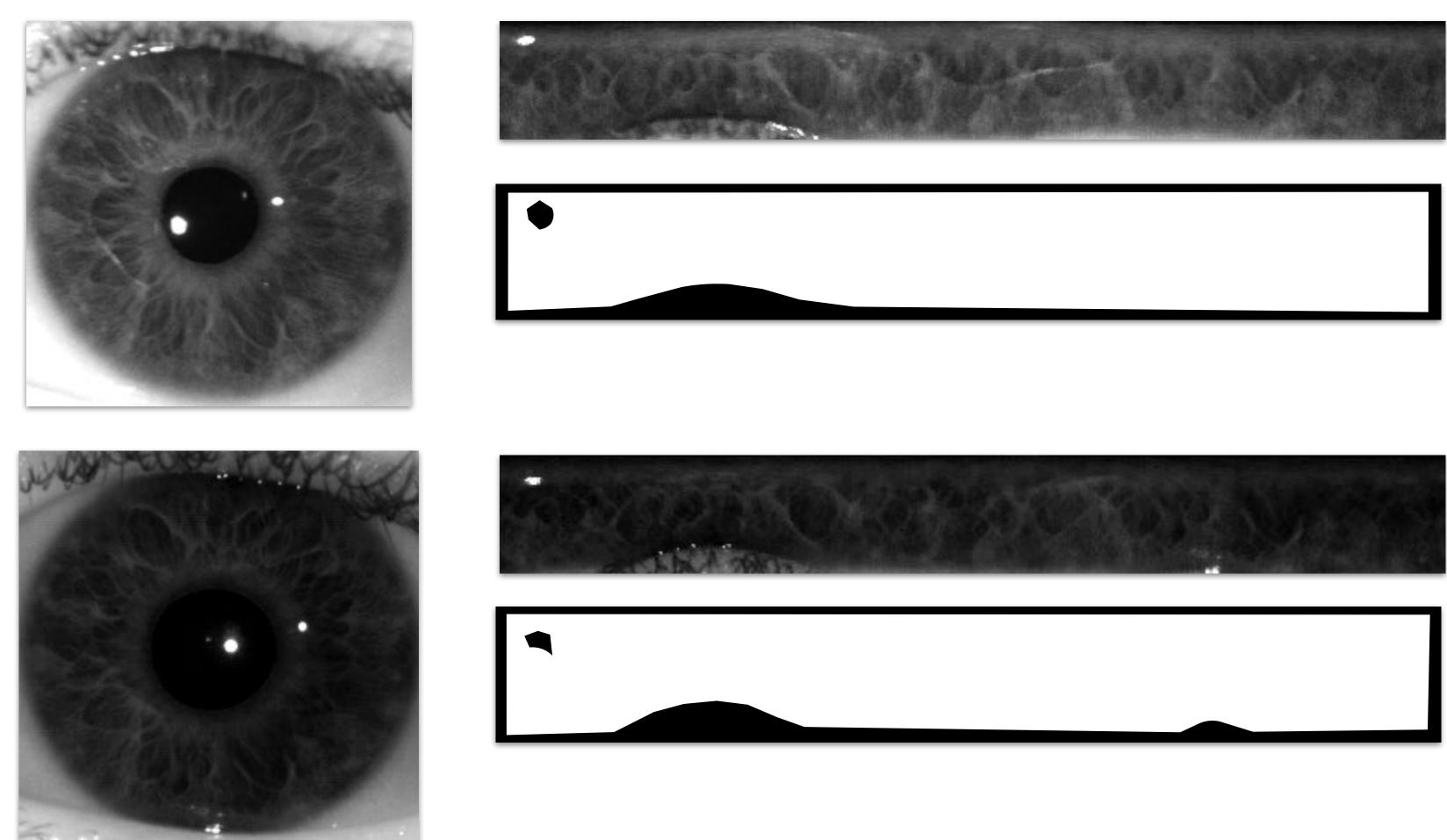


source



target







Limitations

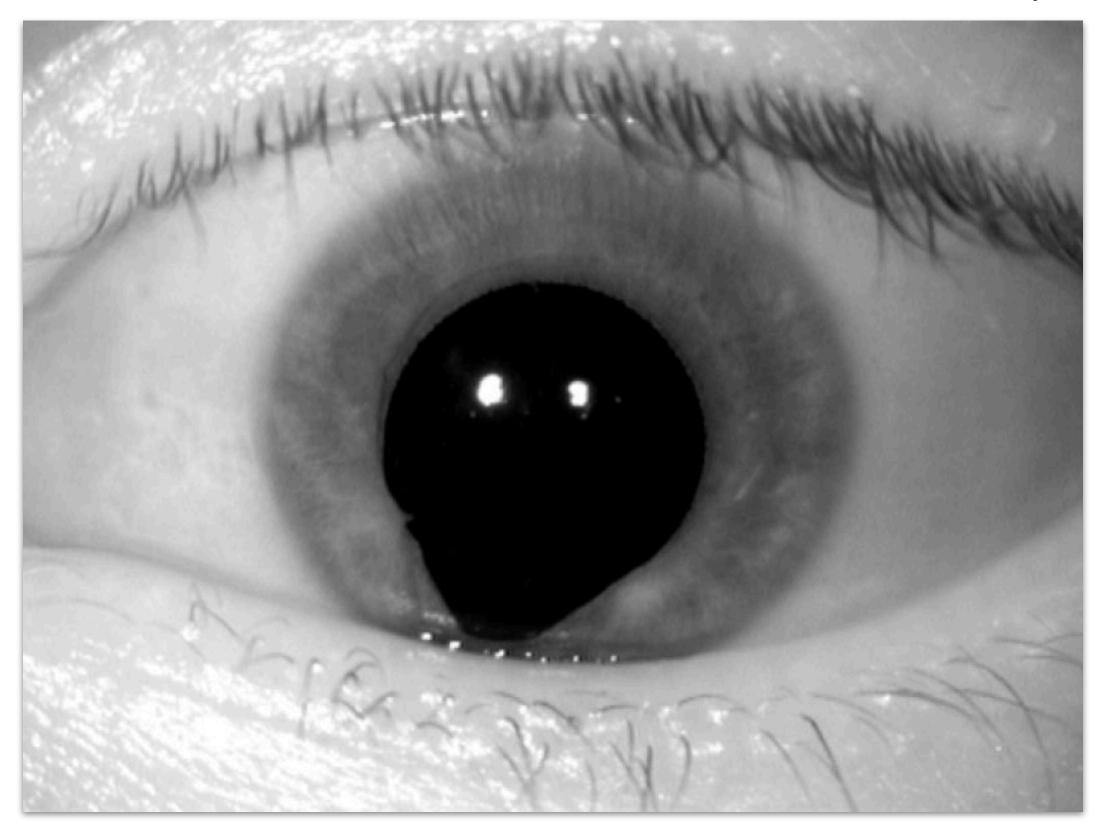
Segmentation

Pupil and iris are not concentric (pupils are slightly shifted to the nasal corner). They are not perfectly round.



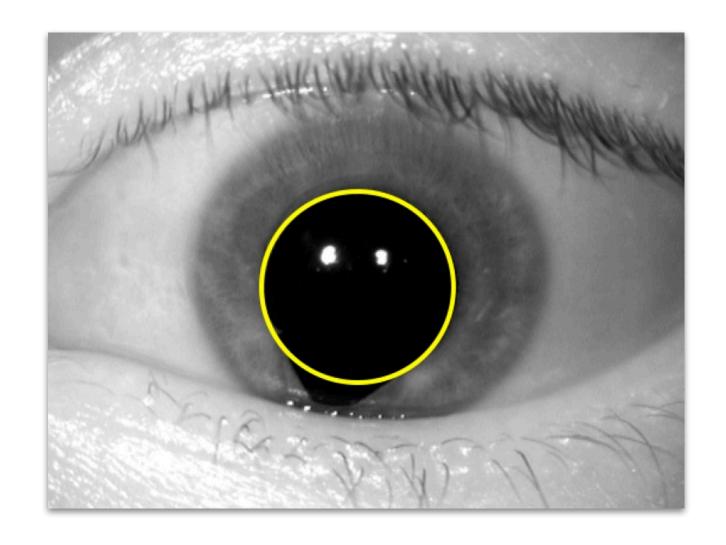


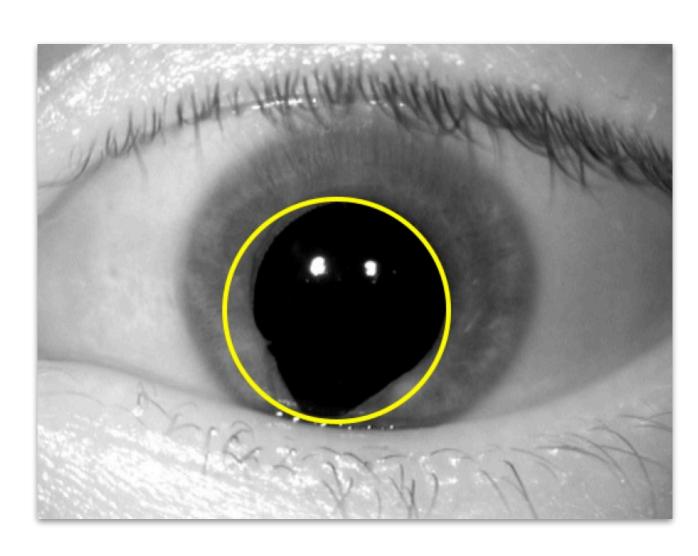
Dr. Adam Czajka



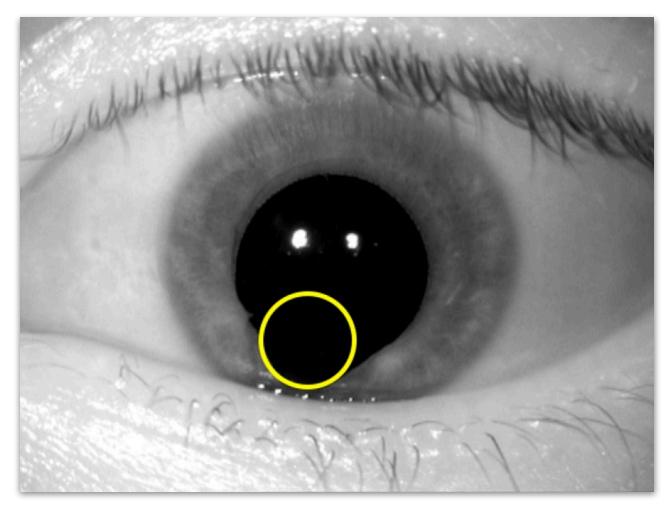
coloboma condition







Dr. Adam Czajka

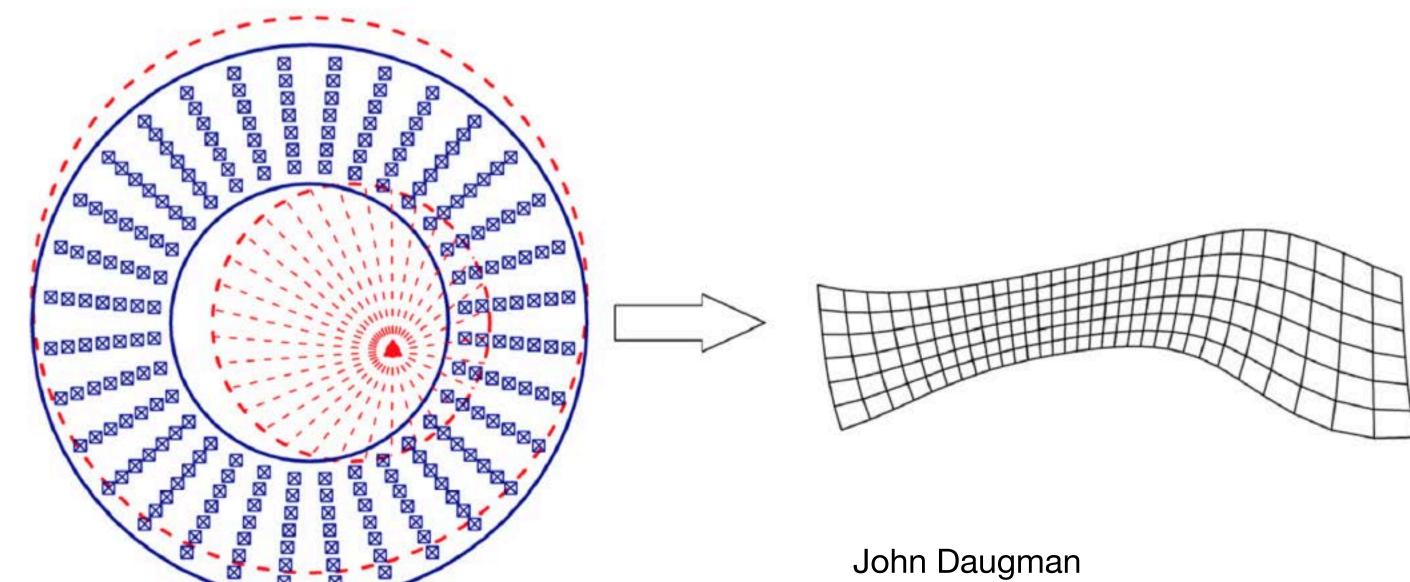




Limitations

Normalization

Forcing circular models may lead to poor mapping.



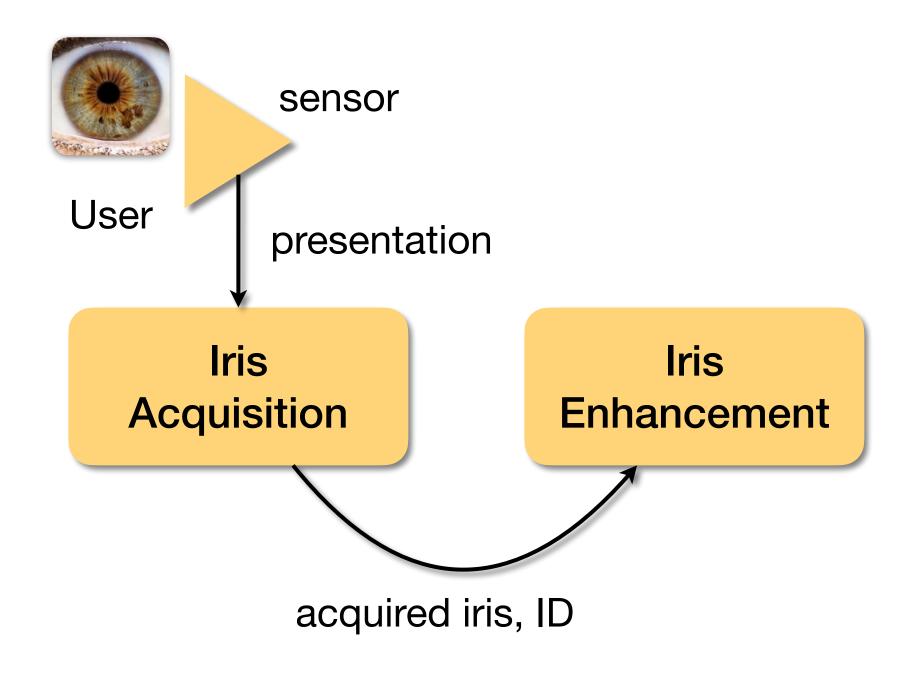
John Daugman

Evolving Method in Iris Recognition

BTAS, 2012

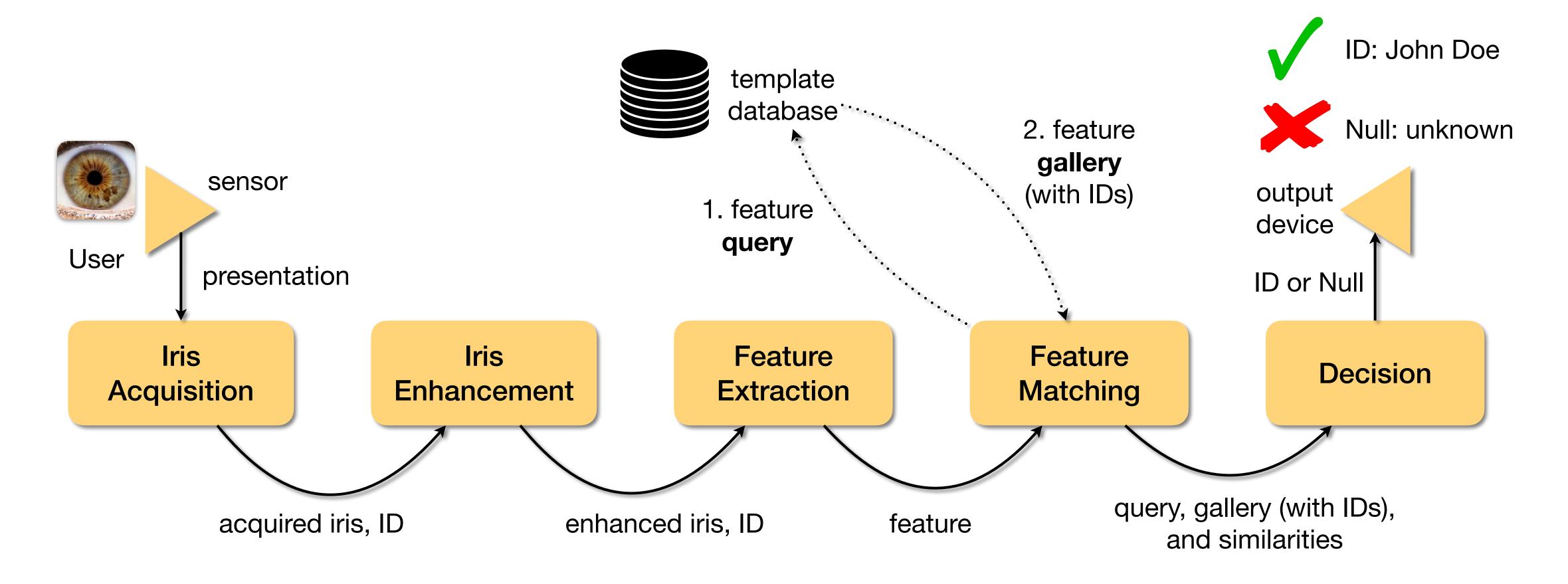


Iris Recognition





Iris Recognition





What's Next?

Iris Description and Matching

Fill out your

Today-I-missed Statement

Please visit

https://sakai.luc.edu/x/HAZC1P.



